

Dokumentation | EN

EL9562, EL9562-0015

Power supply terminals with galvanically isolated output voltages



EtherCAT®

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1 Foreword

1.1 Notes on the documentation

Intended audience

This description is only intended for the use of trained specialists in control and automation engineering who are familiar with the applicable national standards.

It is essential that the documentation and the following notes and explanations are followed when installing and commissioning these components.

The qualified personnel is obliged to always use the currently valid documentation.

The responsible staff must ensure that the application or use of the products described satisfy all the requirements for safety, including all the relevant laws, regulations, guidelines and standards.

Disclaimer

The documentation has been prepared with care. The products described are, however, constantly under development.

We reserve the right to revise and change the documentation at any time and without prior announcement.

No claims for the modification of products that have already been supplied may be made on the basis of the data, diagrams and descriptions in this documentation.

Trademarks

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1.2 Guide through documentation

NOTICE



Further components of documentation

This documentation describes device-specific content. It is part of the modular documentation concept for Beckhoff I/O components. For the use and safe operation of the device / devices described in this documentation, additional cross-product descriptions are required, which can be found in the following table.

Title	Description
EtherCAT System Documentation (PDF)	<ul style="list-style-type: none"> • System overview • EtherCAT basics • Cable redundancy • Hot Connect • EtherCAT devices configuration
Infrastructure for EtherCAT/Ethernet (PDF)	Technical recommendations and notes for design, implementation and testing
Software Declarations I/O (PDF)	Open source software declarations for Beckhoff I/O components

The documentations can be viewed at and downloaded from the Beckhoff website (www.beckhoff.com) via:

- the “Documentation and Download” area of the respective product page,
- the [Download finder](#),
- the [Beckhoff Information System](#).

If you have any suggestions or proposals for our documentation, please send us an e-mail stating the documentation title and version number to: documentation@beckhoff.com

1.3 Safety instructions

Safety regulations

Please note the following safety instructions and explanations!

Product-specific safety instructions can be found on following pages or in the areas mounting, wiring, commissioning etc.

Exclusion of liability

All the components are supplied in particular hardware and software configurations appropriate for the application. Modifications to hardware or software configurations other than those described in the documentation are not permitted, and nullify the liability of Beckhoff Automation GmbH & Co. KG.

Personnel qualification

This description is only intended for trained specialists in control, automation and drive engineering who are familiar with the applicable national standards.

Signal words

The signal words used in the documentation are classified below. In order to prevent injury and damage to persons and property, read and follow the safety and warning notices.

Personal injury warnings

DANGER

Hazard with high risk of death or serious injury.

WARNING

Hazard with medium risk of death or serious injury.

CAUTION

There is a low-risk hazard that could result in medium or minor injury.

Warning of damage to property or environment

NOTICE

The environment, equipment, or data may be damaged.

Information on handling the product



This information includes, for example:
recommendations for action, assistance or further information on the product.

1.4 Documentation issue status

Version	Comment
1.2.0	<ul style="list-style-type: none">• Connection corrected• Update chapter "Installation on mounting rails"
1.1.0	<ul style="list-style-type: none">• Image of EL9562-0015 corrected• Chapter <i>Process data</i> updated
1.0.0	<ul style="list-style-type: none">• First release

1.5 Version identification of EtherCAT devices

1.5.1 General notes on marking

Designation

A Beckhoff EtherCAT device has a 14-digit designation, made up of

- family key
- type
- version
- revision

Example	Family	Type	Version	Revision
EL3314-0000-0016	EL terminal 12 mm, non-pluggable connection level	3314 4-channel thermocouple terminal	0000 basic type	0016
ES3602-0010-0017	ES terminal 12 mm, pluggable connection level	3602 2-channel voltage measurement	0010 high-precision version	0017
CU2008-0000-0000	CU device	2008 8-port fast ethernet switch	0000 basic type	0000

Notes

- The elements mentioned above result in the **technical designation**. EL3314-0000-0016 is used in the example below.
- EL3314-0000 is the order identifier, in the case of "-0000" usually abbreviated to EL3314. "-0016" is the EtherCAT revision.
- The **order identifier** is made up of
 - family key (EL, EP, CU, ES, KL, CX, etc.)
 - type (3314)
 - version (-0000)
- The **revision** -0016 shows the technical progress, such as the extension of features with regard to the EtherCAT communication, and is managed by Beckhoff.
In principle, a device with a higher revision can replace a device with a lower revision, unless specified otherwise, e.g. in the documentation.
Associated and synonymous with each revision there is usually a description (ESI, EtherCAT Slave Information) in the form of an XML file, which is available for download from the Beckhoff web site.
From 2014/01 the revision is shown on the outside of the IP20 terminals, see Fig. "EL2872 with revision 0022 and serial number 01200815".
- The type, version and revision are read as decimal numbers, even if they are technically saved in hexadecimal.

1.5.2 Version identification of EL terminals

The serial number/ data code for Beckhoff IO devices is usually the 8-digit number printed on the device or on a sticker. The serial number indicates the configuration in delivery state and therefore refers to a whole production batch, without distinguishing the individual modules of a batch.

Structure of the serial number: **KK YY FF HH**

KK - week of production (CW, calendar week)

YY - year of production

FF - firmware version

HH - hardware version

Example with serial number 12 06 3A 02:

12 - production week 12

06 - production year 2006

3A - firmware version 3A

02 - hardware version 02



Fig. 1: EL2872 with revision 0022 and serial number 01200815

1.5.3 Beckhoff Identification Code (BIC)

The Beckhoff Identification Code (BIC) is increasingly being applied to Beckhoff products to uniquely identify the product. The BIC is represented as a Data Matrix Code (DMC, code scheme ECC200), the content is based on the ANSI standard MH10.8.2-2016.

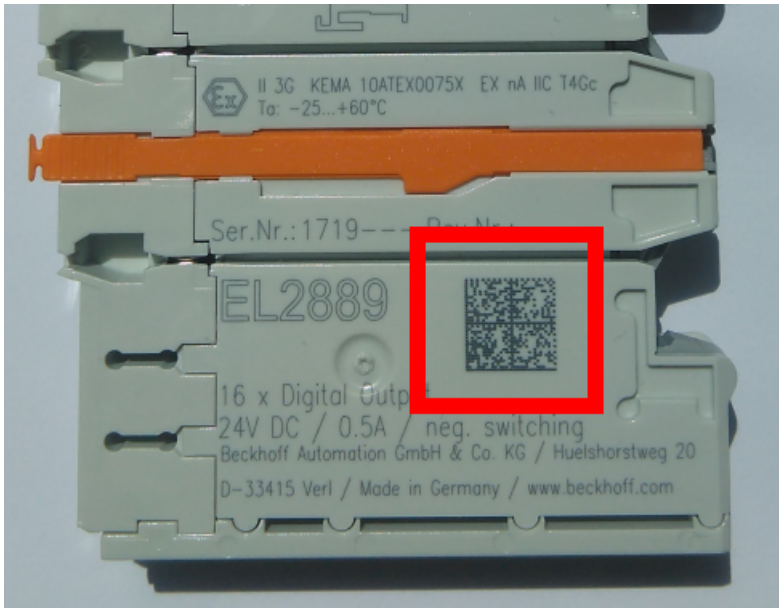


Fig. 2: BIC as data matrix code (DMC, code scheme ECC200)

The BIC will be introduced step by step across all product groups.

Depending on the product, it can be found in the following places:

- on the packaging unit
- directly on the product (if space suffices)
- on the packaging unit and the product

The BIC is machine-readable and contains information that can also be used by the customer for handling and product management.

Each piece of information can be uniquely identified using the so-called data identifier (ANSI MH10.8.2-2016). The data identifier is followed by a character string. Both together have a maximum length according to the table below. If the information is shorter, spaces are added to it.

Following information is possible, positions 1 to 4 are always present, the other according to need of production:

Position	Type of information	Explanation	Data identifier	Number of digits incl. data identifier	Example
1	Beckhoff order number	Beckhoff order number	1P	8	1P 072222
2	Beckhoff Traceability Number (BTN)	Unique serial number, see note below	SBTN	12	SBTN k4p562d7
3	Article description	Beckhoff article description, e.g. EL1008	1K	32	1KEL 1809
4	Quantity	Quantity in packaging unit, e.g. 1, 10, etc.	Q	6	Q1
5	Batch number	Optional: Year and week of production	2P	14	2P 401503180016
6	ID/serial number	Optional: Present-day serial number system, e.g. with safety products	51S	12	51S 678294
7	Variant number	Optional: Product variant number on the basis of standard products	30P	12	30P F971, 2*K183
...					

Further types of information and data identifiers are used by Beckhoff and serve internal processes.

Structure of the BIC

Example of composite information from positions 1 to 4 and with the above given example value on position 6. The data identifiers are highlighted in bold font:

1P072222**SBTN**k4p562d7**1KEL**1809 **Q1** **51S**678294

Accordingly as DMC:



Fig. 3: Example DMC **1P**072222**SBTN**k4p562d7**1KEL**1809 **Q1** **51S**678294

BTN

An important component of the BIC is the Beckhoff Traceability Number (BTN, position 2). The BTN is a unique serial number consisting of eight characters that will replace all other serial number systems at Beckhoff in the long term (e.g. batch designations on IO components, previous serial number range for safety products, etc.). The BTN will also be introduced step by step, so it may happen that the BTN is not yet coded in the BIC.

NOTICE

This information has been carefully prepared. However, the procedure described is constantly being further developed. We reserve the right to revise and change procedures and documentation at any time and without prior notice. No claims for changes can be made from the information, illustrations and descriptions in this documentation.

1.5.4 Electronic access to the BIC (eBIC)

Electronic BIC (eBIC)

The Beckhoff Identification Code (BIC) is applied to the outside of Beckhoff products in a visible place. If possible, it should also be electronically readable.

The interface that the product can be electronically addressed by is crucial for the electronic readout.

K-bus devices (IP20, IP67)

Currently, no electronic storage or readout is planned for these devices.

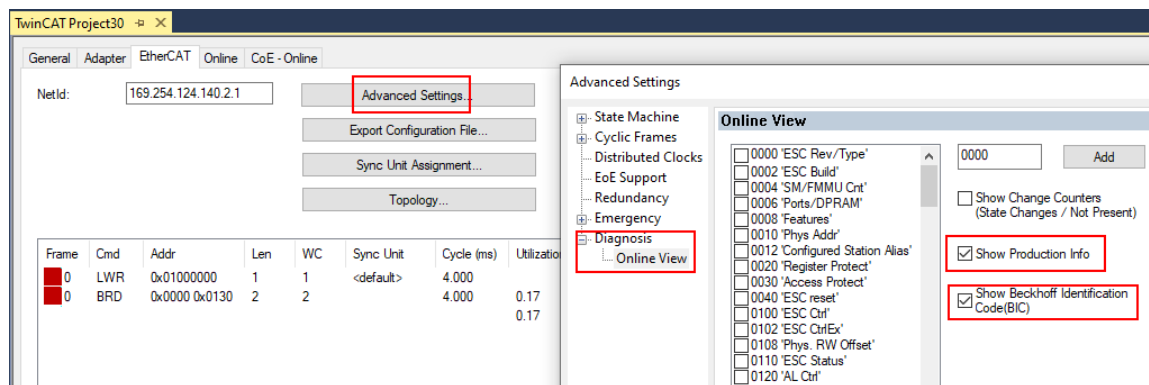
EtherCAT devices (IP20, IP67)

All Beckhoff EtherCAT devices have an ESI-EEPROM which contains the EtherCAT identity with the revision number. The EtherCAT slave information, also colloquially known as the ESI/XML configuration file for the EtherCAT master, is stored in it. See the corresponding chapter in the EtherCAT system manual ([Link](#)) for the relationships.

Beckhoff also stores the eBIC in the ESI-EEPROM. The eBIC was introduced into Beckhoff IO production (terminals, box modules) in 2020; as of 2023, implementation is largely complete.

The user can electronically access the eBIC (if present) as follows:

- With all EtherCAT devices, the EtherCAT master (TwinCAT) can read the eBIC from the ESI-EEPROM
 - From TwinCAT 3.1 build 4024.11, the eBIC can be displayed in the online view.
 - To do this, check the "Show Beckhoff Identification Code (BIC)" checkbox under EtherCAT → Advanced Settings → Diagnostics:



- The BTN and its contents are then displayed:

No	Addr	Name	State	CRC	Fw	Hw	Production Data	ItemNo	BTN	Description	Quantity	BatchNo	SerialNo
1	1001	Term 1 (EK1100)	OP	0.0	0	0	---						
2	1002	Term 2 (EL1018)	OP	0.0	0	0	2020 KW36 Fr	072222	k4p562d7	EL1809	1		678294
3	1003	Term 3 (EL3204)	OP	0.0	7	6	2012 KW24 Sa						
4	1004	Term 4 (EL2004)	OP	0.0	0	0	---	072223	k4p562d7	EL2004	1		678295
5	1005	Term 5 (EL1008)	OP	0.0	0	0	---						
6	1006	Term 6 (EL2008)	OP	0.0	0	12	2014 KW14 Mo						
7	1007	Term 7 (EK1110)	OP	0	1	8	2012 KW25 Mo						

- Note: As shown in the figure, the production data HW version, FW version, and production date, which have been programmed since 2012, can also be displayed with "Show production info".
- Access from the PLC: From TwinCAT 3.1. build 4024.24, the functions *FB_EcReadBIC* and *FB_EcReadBTN* for reading into the PLC are available in the Tc2_EtherCAT library from v3.3.19.0.
- EtherCAT devices with a CoE directory may also have the object 0x10E2:01 to display their own eBIC, which can also be easily accessed by the PLC:

- The device must be in PREOP/SAFEOP/OP for access:

Index	Name	Flags	Value
1000	Device type	RO	0x015E1389 (22942601)
1008	Device name	RO	ELM3704-0000
1009	Hardware version	RO	00
100A	Software version	RO	01
100B	Bootloader version	RO	J0.1.27.0
+ 1011:0	Restore default parameters	RO	> 1 <
+ 1018:0	Identity	RO	> 4 <
- 10E2:0	Manufacturer-specific Identification C...	RO	> 1 <
- 10E2:01	SubIndex 001	RO	1P158442SBTN0008jekp1KELM3704 Q1 2P482001000016
+ 10F0:0	Backup parameter handling	RO	> 1 <
+ 10F3:0	Diagnosis History	RO	> 21 <
- 10F8	Actual Time Stamp	RO	0x170bf6277e

- The object 0x10E2 will be preferentially introduced into stock products in the course of necessary firmware revision.
- From TwinCAT 3.1. build 4024.24, the functions *FB_EcCoEReadBIC* and *FB_EcCoEReadBTN* for reading into the PLC are available in the Tc2_EtherCAT library from v3.3.19.0
- The following auxiliary functions are available for processing the BIC/BTN data in the PLC in *Tc2_Uilities* as of TwinCAT 3.1 build 4024.24
 - *F_SplitBIC*: The function splits the Beckhoff Identification Code (BIC) sBICValue into its components using known identifiers and returns the recognized substrings in the ST_SplittedBIC structure as a return value
 - *BIC_TO_BTN*: The function extracts the BTN from the BIC and returns it as a return value
- Note: If there is further electronic processing, the BTN is to be handled as a string(8); the identifier "SBTN" is not part of the BTN.
- Technical background
The new BIC information is written as an additional category in the ESI-EEPROM during device production. The structure of the ESI content is largely dictated by the ETG specifications, therefore the additional vendor-specific content is stored using a category in accordance with the ETG.2010. ID 03 tells all EtherCAT masters that they may not overwrite these data in the event of an update or restore the data after an ESI update.
The structure follows the content of the BIC, see here. The EEPROM therefore requires approx. 50..200 bytes of memory.
- Special cases
 - If multiple hierarchically arranged ESCs are installed in a device, only the top-level ESC carries the eBIC information.
 - If multiple non-hierarchically arranged ESCs are installed in a device, all ESCs carry the eBIC information.
 - If the device consists of several sub-devices which each have their own identity, but only the top-level device is accessible via EtherCAT, the eBIC of the top-level device is located in the CoE object directory 0x10E2:01 and the eBICs of the sub-devices follow in 0x10E2:nn.

PROFIBUS, PROFINET, and DeviceNet devices

Currently, no electronic storage or readout is planned for these devices.

2 Product overview

Power supply terminals with electrically isolated output voltages

Power supply terminal	Output voltage	Output current	Comment
EL9562 [► 15]	24 V _{DC}	2 x 0.2 A	electrically isolated
EL9562-0015 [► 16]	15 V _{DC}	2 x 0.3 A	electrically isolated

2.1 EL9562 - Introduction

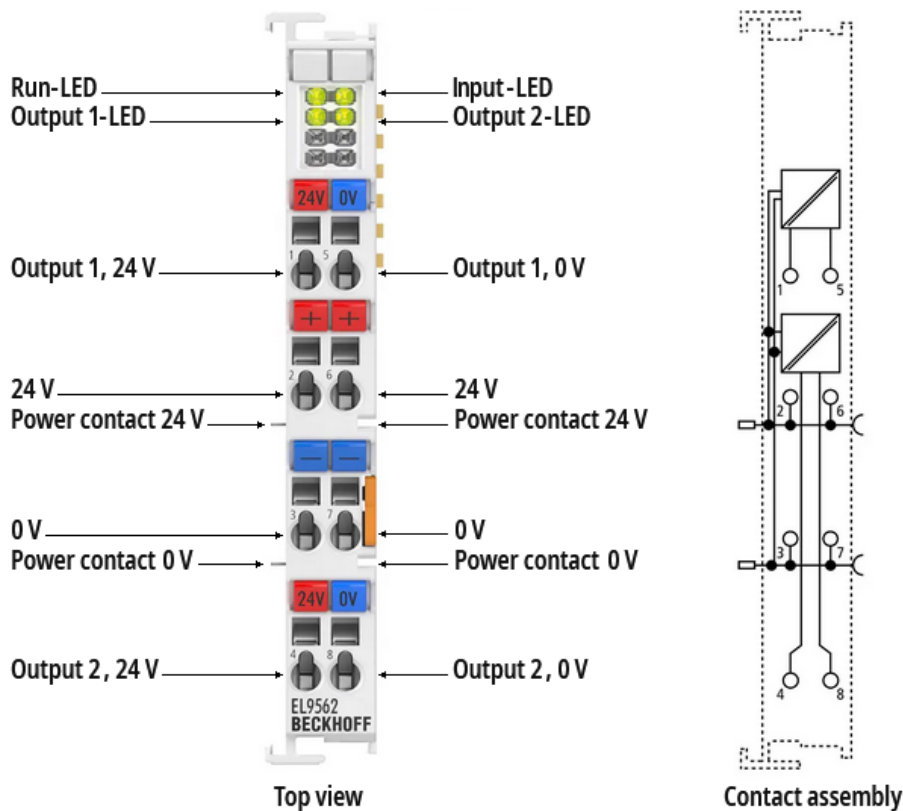


Fig. 4: EL9562

The EL9562 power supply terminal generates two electrically isolated output voltages of 24 V_{DC} each from the input voltage (24 V_{DC}). The output voltages can be tapped at the terminal and are electrically isolated from each other and from the input voltage. A symmetrical DC voltage can be generated by connecting both output voltages.

The power contacts are connected through and forward the supplied 24 V_{DC} to the downstream EtherCAT Terminals.

The status LEDs indicate the terminals' operating state.

2.2 EL9562-0015 - Introduction

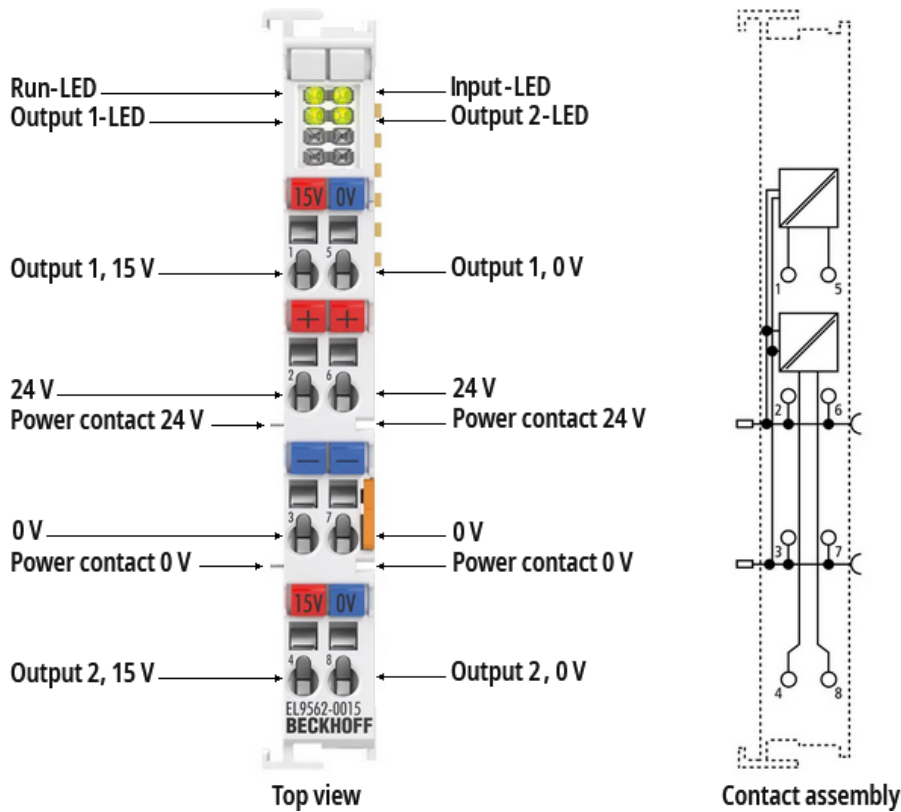


Fig. 5: EL9562-0015

The EL9562-0015 power supply terminal generates two electrically isolated output voltages of 15 V_{DC} each from the input voltage (24 V_{DC}). The output voltages can be tapped at the terminal and are electrically isolated from each other and from the input voltage. A symmetrical DC voltage can be generated by connecting both output voltages.

The power contacts are connected through and forward the supplied 24 V_{DC} to the downstream EtherCAT Terminals.

The status LEDs indicate the terminals' operating state.

2.3 Technical data

Technical data	EL9562	EL9562-0015
Technology	Power supply terminal with electrical isolation	
Input voltage	24 V _{DC} (-15 % / +20 %)	
Output voltage	24 V _{DC} (-5 % / +15 %)	15 V _{DC} (-5 % / +5 %)
Output current	max. 2 x 0.2 A	max. 2 x 0.3 A
Resistant to short circuit	yes	
Special features	automatic restart after short circuit, diagnosis U _{IN} /U _{OUT}	
Short circuit diagnosis, overload:	Overcurrent LED	
Message to E-bus	yes	
Power contacts (right)	U ₀ , 0 V	
E-bus current consumption	typ. 60 mA	
Bit width in process image	2	
Electrical connection to the mounting rail	-	
Insulation voltage field side/E-bus	Constant load 500 V _{AC}	
Insulation voltage input/output	Constant load 500 V _{AC}	
Size (W x H x D)	approx. 15 mm x 100 mm x 68 mm (width aligned: 12 mm)	
Configuration	no address or configuration settings required	
Weight	approx. 55 g	
Permissible ambient temperature range during operation	0 °C ... + 55 °C	
Permissible ambient temperature range during storage	-25 °C ... + 85 °C	
Permissible relative air humidity	95 %, no condensation	
Installation [► 19]	on 35 mm mounting rail, conforms to EN 60715	
Vibration / shock resistance	conforms to EN 60068-2-6 / EN 60068-2-27	
EMC immunity / emission	conforms to EN 61000-6-2 / EN 61000-6-4	
Protection rating	IP20	
Installation position	variable	
Approvals / markings*	CE, UKCA, EAC	

*) Real applicable approvals/markings see type plate on the side (product marking).

3 Mounting and wiring

3.1 Instructions for ESD protection

NOTICE

Destruction of the devices by electrostatic discharge possible!

The devices contain components at risk from electrostatic discharge caused by improper handling.

- When handling the components, ensure that there is no electrostatic discharge; also avoid touching the spring contacts directly (see illustration).
- Contact with highly insulating materials (synthetic fibers, plastic films, etc.) should be avoided when handling components at the same time.
- When handling the components, ensure that the environment (workplace, packaging and persons) is properly earthed.
- Each bus station must be terminated on the right-hand side with the [EL9011](#) or [EL9012](#) end cap to ensure the degree of protection and ESD protection.

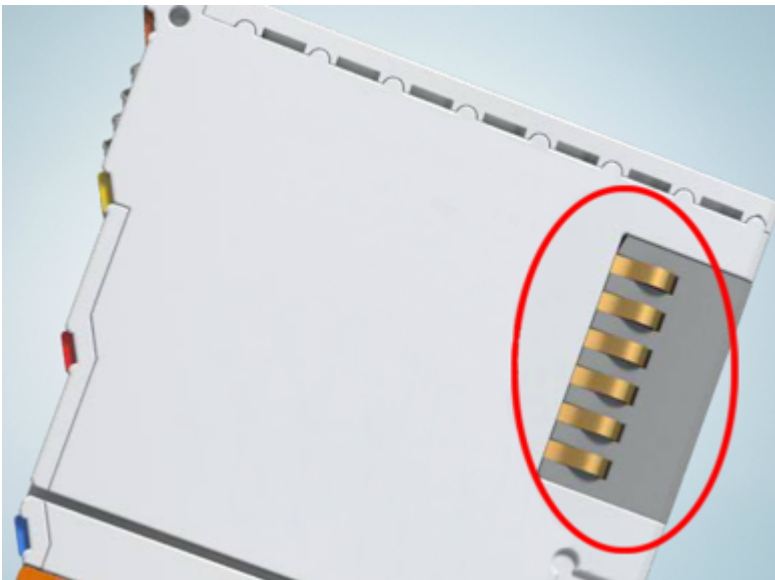


Fig. 6: Spring contacts of the Beckhoff I/O components

3.2 Installation on mounting rails

⚠ WARNING

Risk of electric shock and damage of device!

Bring the bus terminal system into a safe, powered down state before starting installation, disassembly or wiring of the bus terminals!

The Bus Terminal system and is designed for mounting in a control cabinet or terminal box.

Assembly

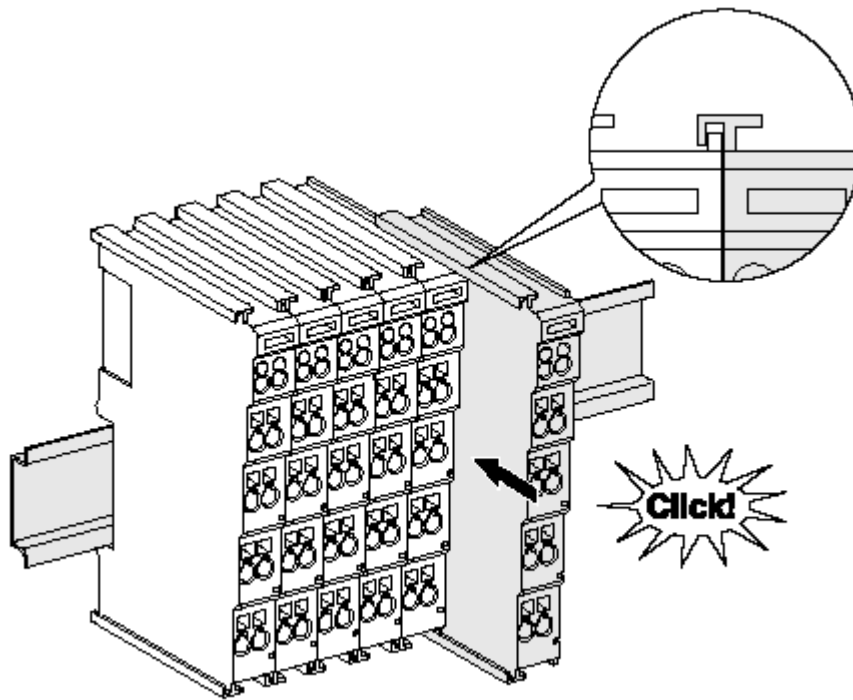


Fig. 7: Attaching on mounting rail

The bus coupler and bus terminals are attached to commercially available 35 mm mounting rails (DIN rails according to EN 60715) by applying slight pressure:

1. First attach the fieldbus coupler to the mounting rail.
2. The bus terminals are now attached on the right-hand side of the fieldbus coupler. Join the components with tongue and groove and push the terminals against the mounting rail, until the lock clicks onto the mounting rail.

If the terminals are clipped onto the mounting rail first and then pushed together without tongue and groove, the connection will not be operational! When correctly assembled, no significant gap should be visible between the housings.

● Fixing of mounting rails

i The locking mechanism of the terminals and couplers extends to the profile of the mounting rail. At the installation, the locking mechanism of the components must not come into conflict with the fixing bolts of the mounting rail. To mount the mounting rails with a height of 7.5 mm under the terminals and couplers, you should use flat mounting connections (e.g. countersunk screws or blind rivets).

NOTICE

Ground the mounting rail!

Ensure that the mounting rail is sufficiently earthed.

Connections within a bus terminal block

The electric connections between the Bus Coupler and the Bus Terminals are automatically realized by joining the components:

- The six spring contacts of the E-Bus/K-Bus deal with the transfer of the data and the supply of the Bus Terminal electronics.
- The power contacts deal with the supply for the field electronics and thus represent a supply rail within the bus terminal block. The power contacts are supplied via terminals points on the Bus Coupler (up to 24 V) or for higher voltages via power feed terminals.



Power Contacts

During the design of a bus terminal block, the pin assignment of the individual Bus Terminals must be taken account of, since some types (e.g. analog Bus Terminals or digital 4-channel Bus Terminals) do not or not fully loop through the power contacts. Power Feed Terminals (EL91xx, EL92xx or KL91xx, KL92xx) interrupt the power contacts and thus represent the start of a new supply rail.

Power contact $\perp$

The power contact labeled $\perp$ (earthing connection according to IEC 60417-5017) can be used as a functional earth. For safety reasons this contact mates first when plugging together, and can ground short-circuit currents of up to 125 A.

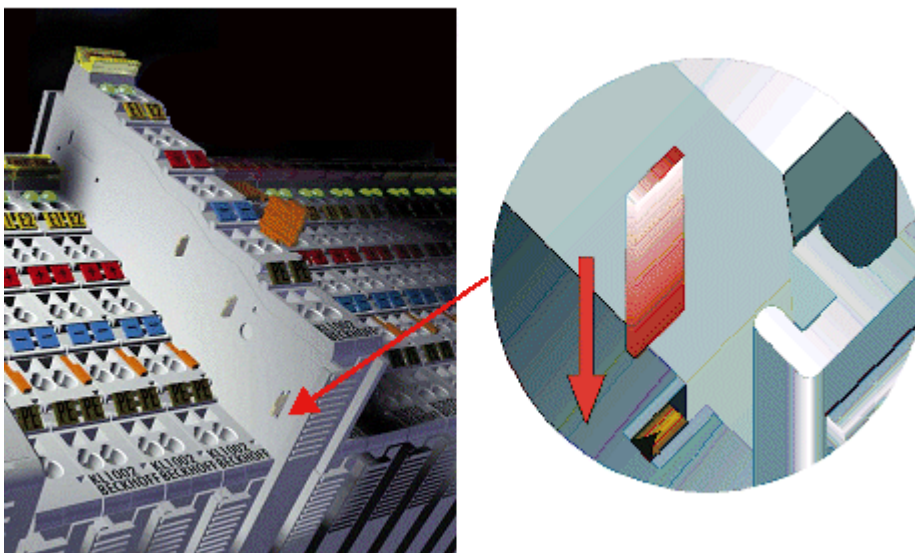


Fig. 8: Power contact on left side

WARNING

Risk of electric shock!

The power contact labeled $\perp$ must not be used for other potentials!

NOTICE

Possible damage of the device

Note that, for reasons of electromagnetic compatibility, the earthing contacts are capacitatively coupled to the mounting rail. This may lead to incorrect results during insulation testing or to damage on the terminal (e.g. disruptive discharge to the earthing line during insulation testing of a consumer with a nominal voltage of 230 V). For insulation testing, disconnect the earthing supply line at the Bus Coupler or the Power Feed Terminal! In order to decouple further feed points for testing, these Power Feed Terminals can be released and pulled at least 10 mm from the group of terminals.

Disassembly

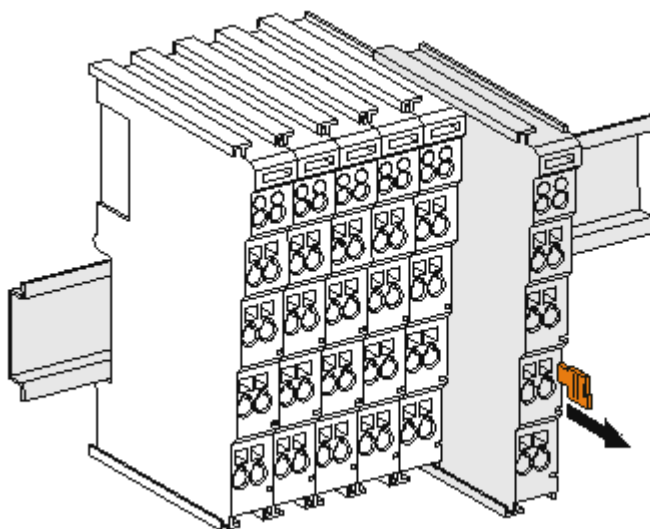


Fig. 9: Disassembling of terminal

Each terminal is secured by a lock on the mounting rail, which must be released for disassembly:

1. Pull the terminal by its orange-colored lugs approximately 1 cm away from the mounting rail. In doing so for this terminal the mounting rail lock is released automatically and you can pull the terminal out of the bus terminal block easily without excessive force.
2. Grasp the released terminal with thumb and index finger simultaneous at the upper and lower grooved housing surfaces and pull the terminal out of the bus terminal block.

3.3 Installation positions

NOTICE

Constraints regarding installation position and operating temperature range

Please refer to the technical data for a terminal to ascertain whether any restrictions regarding the installation position and/or the operating temperature range have been specified. When installing high power dissipation terminals ensure that an adequate spacing is maintained between other components above and below the terminal in order to guarantee adequate ventilation!

Optimum installation position (standard)

The optimum installation position requires the mounting rail to be installed horizontally and the connection surfaces of the EL- / KL terminals to face forward (see Fig. "Recommended distances for standard installation position"). The terminals are ventilated from below, which enables optimum cooling of the electronics through convection. "From below" is relative to the acceleration of gravity.

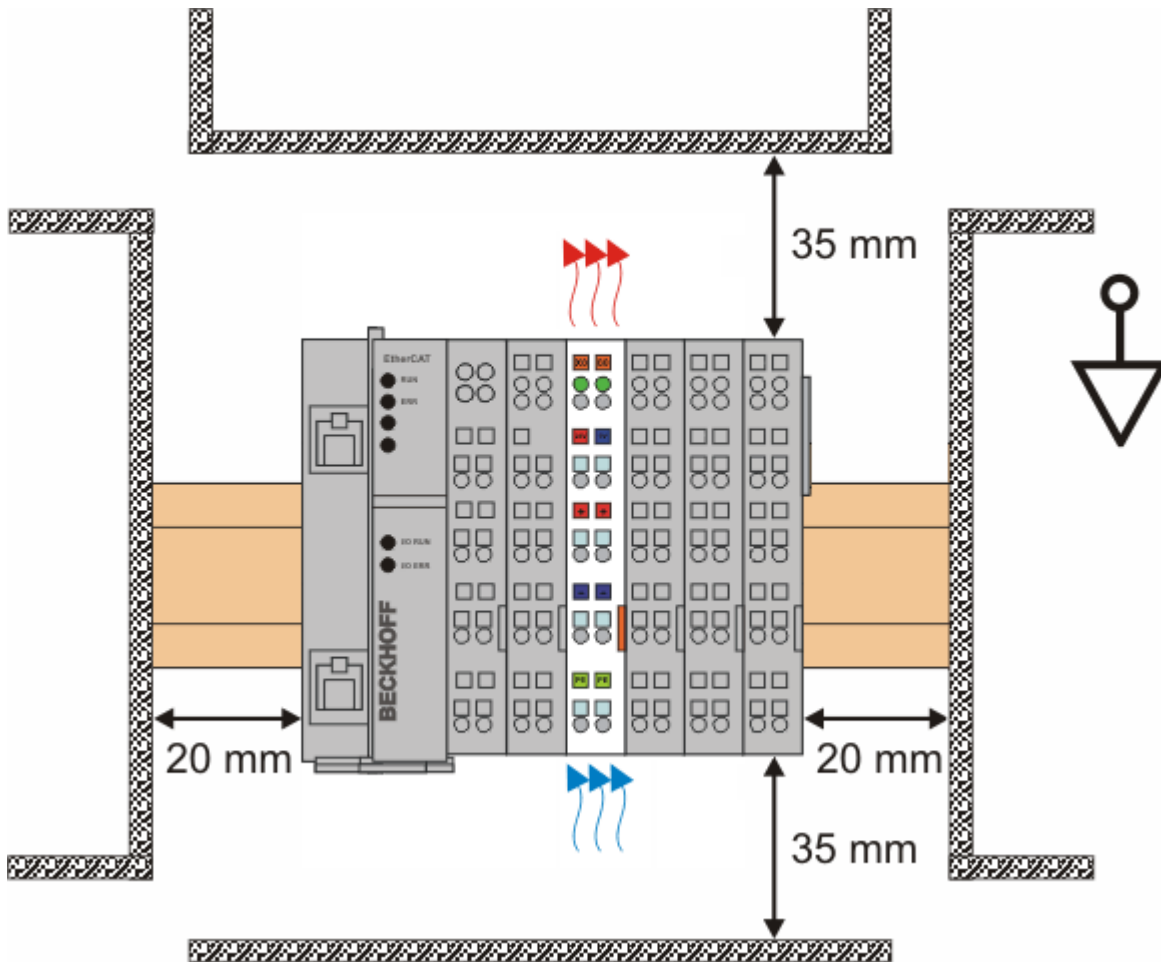


Fig. 10: Recommended distances for standard installation position

Compliance with the distances shown in Fig. "Recommended distances for standard installation position" is recommended.

Other installation positions

All other installation positions are characterized by different spatial arrangement of the mounting rail - see Fig "Other installation positions".

The minimum distances to ambient specified above also apply to these installation positions.

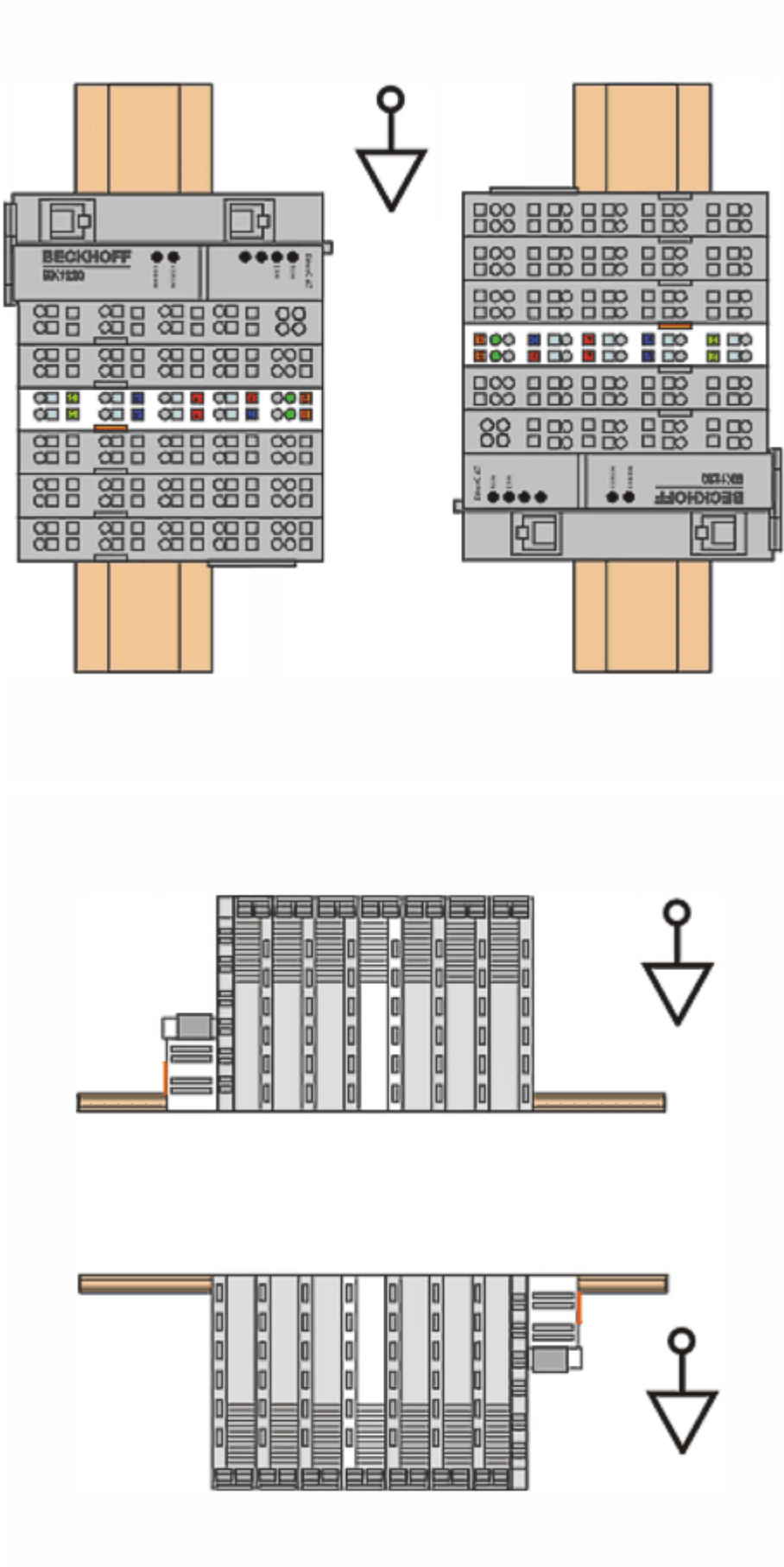


Fig. 11: Other installation positions

3.4 Positioning of passive Terminals



Hint for positioning of passive terminals in the bus terminal block

EtherCAT Terminals (ELxxxx / ESxxxx), which do not take an active part in data transfer within the bus terminal block are so called passive terminals. The passive terminals have no current consumption out of the E-Bus.

To ensure an optimal data transfer, you must not directly string together more than two passive terminals!

Examples for positioning of passive terminals (highlighted)

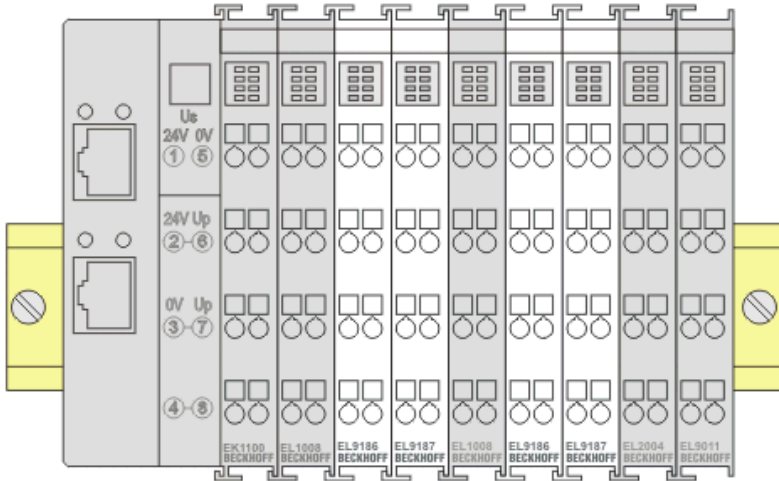


Fig. 12: Correct positioning

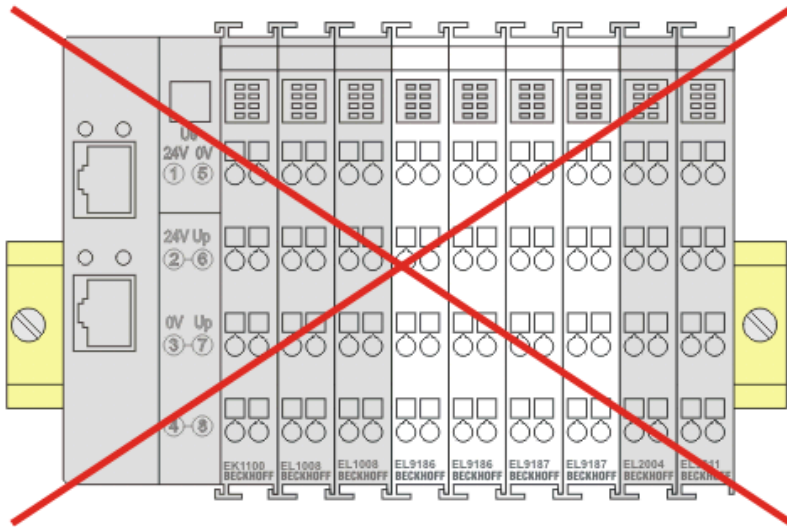


Fig. 13: Incorrect positioning

3.5 Note - power supply

WARNING

Power supply from SELV / PELV power supply unit!

SELV / PELV circuits (safety extra-low voltage / protective extra-low voltage) according to IEC 61010-2-201 must be used to supply this device.

Notes:

- SELV / PELV circuits may give rise to further requirements from standards such as IEC 60204-1 et al, for example with regard to cable spacing and insulation.
- A SELV supply provides safe electrical isolation and limitation of the voltage without a connection to the protective conductor, a PELV supply also requires a safe connection to the protective conductor.

3.6 Connection

3.6.1 Connection system

⚠ WARNING

Risk of electric shock and damage of device!

Bring the bus terminal system into a safe, powered down state before starting installation, disassembly or wiring of the bus terminals!

Overview

The bus terminal system offers different connection options for optimum adaptation to the respective application:

- The terminals of ELxxxx and KLxxxx series with standard wiring include electronics and connection level in a single enclosure.
- The terminals of ESxxxx and KSxxxx series feature a pluggable connection level and enable steady wiring while replacing.
- The High Density Terminals (HD Terminals) include electronics and connection level in a single enclosure and have advanced packaging density.

Standard wiring (ELxxxx / KLxxxx)



Fig. 14: Standard wiring

The terminals of the ELxxxx and KLxxxx series integrate screwless spring-cage technology for quick and easy wiring.

Pluggable wiring (ESxxxx / KSxxxx)



Fig. 15: Pluggable wiring

The terminals of ESxxxx and KSxxxx series feature a pluggable connection level. The assembly and wiring procedure is the same as for the ELxxxx and KLxxxx series. The pluggable connection level enables the complete wiring to be removed as a plug connector from the top of the housing for servicing. The lower section can be removed from the terminal block by pulling the unlocking tab. Insert the new component and plug in the connector with the wiring. This reduces the installation time and eliminates the risk of wires being mixed up.

The familiar dimensions of the terminal only had to be changed slightly. The new connector adds about 3 mm. The maximum height of the terminal remains unchanged.

A tab for strain relief of the cable simplifies assembly in many applications and prevents tangling of individual connection wires when the connector is removed.

Conductor cross sections between 0.08 mm² and 2.5 mm² can continue to be used with the proven spring force technology.

The overview and nomenclature of the product names for ESxxxx and KSxxxx series has been retained as known from ELxxxx and KLxxxx series.

High Density Terminals (HD Terminals)



Fig. 16: High Density Terminals

The terminals from these series with 16/32 terminal points are distinguished by a particularly compact design, as the packaging density is twice as large as that of the standard 12 mm bus terminals. Massive conductors and conductors with a wire end sleeve can be inserted directly into the spring loaded terminal point without tools.



Wiring HD Terminals

The High Density Terminals of the ELx8xx and KLx8xx series doesn't support pluggable wiring.

Ultrasonically compacted (ultrasonically welded) strands



Ultrasonically compacted (ultrasonically welded) strands

Ultrasonically compacted (ultrasonically welded) strands can also be connected to the standard and high-density terminals. In this case, please note the tables concerning the wire-size width [► 29]!

3.6.2 Wiring

⚠ WARNING

Risk of electric shock and damage of device!

Bring the bus terminal system into a safe, powered down state before starting installation, disassembly or wiring of the bus terminals!

Terminals for standard wiring ELxxxx/KLxxxx and for pluggable wiring ESxxxx/KSxxxx

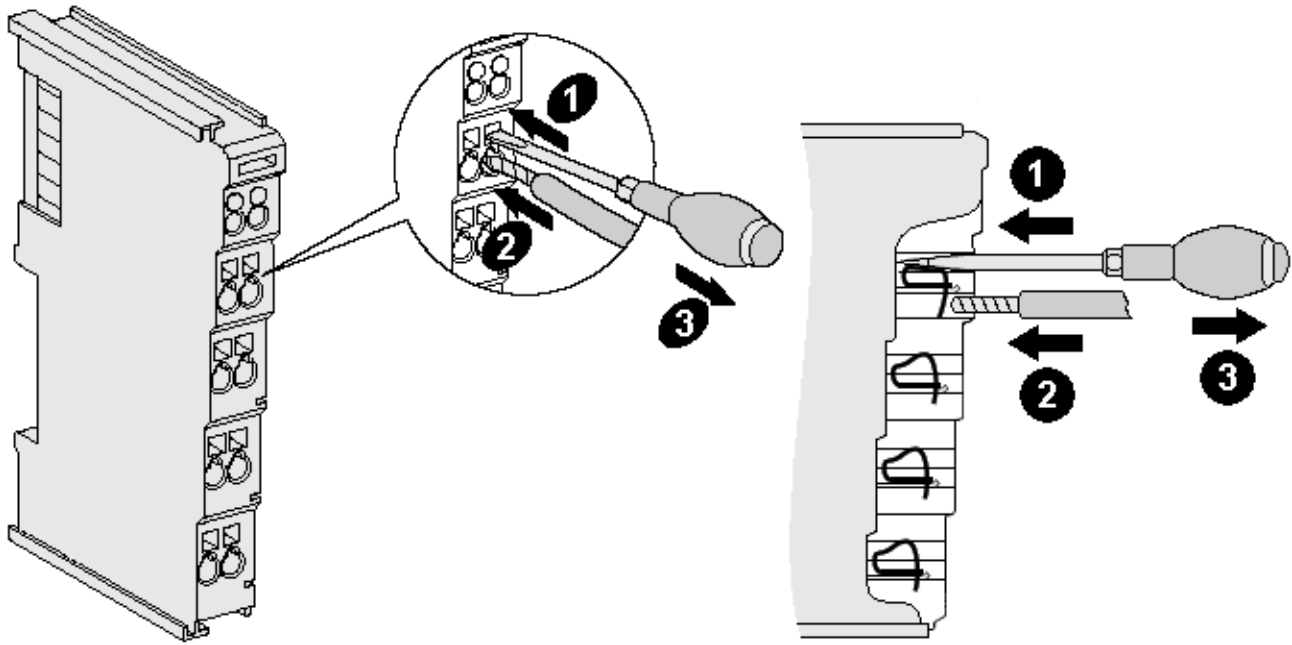


Fig. 17: Connecting a cable on a terminal point

Up to eight terminal points enable the connection of solid or finely stranded cables to the bus terminal. The terminal points are implemented in spring force technology. Connect the cables as follows (see fig. "Connecting a cable on a terminal point"):

1. Open a terminal point by pushing a screwdriver straight against the stop into the square opening above the terminal point. Do not turn the screwdriver or move it alternately (don't toggle).
2. The wire can now be inserted into the round terminal opening without any force.
3. When the screwdriver is removed, the terminal point closes automatically and holds the wire securely and permanently in place

See the following table for the suitable wire size width:

Terminal housing	ELxxxx, KLxxxx	ESxxxx, KSxxxx
Wire size width (single core wires)	0.08 ... 2.5 mm ²	0.08 ... 2.5 mm ²
Wire size width (fine-wire conductors)	0.08 ... 2.5 mm ²	0.08 ... 2.5 mm ²
Wire size width (conductors with a wire end sleeve)	0.14 ... 1.5 mm ²	0.14 ... 1.5 mm ²
Wire stripping length	8 ... 9 mm	9 ... 10 mm

High Density Terminals (HD Terminals [► 27]) with 16/32 terminal points

The conductors of the HD Terminals are connected without tools for single-wire conductors using the direct plug-in technique, i.e. after stripping the wire is simply plugged into the terminal point. The cables are released, as usual, using the contact release with the aid of a screwdriver. See the following table for the suitable wire size width.

Terminal housing	High Density Housing
Wire size width (single core wires)	0.08 ... 1.5 mm ²
Wire size width (fine-wire conductors)	0.25 ... 1.5 mm ²
Wire size width (conductors with a wire end sleeve)	0.14 ... 0.75 mm ²
Wire size width (ultrasonically compacted [ultrasonically welded] strands)	only 1.5 mm ² (see <u>notice</u> [► 27])
Wire stripping length	8 ... 9 mm

3.6.3 Shielding



Shielding

Encoder, analog sensors and actuators should always be connected with shielded, twisted paired wires.

3.6.4 EL9562 - connection and LED displays

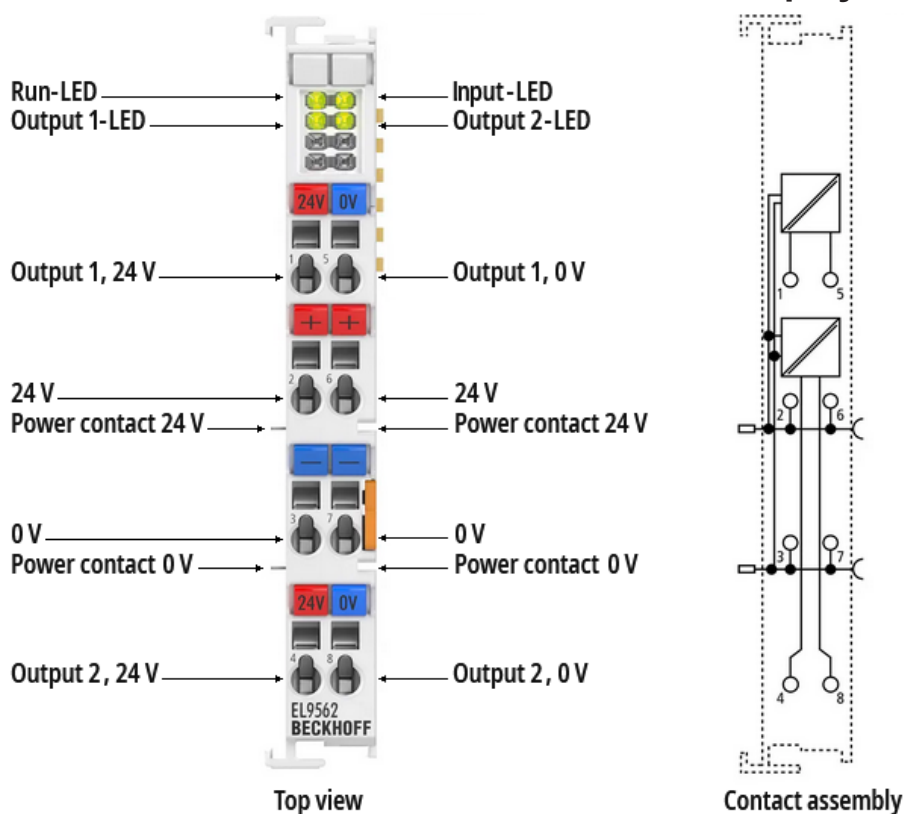


Fig. 18: EL9562 - connection and LED displays

Connection

Terminal point		Description
Name	No.	
Output 1, 24 V	1	Output 1, 24 V
24 V	2	24 V, internally connected to terminal point 6 and power contact 24 V
0 V	3	0 V, internally connected to terminal point 7 and power contact 0 V
Output 2, 24 V	4	Output 2, 24 V
Output 1, 0 V	5	Output 1, 0 V
24 V	6	24 V, internally connected to terminal point 2 and power contact 24 V
0 V	7	0 V, internally connected to terminal point 3 and power contact 0 V
Output 2, 0 V	8	Output 2, 0 V

LED displays

LED	Color	Display	Meaning
Run	green	lit	Terminal is exchanging data
Output 1	green	lit	Output voltage 1 active
Input	green	lit	Input voltage Up present
Output 2	green	lit	Output voltage 2 active

3.6.5 EL9562-0015 - connection and LED displays

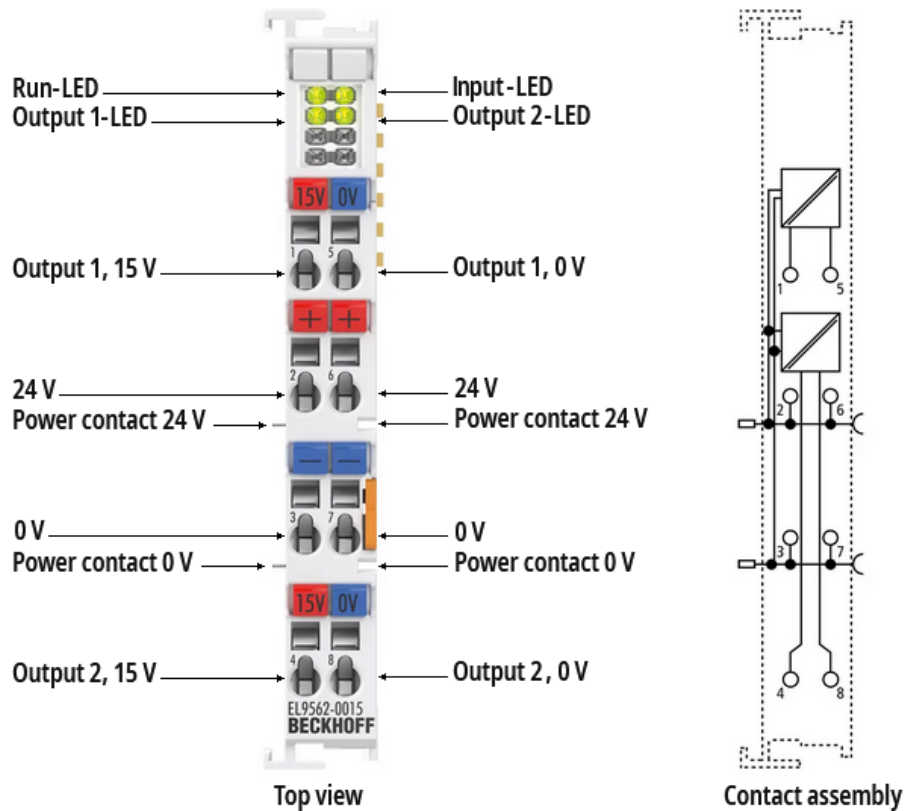


Fig. 19: EL9562-0015 - connection and LED displays

Connection

Terminal point		Description
Name	No.	
Output 1, 15 V	1	Output 1, 15 V
24 V	2	24 V, internally connected to terminal point 6 and power contact 24 V
0 V	3	0 V, internally connected to terminal point 7 and power contact 0 V
Output 2, 15 V	4	Output 2, 15 V
Output 1, 0 V	5	Output 1, 0 V
24 V	6	24 V, internally connected to terminal point 2 and power contact 24 V
0 V	7	0 V, internally connected to terminal point 3 and power contact 0 V
Output 2, 0 V	8	Output 2, 0 V

LED displays

LED	Color	Display	Meaning
Run	green	lit	Terminal is exchanging data
Output 1	green	lit	Output voltage 1 active
Input	green	lit	Input voltage Up present
Output 2	green	lit	Output voltage 2 active

3.7 UL notice

⚠ CAUTION	
	Application Beckhoff EtherCAT modules are intended for use with Beckhoff's UL Listed EtherCAT System only.
⚠ CAUTION	
	Examination For cULus examination, the Beckhoff I/O System has only been investigated for risk of fire and electrical shock (in accordance with UL508 and CSA C22.2 No. 142).
⚠ CAUTION	
	For devices with Ethernet connectors Not for connection to telecommunication circuits.
⚠ WARNING	
	Operating of the Beckhoff Terminal EL9260 with Beckhoff Terminal EL1702-0020 Fuses have to be specified as 250Vac/6.3A/size 20x5.2mm as all of these parameters are critical for safety.

Basic principles

UL certification according to UL508. Devices with this kind of certification are marked by this sign:



3.8 Disposal



Products marked with a crossed-out wheeled bin shall not be discarded with the normal waste stream. The device is considered as waste electrical and electronic equipment. The national regulations for the disposal of waste electrical and electronic equipment must be observed.

4 Commissioning

4.1 Inserting the terminal in the EtherCAT terminal network

(Master: TwinCAT 2.1x)

● Installation of the latest XML device description



Please ensure that you have installed the corresponding latest XML device description in TwinCAT. This can be downloaded from the Beckhoff Website and installed according to the installation instructions.

The configuration tree in the Beckhoff TwinCAT System Manager can be created in 2 ways:

- by scanning of existing hardware (referred to as “online”), or
- by manually inserting/appending fieldbus devices, couplers and slaves.

Automatic scanning in of the terminal

- The Bus Terminal system must be in a safe, de-energized state before the terminals are inserted into the terminal network as described in section [Mounting rail installation](#) [► 19].
- Once the operating voltage has been switched on, open the TwinCAT System Manager (Config mode) and scan in the terminal (see Fig. *Scanning in the EtherCAT configuration (I/O Devices -> right click -> Scan Devices...)*). Acknowledge all dialogs with “OK”, so that the configuration is in “FreeRun” mode.

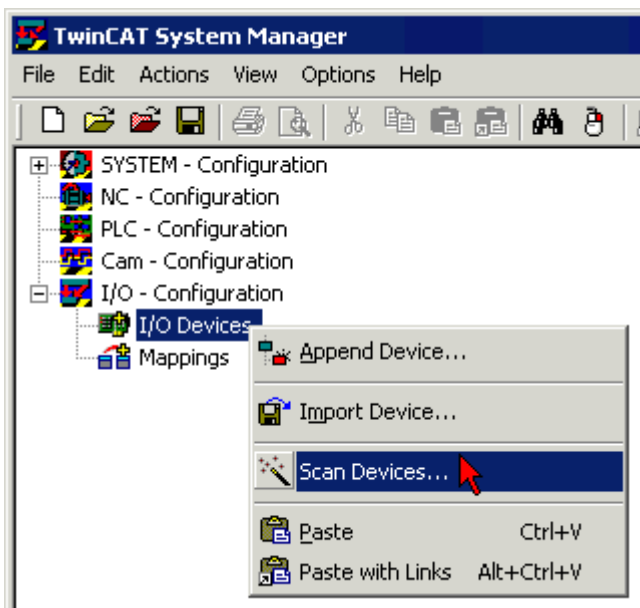


Fig. 20: Scanning in the EtherCAT configuration (I/O Devices-> right-click -> Scan Devices...)

Appending a terminal manually

- The Bus Terminal system must be in a safe, de-energized state before the terminals are inserted into the terminal network as described in section [Mounting rail installation](#) [► 19].
- Switch on the operating voltage, open the TwinCAT System Manager (Config mode)
- Appending a new I/O device (see Fig. *Appending a new I/O device (I/O Devices -> right click -> Append Device...)*). In the dialog that follows select the device *EtherCAT (Direct Mode)*, see Fig. *Selecting the device EtherCAT (Direct Mode)* and confirm with OK.

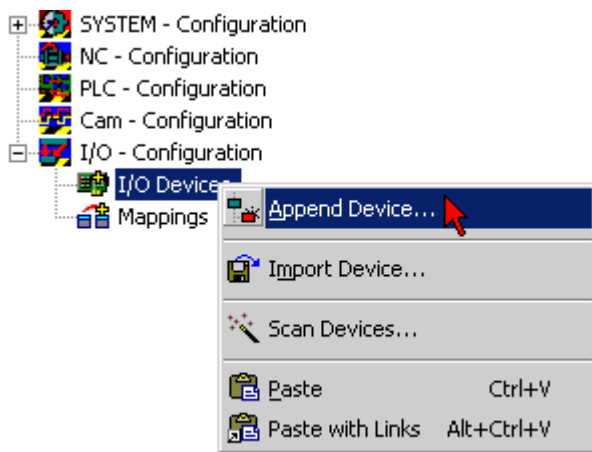


Fig. 21: Appending a new I/O device (I/O Devices-> right-click -> Append Device...)

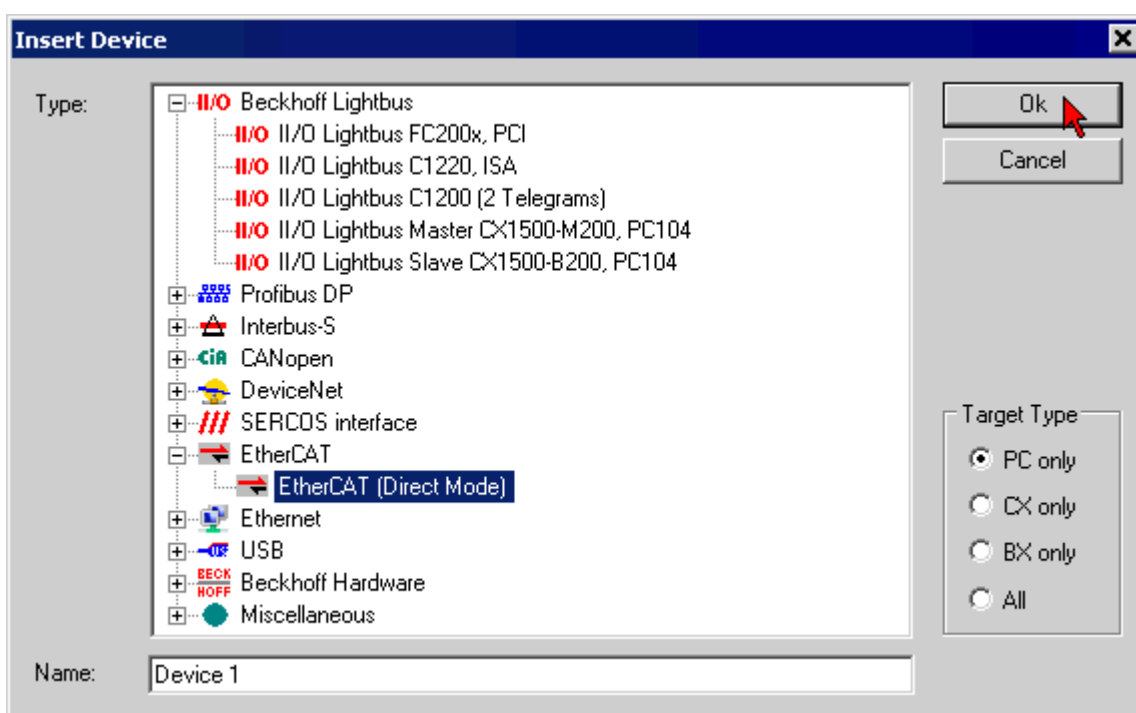


Fig. 22: Selecting the device EtherCAT (Direct Mode)

- Appending a new box (see Fig. *Appending a new box (Device -> right click -> Append Box...)*). In the dialog that follows select an EK1100 system coupler, for example (see Fig. *Selecting a system coupler (e.g. EK1100)*) and confirm with OK.

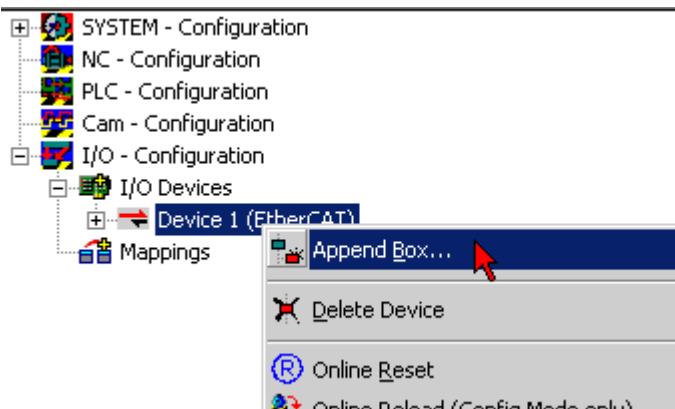


Fig. 23: Appending a new box (Device -> right-click -> Append Box...)

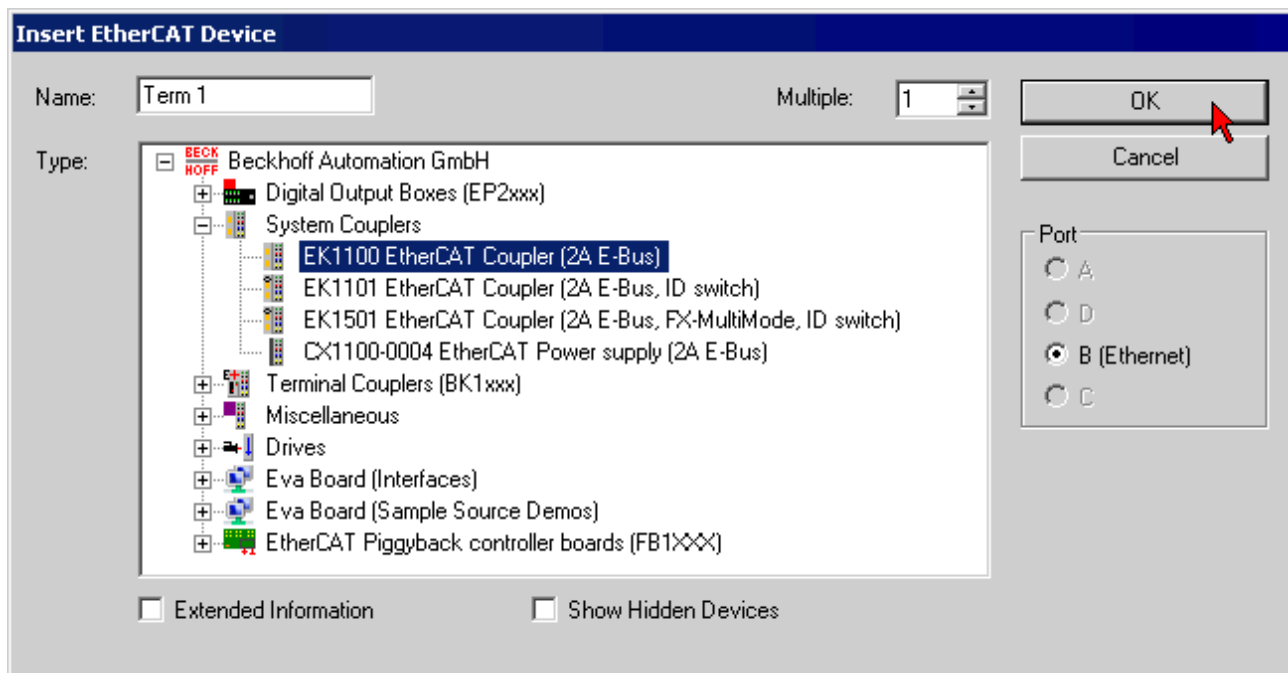


Fig. 24: Selecting a system coupler (e.g. EK1100)

- Appending a new box (see Fig. *Appending a new box (Device -> right click -> Append Box...)*). In the dialog that follows select the EL95xx, (see Fig. *Selecting the terminal, e.g. EL9505*) and confirm with OK.
- The terminal is added in the TwinCAT tree (see Fig. *Terminal in the TwinCAT tree*).

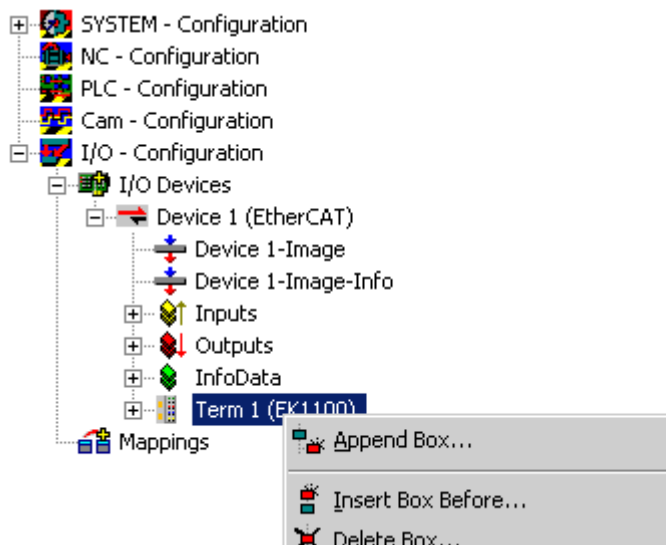


Fig. 25: Appending a new box (Device -> right-click -> Append Box...)

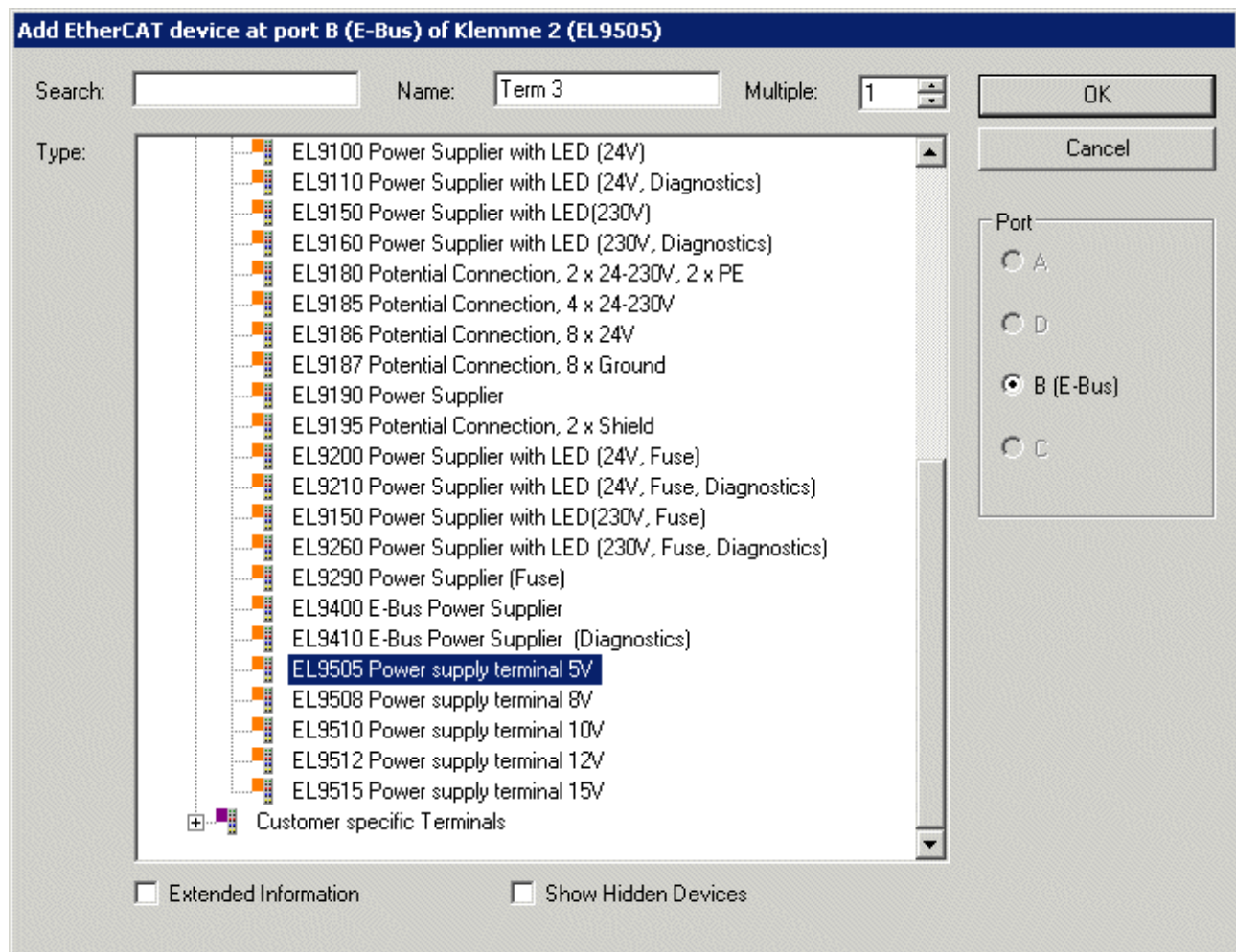


Fig. 26: Selecting the terminal, e.g. EL9505

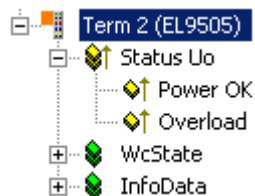


Fig. 27: Terminal in the TwinCAT tree

4.2 Process data

TwinCAT displays the process data of the EL9562 in a tree structure.

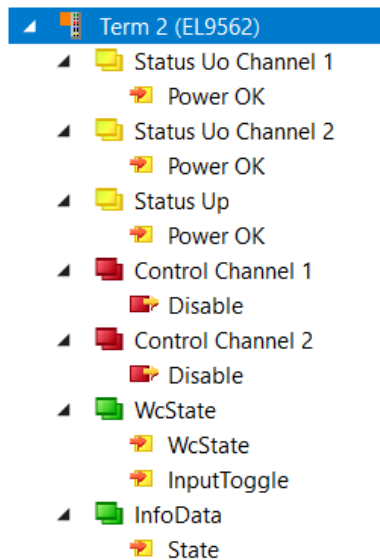


Fig. 28: EL9562 - Tree structure

The EL9562 contains the three input objects:

- Status Uo Channel 1 (0x1A00) with the *Power OK* signal for the status of output voltage 1
- Status Uo Channel 2 (0x1A01) with the *Power OK* signal for the status of output voltage 2
- Status Up (0x1A02) with the *Power OK* signal for the status of the input voltage Up (24 V)

The EL9562 contains the two output objects:

- Control Channel 1 (0x1600) with the *Disable* output for switching off the output voltage 1
- Control Channel 2 (0x1601) with the *Disable* output for switching off the output voltage 2

TwinCAT Project3

General | EtherCAT | **Process Data** | Online

Sync Manager:

SM	Size	Type	Flags
0	1	Outputs	
1	1	Inputs	

PDO List:

Index	Size	Name	Flags	SM	SU
0x1A00	0.3	Status Uo Channel 1	MF	1	0
0x1A01	0.1	Status Uo Channel 2	MF	1	0
0x1A02	0.1	Status Up	MF	1	0
0x1600	0.1	Control Channel 1	MF	0	0
0x1601	0.1	Control Channel 2	MF	0	0

PDO Assignment (0x1C10):

☒ 0x1600
☒ 0x1601

PDO Content (0x1A00):

Index	Size	Offs	Name	Type	Default (hex)
---	0.1	0.0	---		
---	0.1	0.1	---		
0x6000:01	0.1	0.2	Power OK	BIT	
	0.3				

Download:

☐ PDO Assignment
☐ PDO Configuration

Predefined PDO Assignment (none)

Load PDO info from device

Sync Unit Assignment..

Fig. 29: EL9562 - Process data



On delivery, the output voltages of the EL9562 are switched on

As soon as the EL9562-xxxx is supplied with input voltage (24 V_{DC}), the two output voltages are present, even if no EtherCAT communication is taking place.

The output voltages must be actively switched off by setting the process data *Control Channel 1 / Disable* or *Control Channel 2 / Disable*.

4.3 Firmware compatibility

The terminals of the EL95xx series have no firmware.

5 Appendix

5.1 Support and Service

Beckhoff and their partners around the world offer comprehensive support and service, making available fast and competent assistance with all questions related to Beckhoff products and system solutions.

Beckhoff's branch offices and representatives

Please contact your Beckhoff branch office or representative for local support and service on Beckhoff products!

The addresses of Beckhoff's branch offices and representatives round the world can be found on her internet pages: www.beckhoff.com

You will also find further documentation for Beckhoff components there.

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The Beckhoff Support offers you comprehensive technical assistance, helping you not only with the application of individual Beckhoff products, but also with other, wide-ranging services:

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- design, programming and commissioning of complex automation systems
- and extensive training program for Beckhoff system components

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- spare parts service
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