BECKHOFF New Automation Technology

Documentation | EN

EP9224-0037

4-channel power distribution, ENP to EtherCAT P



2026-09-16 | Version: 1.6

Table of contents

1 Foreword 5
1.1 Notes on the documentation 5
1.2 Safety instructions 6
1.3 Documentation issue status 7

2 EtherCAT Box - Introduction 8

3 Product overview 10
3.1 Introduction 10
3.2 Block diagram 11
3.3 Technical data 11
3.4 Scope of supply 14
3.5 Process image 15
3.6 Basic Function Principles 19
3.6.1 Internal EtherCAT data flow 19

4 Mounting and cabling 20
4.1 Mounting 20
4.1.1 Dimensions 20
4.1.2 Fixing 21
4.1.3 Tightening torques for plug connectors 21
4.2 Functional earth (FE) 22
4.3 Supply voltage input and downstream connection 23
4.3.1 Connection 24
4.3.2 Status LEDs 25
4.3.3 Conductor losses 25
4.4 EtherCAT input and downstream connection 26
4.4.1 Connection 26
4.4.2 Status LEDs 27
4.5 EtherCAT P 28
4.5.1 Connection 28
4.5.2 Status LEDs 29
4.5.3 Conductor losses 30
4.6 Disposal 31

5 Commissioning and configuration 32
5.1 Integration in TwinCAT 32
5.1.1 Assignment of the connections 32
5.2 Protective functions 35
5.2.1 Overload protection 36
5.2.2 Overcurrent protection for sum currents 39
5.2.3 Undervoltage protection 40
5.2.4 Overtemperature protection 40
5.2.5 Warning and error messages 41
5.3 Diagnostic functions 42
5.3.1 Data logger 42
5.3.2 Peak value detector 45

5.4 Switch output voltages 48
5.5 Restore the delivery state 50

6 CoE parameters 51
6.1 Objects for parameterization 52
6.2 Standard objects 59
6.3 Profile-specific objects 69

7 Appendix 73
7.1 General operating conditions 73
7.2 Accessories 74
7.3 Version identification of EtherCAT devices 75
7.3.1 General notes on marking 75
7.3.2 Version identification of IP67 modules 76
7.3.3 Beckhoff Identification Code (BIC) 77
7.3.4 Electronic access to the BIC (eBIC) 79
7.4 Support and Service 81

1 Foreword

1.1 Notes on the documentation

Intended audience

This description is only intended for the use of trained specialists in control and automation engineering who are familiar with the applicable national standards.
It is essential that the documentation and the following notes and explanations are followed when installing and commissioning these components.
The qualified personnel is obliged to always use the currently valid documentation.

The responsible staff must ensure that the application or use of the products described satisfy all the requirements for safety, including all the relevant laws, regulations, guidelines and standards.

Disclaimer

The documentation has been prepared with care. The products described are, however, constantly under development.

We reserve the right to revise and change the documentation at any time and without prior announcement.

No claims for the modification of products that have already been supplied may be made on the basis of the data, diagrams and descriptions in this documentation.

Trademarks

Beckhoff®, ATRO®, EtherCAT®, EtherCAT G®, EtherCAT G10®, EtherCAT P®, MX-System®, Safety over EtherCAT®, TC/BSD®, TwinCAT®, TwinCAT/BSD®, TwinSAFE®, XFC®, XPlanar® and XTS® are registered trademarks of and licensed by Beckhoff Automation GmbH.

Other designations used in this publication may be trademarks whose use by third parties for their own purposes could violate the rights of the owners.





EtherCAT® and EtherCAT P® are registered trademarks and patented technologies, licensed by Beckhoff Automation GmbH, Germany.

Copyright

© Beckhoff Automation GmbH & Co. KG, Germany.
The reproduction, distribution and utilization of this document as well as the communication of its contents to others without express authorization are prohibited.
Offenders will be held liable for the payment of damages. All rights reserved in the event of the grant of a patent, utility model or design.

Third-party brands

Trademarks of third parties may be used in this documentation. You can find the trademark notices here:
https://www.beckhoff.com/trademarks

1.2 Safety instructions

Safety regulations

Please note the following safety instructions and explanations!
Product-specific safety instructions can be found on following pages or in the areas mounting, wiring, commissioning etc.

Exclusion of liability

All the components are supplied in particular hardware and software configurations appropriate for the application. Modifications to hardware or software configurations other than those described in the documentation are not permitted, and nullify the liability of Beckhoff Automation GmbH & Co. KG.

Personnel qualification

This description is only intended for trained specialists in control, automation and drive engineering who are familiar with the applicable national standards.

Signal words

The signal words used in the documentation are classified below. In order to prevent injury and damage to persons and property, read and follow the safety and warning notices.

Personal injury warnings

⚠ DANGER
Hazard with high risk of death or serious injury.

⚠ WARNING
Hazard with medium risk of death or serious injury.

⚠ CAUTION
There is a low-risk hazard that could result in medium or minor injury.

Warning of damage to property or environment

NOTICE
The environment, equipment, or data may be damaged.

Information on handling the product

This information includes, for example:
recommendations for action, assistance or further information on the product.

1.3 Documentation issue status

Version	Comment
1.6	• Technical data updated
1.5	• Overload protection updated
1.4	• CoE parameters updated
1.3	• Technical data updated.
1.2	• Block diagram added • Chapter added: "Internal EtherCAT data flow" • Dimensions updated
1.1	• Front page updated
1.0	• First release

Firmware and hardware versions

This documentation refers to the firmware and hardware version that was applicable at the time the documentation was written.

The module features are continuously improved and developed further. Modules having earlier production statuses cannot have the same properties as modules with the latest status. However, existing properties are retained and are not changed, so that older modules can always be replaced with new ones.

The firmware and hardware version (delivery state) can be found in the batch number (D-number) printed on the side of the EtherCAT Box.

Syntax of the batch number (D-number)

D: WW YY FF HH	Example with D no. 29 10 02 01:
WW - week of production (calendar week) YY - year of production FF - firmware version HH - hardware version	29 - week of production 29 10 - year of production 2010 02 - firmware version 02 01 - hardware version 01

Further information on this topic: Version identification of EtherCAT devices [▶ 75].

2 EtherCAT Box - Introduction

The EtherCAT system has been extended with EtherCAT Box modules with protection rating IP67. Through the integrated EtherCAT interface the modules can be connected directly to an EtherCAT network without an additional Coupler Box. The high-performance of EtherCAT is thus maintained into each module.

The extremely low dimensions of only 126 x 30 x 26.5 mm (h x w x d) are identical to those of the Fieldbus Box extension modules. They are thus particularly suitable for use where space is at a premium. The small mass of the EtherCAT modules facilitates applications with mobile I/O interface (e.g. on a robot arm). The EtherCAT connection is established via screened M8 connectors.

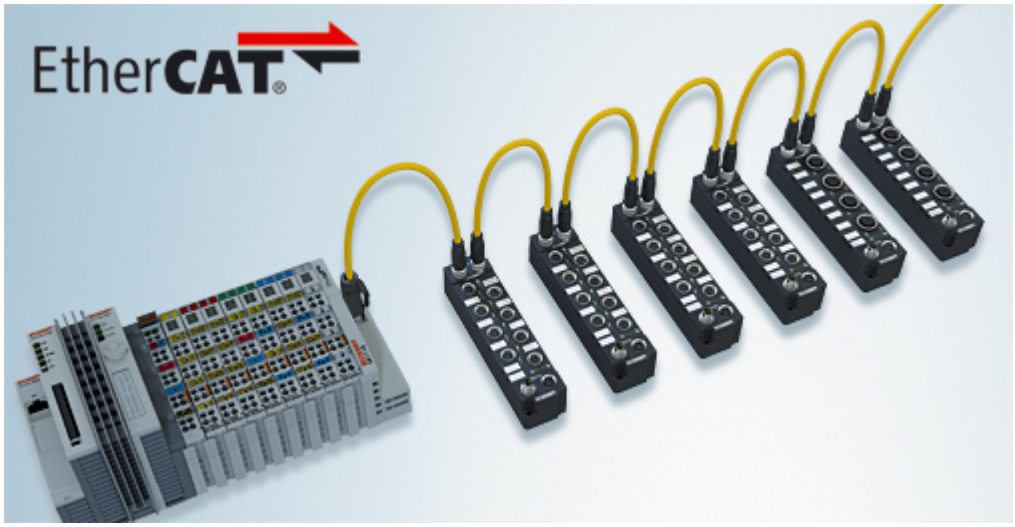


Fig. 1: EtherCAT Box Modules within an EtherCAT network

The robust design of the EtherCAT Box modules enables them to be used directly at the machine. Control cabinets and terminal boxes are now no longer required. The modules are fully sealed and therefore ideally prepared for wet, dirty or dusty conditions.

Pre-assembled cables significantly simplify EtherCAT and signal wiring. Very few wiring errors are made, so that commissioning is optimized. In addition to pre-assembled EtherCAT, power and sensor cables, field-configurable connectors and cables are available for maximum flexibility. Depending on the application, the sensors and actuators are connected through M8 or M12 connectors.

The EtherCAT modules cover the typical range of requirements for I/O signals with protection rating IP67:

- digital inputs with different filters (3.0 ms or 10 µs)
- digital outputs with 0.5 or 2 A output current
- analog inputs and outputs with 16 bit resolution
- Thermocouple and RTD inputs
- Stepper motor modules

XFC (eXtreme Fast Control Technology) modules, including inputs with time stamp, are also available.



Fig. 2: EtherCAT Box with M8 connections for sensors/actuators



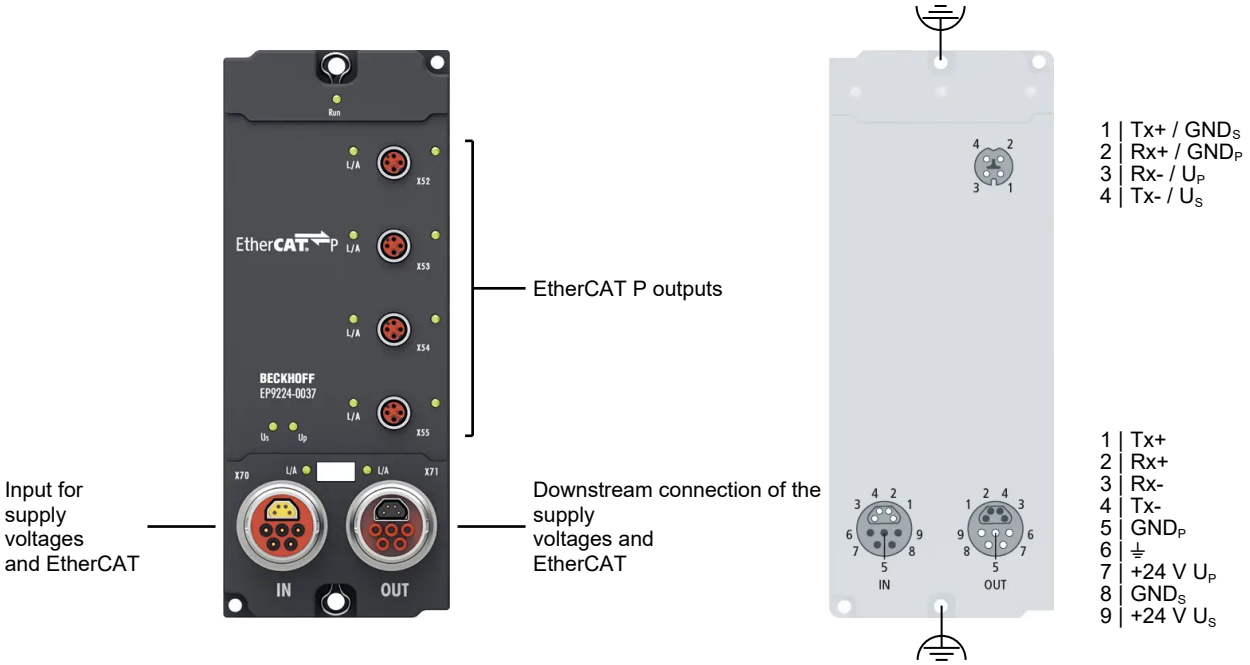
Fig. 3: EtherCAT Box with M12 connections for sensors/actuators

Basic EtherCAT documentation

You will find a detailed description of the EtherCAT system in the Basic System Documentation for EtherCAT, which is available for download from our website (www.beckhoff.com) under Downloads.

3 Product overview

3.1 Introduction



4-channel power distribution, ENP to EtherCAT P

The EP9224-0037 EtherCAT Box distributes an EtherCAT signal to four EtherCAT P ports.

It measures supply voltages, output currents and its own temperature. The measured values are available as process data.

Internal protective functions use the measured values to switch off the output voltages of the EtherCAT P ports in case of error. This prevents damage and malfunctions:

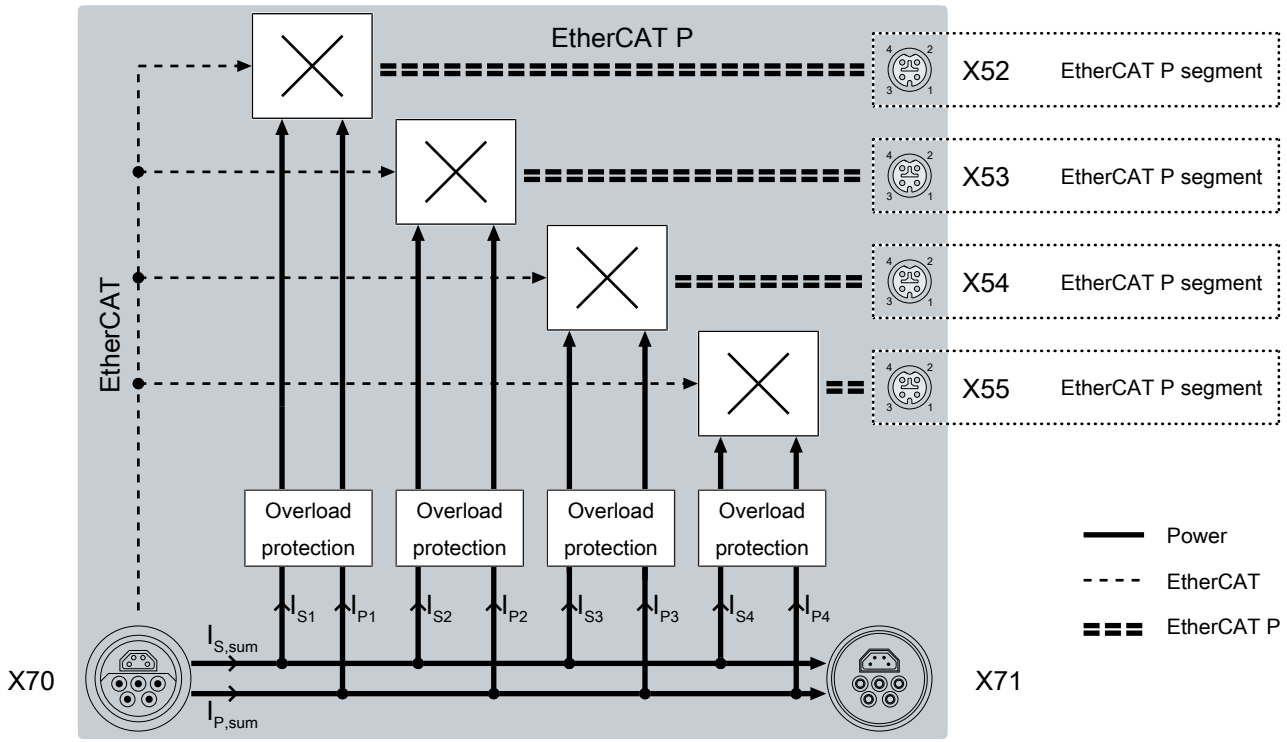
- Overloading of the supply line
- Overloading of the power supply unit
- Overloading of the EtherCAT P cables
- Undervoltage of the supply voltages

The EP9224-0037 has a peak value detector and a data logger for the diagnosis of errors.

Quick links

Technical data [▶ 11]
Process image [▶ 15]
Dimensions [▶ 20]
Commissioning and configuration [▶ 32]

3.2 Block diagram



3.3 Technical data

All values are typical values over the entire temperature range, unless stated otherwise.

EtherCAT	
Connection	ENP B17 – connector
Electrical isolation	500 V

Supply voltages	
Connection	Power supply (X70): plug B17 5G 1.5mm² ENP Downstream connection (X71): socket B17 5G 1.5mm² ENP
U_S rated voltage	24 V DC (-15%, +20%)
U_S sum current $I_{S,sum}$	max. 15.5 A at 45 °C
Current consumption from U_S	110 mA + Load: I_{S1}, I_{S2}, I_{S3}, I_{S4}
Rated voltage U_P	24 V DC (-15 %, +20 %)
U_P sum current $I_{P,sum}$	max. 15.5 A at 45 °C
Current consumption from U_S	40 mA + Load: I_{P1}, I_{P2}, I_{P3}, I_{P4}

EtherCAT P ports	from hardware 04	up to hardware 03
Number	4	4
Connection	4 x M8 female socket, P-coded, 4-pin, shielded	4 x M8 female socket, P-coded, 4-pin, shielded
Cable length per port	max. 75 m	max. 75 m
Number of EtherCAT P slaves per port	max. 10 [1)]	max. 10 [1)]
Output current per port	max. 3 A per U_S and U_P	max. 3 A per U_S and U_P
Current limitation per port	3.3 A per U_S and U_P	5 A per U_S and U_P. Shutdown after typ. 75 ms current limitation.
Power limitation per port	100 W per U_S and U_P	--
Fuse per port (fail-safe element)	Fuse 5 A according to UL 248-1	Rated current: 5 A Melting integral I^2t: 5.566 A^2 s. (with a pulse width of 8 ms)
Capacitive load per port	max. 2200 µF per U_S and U_P	
Time offset for switching on the ports [2)]	Adjustable [▶ 48]: • “Fast” = 10 ms • “Moderate” = 100 ms (default) • “Slow” = 200 ms	
Power loss at full load	max. 10 W (at 3 A output current per U_S and U_P on all ports)	

[1)] This value is a typical value. The number of EtherCAT P slaves actually possible per segment can be affected by:

- the inrush current of sensors/actuators connected to the EtherCAT P slaves
- cable lengths

[2)] The output voltages of the EtherCAT P ports are switched on one after the other at the start so that the inrush currents do not add up. See chapter Switch output voltages [▶ 48].

Protective functions and diagnostics	
Overtemperature protection	Threshold values: T_{warn} = 75 °C → Warning if exceeded T_{err} = 85 °C → Error message if exceeded
Undervoltage protection	Threshold values: U_{warn} = 21.6 V → Warning when falling below U_{err} = 19.1 V → Error message when falling below
Data logger: sampling interval	Adjustable [▶ 42]: • 1 ms • 10 ms (default) • 25 ms • 100 ms • 1000 ms
Data logger: buffer size	25 entries.

Measured values	
Resolution	Measured current values: 10 mA Measured sum current values U_S + U_P: 10 mA Measured voltage values: 100 mV Measured temperature values: 1 K
Representation	Measured current values: 1 mA / LSB Measured sum current values U_S + U_P: 10 mA / LSB Measured voltage values: 100 mV / LSB Measured temperature values: 1 K / LSB (Celsius scale)

Housing data	
Dimensions W × H × D	60 mm × 150 mm × 26,5 mm (without connectors)
Weight	approx. 540 g
Installation position	variable
Material	PA6 (polyamide)

Environmental conditions	
Ambient temperature during operation	-25…+60 °C -25…+55 °C according to cURus
Ambient temperature during storage	-40…+85 °C
Vibration resistance, shock resistance	conforms to EN 60068-2-6 / EN 60068-2-27 Additional tests [▶ 13]
EMC immunity / emission	conforms to EN 61000-6-2 / EN 61000-6-4
Protection rating	IP65, IP66, IP67 (conforms to EN 60529)

Approvals / markings	
Approvals / markings *)	CE, UL under preparation

*) Real applicable approvals/markings see type plate on the side (product marking).

Additional tests

The devices have undergone the following additional tests:

Test	Explanation
Vibration	10 frequency sweeps in 3 axes
	5 Hz < f < 60 Hz displacement 0.35 mm, constant amplitude
	60.1 Hz < f < 500 Hz acceleration 5 g, constant amplitude
Shocks	1000 shocks in each direction, in 3 axes
	35 g, 11 ms

3.4 Scope of supply

Make sure that the following components are included in the scope of delivery:

- 1x EP9224-0037
- 4x protective caps for EtherCAT P socket (mounted)
- 10x labels, blank (1 strip of 10)

Pre-assembled protective caps do not ensure IP67 protection

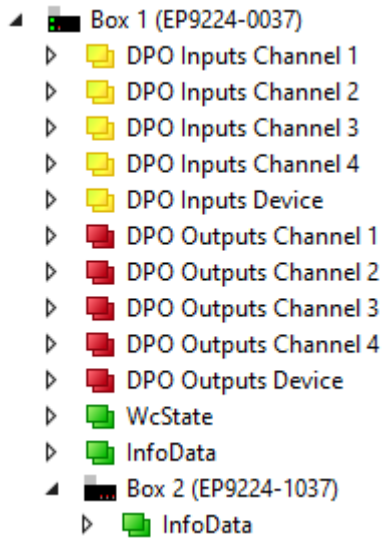
Protective caps are pre-assembled at the factory to protect connectors during transport. They may not be tight enough to ensure IP67 protection.

Ensure that the protective caps are correctly seated to ensure IP67 protection.

3.5 Process image

The EtherCAT P ports are labeled "Channel 1" to "Channel 4" in the process image. The following table shows the correlation between the designations in the process image and the designations of the EtherCAT P ports:

Designation in the process image	EtherCAT P port
Channel 1	X52
Channel 2	X53
Channel 3	X54
Channel 4	X55



DPO Inputs Channel n
Status bits of the channels.

DPO Inputs Device
Status bits of the entire device.

DPO Outputs Channel n
Output bits of the channels.

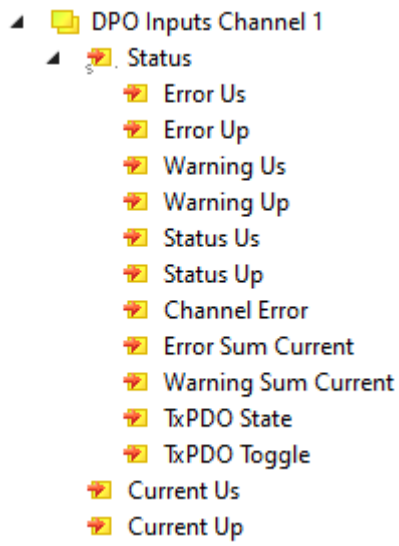
DPO Outputs Device
Output bits of the entire device.

WcState and **InfoData**
EtherCAT system variables.

EP9224-1037
I/O module that represents the second EtherCAT Slave Controller in the device. See chapter Basic Function Principles [▶ 19].

DPO Inputs Channel 1 to 4

Status bits of the individual channels.



Error Us: U_S was switched off due to overload.

Error Up: U_P was switched off due to overload.

Warning Us: The output current U_S currently exceeds the nominal current (CoE parameter 80n0:12).
If the overcurrent persists, U_S is switched off on this channel.

Warning Up: The output current U_S currently exceeds the nominal current (CoE parameter 80n0:13).
If the overcurrent persists, U_P is switched off on this channel.

Status Us: Switching status (on/off) of the output voltage U_S.

Status Up: Switching status (on/off) of the output voltage U_P.

Channel Error: "Error Us" or "Error Up" is TRUE.

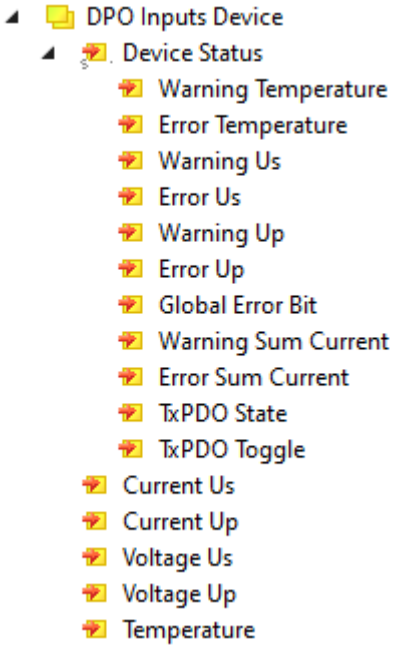
Error Sum Current: The channel was switched off due to sum overcurrent.

Warning Sum Current: The sum current $I_S + I_P$ of the channel currently exceeds the nominal sum current (CoE parameter 80n0:14).
If the overcurrent persists, the channel is switched off.

Current Us, Current Up: 16-bit measured values of the current output currents.

DPO Inputs Device

Status bits for the entire device.



Temperature Warning: The internal temperature exceeds the warning threshold.

Temperature Error: The internal temperature has exceeded the error threshold. The output channels have been switched off.

U_S Warning, U_P Warning: Undervoltage warning. The respective input voltage is currently below the warning threshold value U_{warn}.

Us Error, Up Error: Undervoltage switch-off. The respective input voltage has fallen below the error threshold value U_{err}.
The output voltages have been switched off.

Global Error Bit: There is at least one error message.

Sum Current Warning: The input sum current $I_S + I_P$ currently exceeds the nominal sum current (CoE parameter F80E:12).
If the overcurrent persists, all channels are switched off.

Error Sum Current: All output voltages were switched off due to sum overcurrent.

Current Us: Current U_S input current at supply voltage input X70.

Current Up: Current U_P input current at supply voltage input X70.

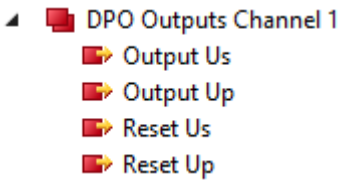
Voltage Us: Current value of the supply voltage U_S in 1/10V

Voltage Up: Current value of the supply voltage U_P in 1/10V

Temperature: Current internal temperature of the device.

DPO Outputs Channel 1 to 4

Output data for the individual channels.

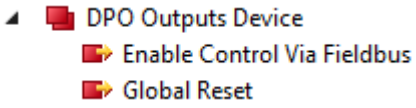


Output U_S, Output U_P: Switches the respective output voltage on or off.

Reset U_S, Reset U_P: Reset the error state of the respective output voltage.

DPO Outputs Device

Output data for the entire device.



Enable Control Via Fieldbus:

- TRUE: Enables the switching of the output voltages via the output variables "Output Us" and "Output Up".
- FALSE: Enables the automatic switching on of the output voltages according to the CoE parameters 80n0:02 and 80n0:03.

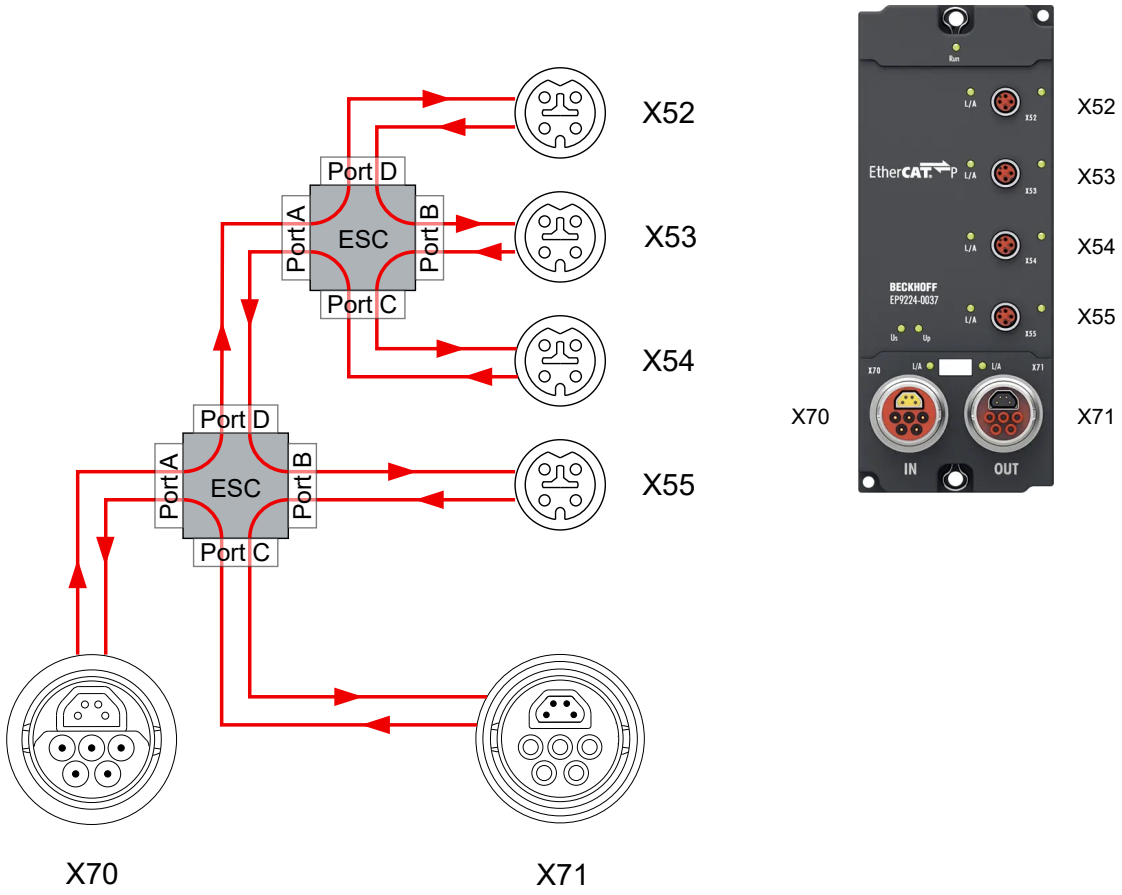
Global Reset: Reset the error state of the device and all channels.

3.6 Basic Function Principles

3.6.1 Internal EtherCAT data flow

The box contains two EtherCAT Slave Controller (ESC).

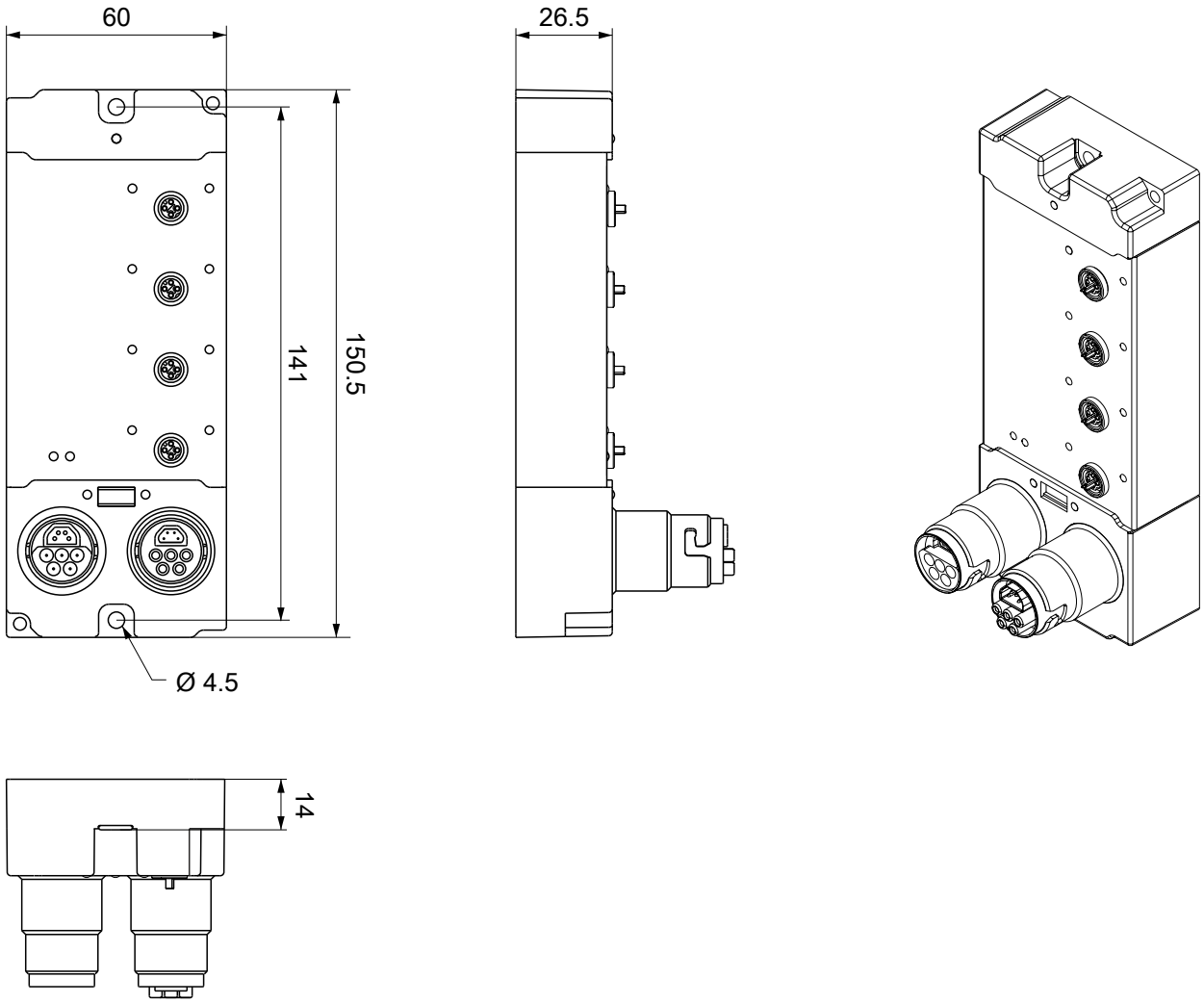
The following figure shows the logical path of an EtherCAT frame through the two ESCs. The ports on an ESC that do not have a device connected are automatically bypassed.



4 Mounting and cabling

4.1 Mounting

4.1.1 Dimensions



All dimensions are given in millimeters.
The drawing is not true to scale.

Housing features

Housing material	PA6 (polyamide)
Sealing compound	polyurethane
Mounting	two mounting holes Ø 4.5 mm for M4
Metal parts	brass, nickel-plated
Contacts	CuZn, gold-plated
Power feed through	max. 15.5 A at 45 °C (B17 5G 1.5 mm^2)
Installation position	variable
Protection rating	IP65, IP66, IP67 (conforms to EN 60529) when screwed together
Dimensions (H × W × D)	approx. 150 × 60 × 26.5 mm (without connectors)

4.1.2 Fixing

NOTICE

Dirt during assembly

Dirty connectors can lead to malfunctions. Protection rating IP67 can only be guaranteed if all cables and connectors are connected.

- Protect the plug connectors against dirt during the assembly.

Mount the module with two M4 screws in the centrally located mounting holes.

Cooling plate

The box has a cooling plate on the underside. For the effective dissipation of the resultant power loss, the box must be bolted to a metal base, e.g. the machine bed, if possible making contact over the entire surface. A temperature-related automatic switch-off of the box can occur if care is not taken to ensure that the power loss from the module is dissipated via the cooling plate. A corresponding temperature error bit is then set.

4.1.3 Tightening torques for plug connectors

M8 connector

Screw M8 connectors tight with a torque wrench. (e.g. ZB8801 from Beckhoff)
Torque: 0.4 Nm.

B17 connector

Screw B17 connectors tight by hand:
Plug the cable connector into the connector on the box to the stop. Turn the cap nuts of the cable connector clockwise by about 1/8 of a turn to the stop.

4.2 Functional earth (FE)

Functional earth via the mounting holes

The mounting holes also serve as connections for the functional earth.

Make sure that the box is grounded with low impedance via both fastening screws.



Functional earth via the supply lines

Starting with hardware version 03, the ⏚ pins 6 of the B17 connectors are directly connected to the mounting holes. Up to hardware version 02, they are connected to the mounting holes via an RC combination.

Connect the functional earth of the ⏚ cores in accordance with the following instructions:

- If the remote station is a device with B17 connector: connect the devices with a pre-assembled cable. See chapter Accessories [▶ 74].
- Otherwise: ground the ⏚ core with low impedance as near as possible to the remote station.
- Leave the cap nuts and housing of the B17 connectors without contact.

4.3 Supply voltage input and downstream connection

⚠ WARNING

Power supply from SELV / PELV power supply unit!

SELV / PELV circuits (safety extra-low voltage / protective extra-low voltage) according to IEC 61010-2-201 must be used to supply this device.

Notes:

- SELV / PELV circuits may give rise to further requirements from standards such as IEC 60204-1 et al, for example with regard to cable spacing and insulation.
- A SELV supply provides safe electrical isolation and limitation of the voltage without a connection to the protective conductor, a PELV supply also requires a safe connection to the protective conductor.

The EtherCAT Box has one input for two supply voltages:

- **Control voltage U_S**
  The following sub-functions are supplied from the control voltage U_S:
  - the fieldbus
  - the processor logic
  - typically the inputs and the sensors if the EtherCAT Box has inputs.
- **Peripheral voltage U_P**
  For EtherCAT Box modules with digital outputs the digital outputs are typically supplied from the peripheral voltage U_P. U_P can be supplied separately. If U_P is switched off, the fieldbus function, the function of the inputs and the supply of the sensors are maintained.

The exact assignment of U_S and U_P can be found in the pin assignment of the I/O connections.

Redirection of the supply voltages

The power IN and OUT connections are bridged in the module. Hence, the supply voltages U_s and U_p can be passed from EtherCAT Box to EtherCAT Box in a simple manner.

NOTICE

Note the maximum current!

Ensure that the permitted current for the connectors is not exceeded when routing the supply voltages U_S and U_P:

M8 connector: max. 4 A
7/8" connector: max 16 A

NOTICE

Unintentional cancellation of the electrical isolation possible

In some types of EtherCAT Box modules the ground potentials GND_S and GND_P are connected.

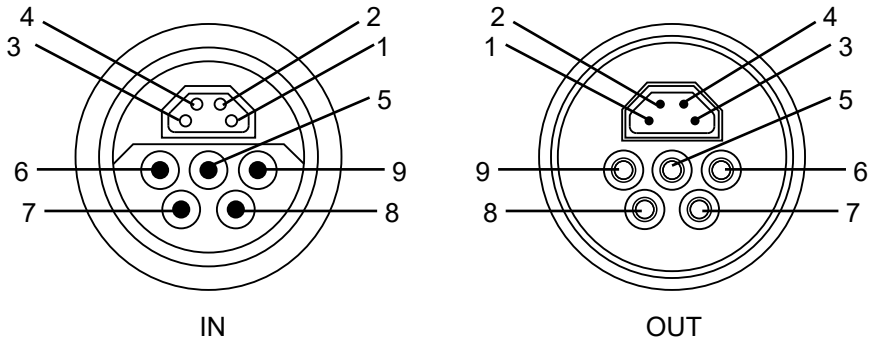
- If several EtherCAT Box modules are supplied with the same electrically isolated voltages, check whether there is an EtherCAT Box among them in which the ground potentials are connected.



4.3.1 Connection

The supply and forwarding of the supply voltages takes place via two 5-pin ENP B17 hybrid connectors at the lower end of the modules:

- X70 "IN": left B17 connector for feeding the supply voltages
- X71 "OUT": right B17 connector for routing the supply voltages



Pin	Voltage/signal	Core colors [1]
1	Tx+	yellow
2	Rx+	white
3	Rx-	blue
4	Tx-	orange
5	GND_P: ground for U_P	grey
6	⏚	green-yellow
7	U_P: peripheral voltage, +24 V_{DC}	black
8	GND_S: ground for U_S	blue
9	U_S: control voltage +24 V_{DC}	brown

[1] The core colors apply to cables, connectors and flanges of the type

- Beckhoff ZB7203-xxxx
- Beckhoff ZK7208-xxxx

4.3.2 Status LEDs

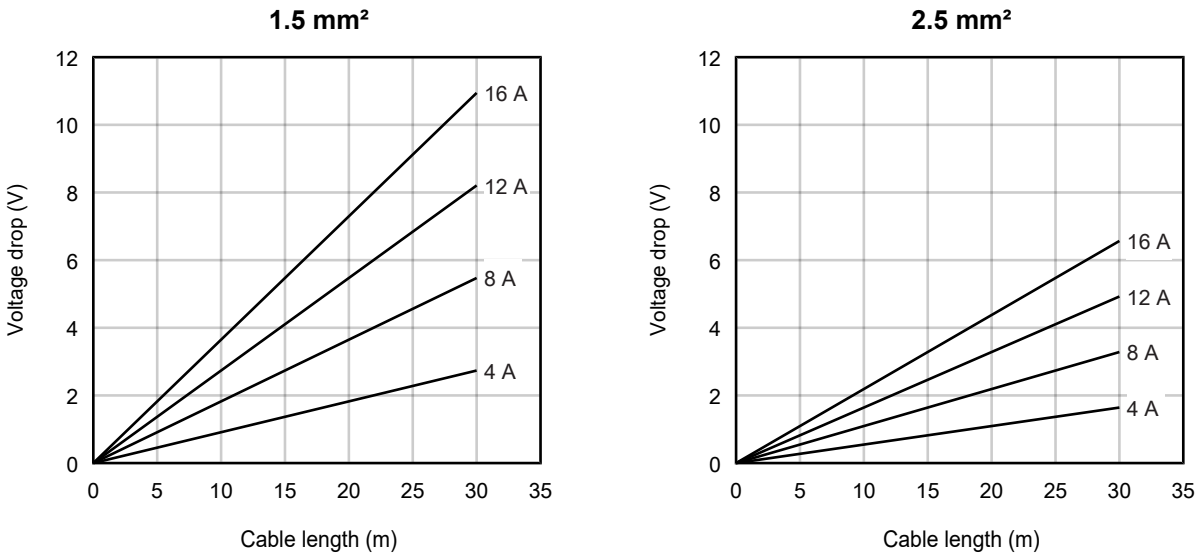
The status of the supply voltages is signaled by two LEDs. A Status LED lights up green when the respective supply voltage is present on the supply voltage input.



4.3.3 Conductor losses

Take into account the voltage drop on the supply line when planning a system. Avoid the voltage drop being so high that the supply voltage at the box lies below the minimum nominal voltage.
Variations in the voltage of the power supply unit must also be taken into account.

Voltage drop on the supply line



For 2.5 mm²: adapter required

Pre-assembled hybrid cables with B17 connectors are available only with a wire cross-section of 1.5 mm².
If you want to use a cable with a cross-section area of 2.5 mm², you will need an adapter cable, such as one from B17 to B23.

4.4 EtherCAT input and downstream connection



4.4.1 Connection

For the incoming and continuing EtherCAT connection the box has two 9-pin B17 connectors, each with

- 4-pin trapezoidal EtherCAT core
- 5-pin power supply unit

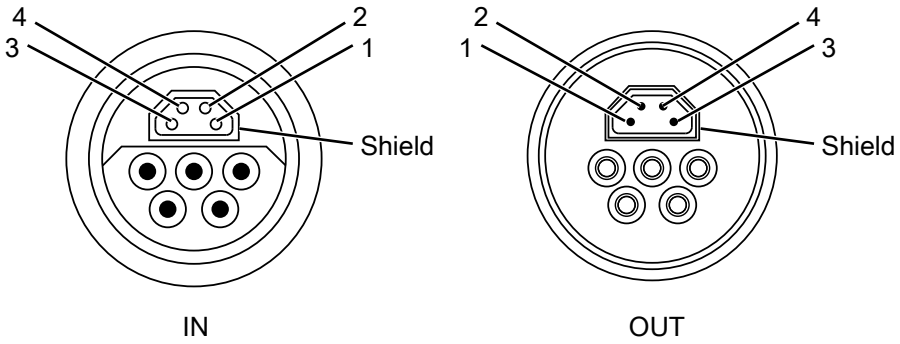


Fig. 4: EtherCAT pin assignment

Pin	Voltage/signal	Core colors [1]
1	Tx+	yellow
2	Rx+	white
3	Rx-	blue
4	Tx-	orange
Shroud	Shield	Cable shield

[1] The core colors apply to cables, connectors and flanges of the type

- Beckhoff ZB7203-xxxx
- Beckhoff ZK7208-xxxx

4.4.2 Status LEDs



Fig. 5: EtherCAT LEDs

L/A (Link/Act)

A green LED labeled "L/A" or "Link/Act" is located next to each EtherCAT/EtherCAT P socket. The LED indicates the communication state of the respective socket:

LED	Meaning
off	no connection to the connected EtherCAT device
lit	LINK: connection to the connected EtherCAT device
flashes	ACT: communication with the connected EtherCAT device

Run

Each EtherCAT slave and each EtherCAT P slave has a green LED labeled "Run". The LED signals the status of the slave in the EtherCAT network:

LED	Meaning
off	Slave is in "Init" state
flashes uniformly	Slave is in "Pre-Operational“ state
flashes sporadically	Slave is in "Safe-Operational" state
lit	Slave is in "Operational" state

4.5 EtherCAT P

NOTICE

Defect possible due to parallel connection.

- Do not connect EtherCAT P outputs in parallel.

EP9224-0037 converts the incoming EtherCAT signal into an EtherCAT P signal by combining the EtherCAT signal with the applied supply voltages. The EtherCAT P signal is available at four output ports: X52, X53, X54, X55.

Electrical isolation

The grounds of the control voltage (GND_S) and peripheral voltage (GND_P) are electrically isolated from each other in order to ensure the electrical isolation of the peripheral devices on U_P from the control voltage.

4.5.1 Connection

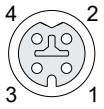


Fig. 6: M8 socket, p-coded

Contact	Signal	Voltage	Core color [1)]
1	Tx +	GND_S	yellow
2	Rx +	GND_P	white
3	Rx -	U_P: peripheral voltage, +24 V DC	blue
4	Tx -	U_S: control voltage, +24 V DC	orange
Housing	Shield	Shield	Shield

[1)] The core colors apply to EtherCAT P cables and ECP cables from Beckhoff.

4.5.2 Status LEDs

The status of an EtherCAT P port is signaled by two LEDs:



Fig. 7: LEDs of EtherCAT P ports (example: X54)

(1) EtherCAT Link/Activity (L/A)

The L/A LEDs of EtherCAT P ports behave like the L/A LEDs of the EtherCAT ports. See chapter Status LEDs [▶ 27] of the EtherCAT ports.

(2) Output voltage status

Each EtherCAT P port is assigned an LED that signals the states of the output voltages of this port.

LED signal	Meaning
Off	The output voltages U_S and U_P are switched off.
Lights up green	At least one of the output voltages (U_S, U_P) is switched on. The output currents are within the nominal operating range. ($I < I_n$)
Flashing green	Warning message [▶ 41]. Overcurrent on at least one of the output voltages.
Flashes red	Error message [▶ 41]. This signal is output in two cases: • At least one of the output voltages has been switched off within the last 20 seconds due to a protective function. • The box has been switched on within the last 20 seconds. Prior to switching on there was an error message that had not yet been reset.
Lights up red	Error message [▶ 41]. At least one of the output voltages has been switched off due to a protective function.
Chaser light red (all four status LEDs)	Error message [▶ 41]. Undervoltage or overtemperature.

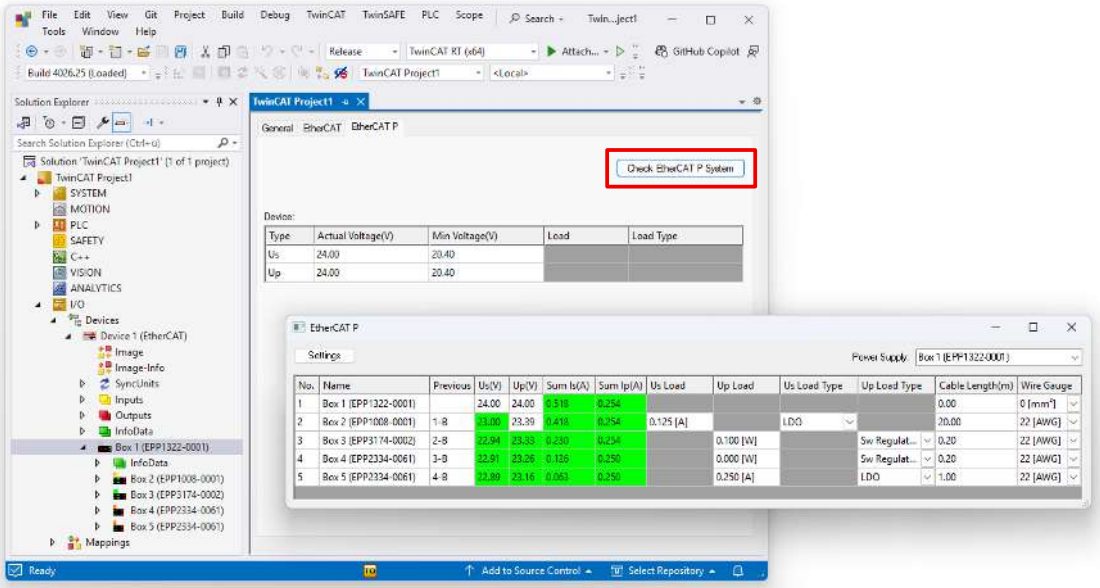
4.5.3 Conductor losses

When planning a system, take into account the voltage drop across the EtherCAT P cables. Make sure that the supply voltages at any EtherCAT P input do not fall below the minimum rated voltage.

Power supply unit voltage fluctuations must also be taken into account.

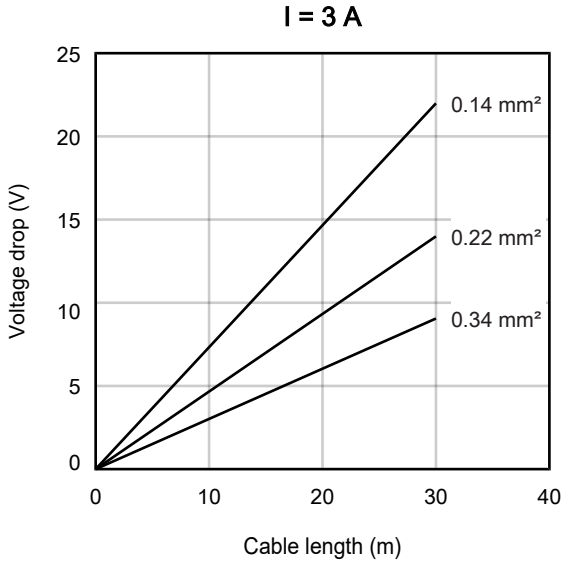
Planning tool for EtherCAT P

You can plan cable lengths, voltages and currents of your EtherCAT P system using TwinCAT 3. The requirement for this is TwinCAT 3 Build 4020 or higher.



Further information can be found in the quick start guide IO configuration in TwinCAT in chapter "Configuration of EtherCAT P via TwinCAT".

Voltage drop across an EtherCAT P cable



4.6 Disposal



Products marked with a crossed-out wheeled bin shall not be discarded with the normal waste stream. The device is considered as waste electrical and electronic equipment. The national regulations for the disposal of waste electrical and electronic equipment must be observed.

5 Commissioning and configuration

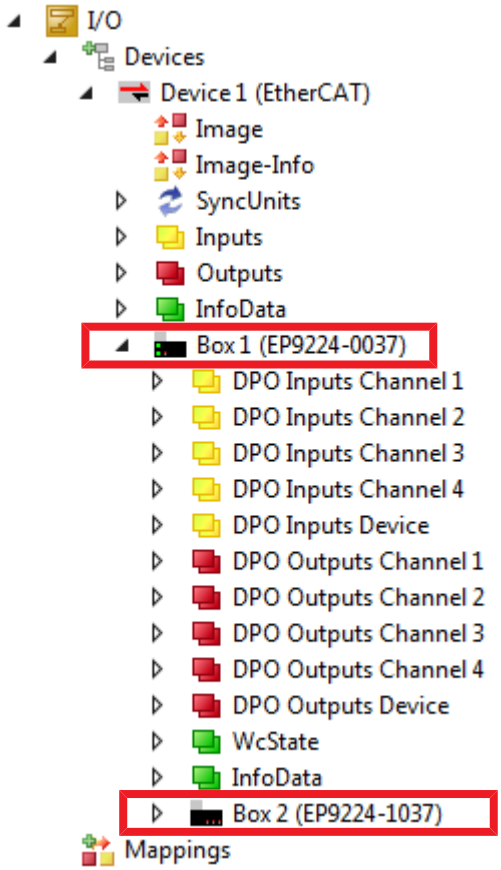
5.1 Integration in TwinCAT

The procedure for integration in a TwinCAT project is described in these Quick start guide.

5.1.1 Assignment of the connections

This chapter describes the assignment of the EP9224-0037 connectors to their representation in TwinCAT. This assignment is required to correctly map an EtherCAT network in TwinCAT "offline" configuration.

An EP9224-0037 is represented by two I/O modules in the TwinCAT I/O tree:



Each I/O module has four ports. Some ports represent connectors, while others represent internal interfaces. The following illustration shows the assignment of the connectors to the ports of the I/O modules in TwinCAT:



X52
X53
X54
X55
X70
X71

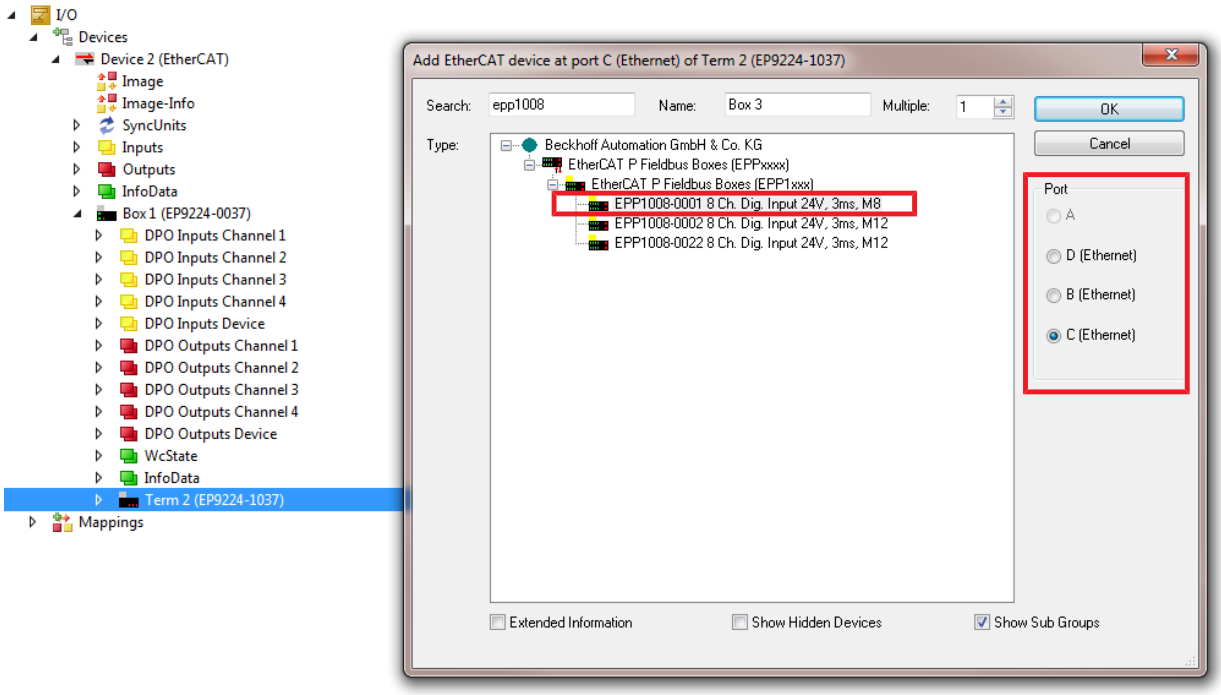
Type	EP9224-0037	TwinCAT	
	Connector	I/O module	Port
EtherCAT P output	X52	EP9224-1037	D
EtherCAT P output	X53		B
EtherCAT P output	X54		C
EtherCAT P output	X55	EP9224-0037	B
EtherCAT input	X70		A
EtherCAT output	X71		C

The following page contains examples of how to use the table.

Example: Appending an EtherCAT P Box to EP9224-0037

✓ Requirement: an EP9224-0037 is appended in the IO tree in TwinCAT.

1. Decide which connector of the EP9224-0037 to connect the EtherCAT P Box to.
   (e.g. to X54)
2. Determine the corresponding IO module and port with the help of the table.
   (e.g. EP9224-1037, Port C)
3. Right-click on the IO module determined in the IO tree.
   (e.g. EP9224-1037)
4. Click on the menu item **Add new Item…**
5. In the window that appears, select the EtherCAT P Box to be appended and the port determined.
   (e.g. EPP1008-0001, Port C)



6. Click **OK**

⇨ Result: The box was appended in the correct place in the IO tree.

Example: Connect an already appended EtherCAT P Box to a different connector

1. Double-click on the EtherCAT P Box in the IO tree.
   (e.g. an EPP1008-0001 that was previously connected to X54)
2. Click on the **EtherCAT** tab.
3. Determine the corresponding IO module and port of the new connector with the help of the table.
   (e.g. X55 → EP9224-0037, Port B)
4. Select the determined IO module and port in the drop-down list **Previous Port**.
   (e.g. "Box 1 (EP9224-0037) – B")

⇨ Result: The EtherCAT P Box is connected to the new connector.

Checking the IO configuration graphically

1. Double-click the EtherCAT master device in the IO tree.
2. Click the **EtherCAT** tab.
3. Click the **Topology** button.

⇨ Result: A graphical illustration of the network structure created in TwinCAT appears.
Move the mouse pointer over the icons of the IO modules to display their description.

5.2 Protective functions

Protective functions protect against overload and malfunctions by switching off output voltages of EtherCAT P ports in case of error.

They signal warnings and errors: Warning and error messages [▶ 41].

Resetting an error state

If a protective function has signaled an error, you must reset the error state so that the switched-off supply voltages can be switched on again:

1. Eliminate the cause of the error.
2. Apply a positive edge to the output variable:
   "DPO Outputs Device" > "Global Reset".

Note: The designation "Reset" refers only to the error state. Parameters and settings remain unchanged.

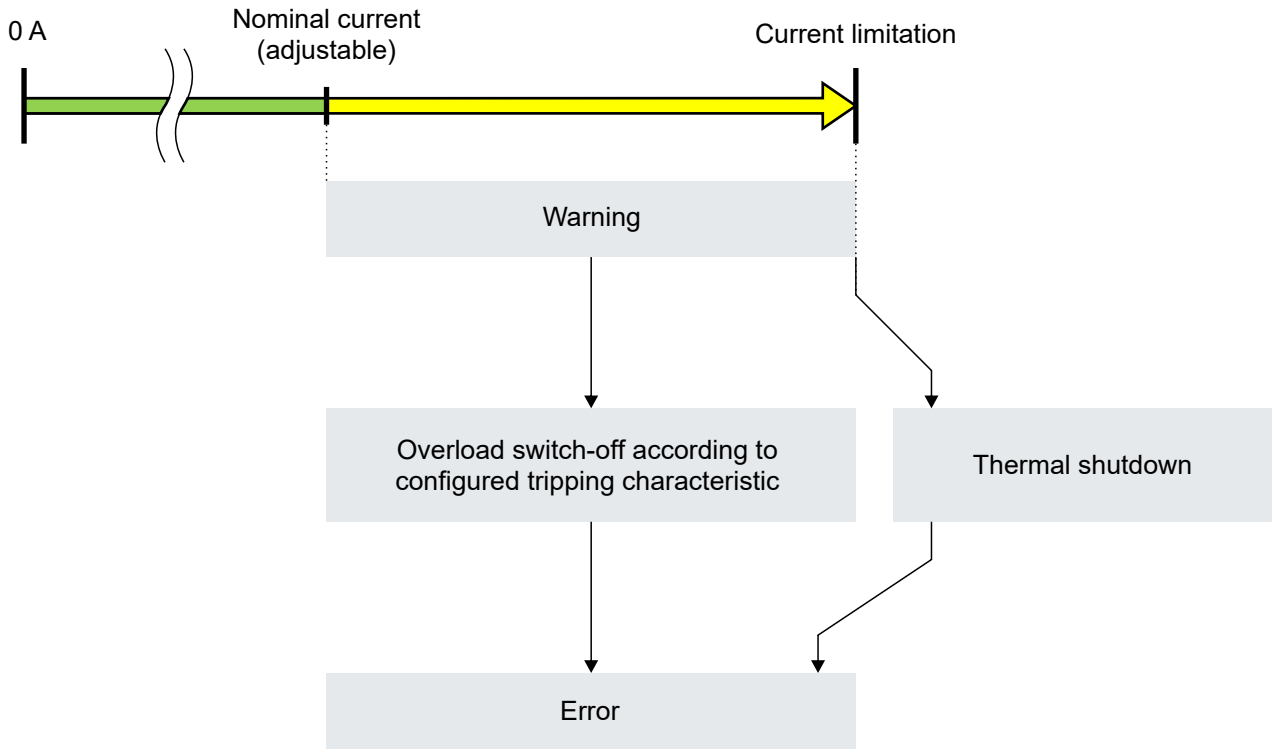
Further information can be found in the sections "Resetting an error state" in the chapter for the individual protective functions.

5.2.1 Overload protection

Each EtherCAT P port has overload protection for the output voltages U_S and U_P. If an output voltage is switched off due to overload, all other output voltages remain switched on.

The overload protection comprises two protection mechanisms:

- Overload switch-off, configurable
- Current limitation, not configurable



	From hardware 04	Up to hardware 03
Rated current (default)	3.0 A	3.0 A
Current limitation	3.3 A	5.0 A
Thermal switch-off time	typ. 160 ms	typ. 75 ms

Above the set nominal current, the status bit "Warning" is set. In this range, the protection mechanisms are active as follows:

- Only the overload switch-off is active between the nominal current and the current limit. It switches off the respective output voltage according to the configured tripping characteristic.
  See chapter Configure overload switch-off [▶ 37].
- The current limitation prevents the output current from exceeding a certain value.
  It switches off the output voltage thermally if the output current has to be limited for too long. The switch-off time depends on the ambient conditions.

You can use the data logger to determine which of the two protection mechanisms has switched off an output voltage. See chapter Troubleshooting with the data logger [▶ 44].

Overload message

If the overload protection has switched off an output voltage, this is reported as follows:

- The status bit "Error Us" or "Error Up" of the port is set.
- The output voltage status LED of the port lights up red.

Resetting an error state

If an output voltage has been switched off by the overload protection, it can be enabled again by one of the following actions:

- a positive edge on the output variable "DPO Inputs Channel n" > "Reset Ux" of the respective EtherCAT P port
- a positive edge on the output variable "DPO Outputs Device" > "Global Reset"

This also resets the status bit "Error".

5.2.1.1 Configure overload switch-off

You can configure the overload switch-off for each output voltage individually.

The configuration of the overload switch-off is similar to the selection of a fuse: you select the rated current and the tripping characteristic.

The rated current can be set between 1000 and 3000 mA.

Port	Rated current in mA	Tripping characteristic
X52	8000:12 „Nominal Current Us“ 8000:13 „Nominal Current Up“	8000:11 „Characteristic“
X53	8010:12 „Nominal Current Us“ 8010:13 „Nominal Current Up“	8010:11 „Characteristic“
X54	8020:12 „Nominal Current Us“ 8020:13 „Nominal Current Up“	8020:11 „Characteristic“
X55	8030:12 „Nominal Current Us“ 8030:13 „Nominal Current Up“	8030:11 „Characteristic“

If the rated current is exceeded, the status bit "Warning" is set.

Examples of the switch-off time

The following table shows the maximum switch-off time of the overload switch-off for different currents and tripping characteristics.

Shorter switch-off time with current limitation

The switch-off times shown only apply to output currents below the current limit.

If the output current is so high that the current limitation becomes active, the shutdown takes place after the thermal switch-off time. The thermal switch-off time cannot be configured and is usually shorter than the configured switch-off time.

From Firmware 20

% of the nominal current	Very fast acting	Fast acting	Slow acting	Time delay
105 %	3600 s	3600 s	3600 s	3600 s
135 %	420 s	3600 s	3600 s	3600 s
200 %	0.5 s	20 s	20 s	100 s
300 %	0.02 s	0.1 s	1 s	3 s

Up to firmware 03

Nominal current	Very fast acting	Fast acting	Slow acting	Time delay
100 %	1 h	-	-	-
110 %	1 h	4 h	-	-
120 %	7 min	4 h	-	-
150 %	30 s	30 min	1 h	4 h
210 %	500 ms	20 s	20 s	100 s
275 %	500 ms	1 s	20 s	10 s
300 %	20 ms	100 ms	1 s	3 s

5.2.2 Overcurrent protection for sum currents

EP9224-0037 determines two types of sum currents:

- Sum current for each individual EtherCAT P port (calculated)
  $U_S + U_P$
- Sum current for all EtherCAT P ports (measured)
  $\sum (U_S + U_P)$

The overcurrent protection for sum currents is disabled in the factory settings. It can be individually activated and parameterized for each sum current:

Sum current	CoE indices		
	Activation "Enable Sum Current Limitation"	Nominal current "Nominal Sum Current"	Tripping characteristic "Sum Current Characteristic"
X52: $U_S + U_P$	8000:04	8000:14	8000:11
X53: $U_S + U_P$	8010:04	8010:14	8010:11
X54: $U_S + U_P$	8020:04	8020:14	8020:11
X55: $U_S + U_P$	8030:04	8030:14	8030:11
$\sum (U_S + U_P)$ (Sum of all output currents)	F80E:02	F80E:12	F80E:13

5.2.3 Undervoltage protection

The undervoltage protection prevents connected EtherCAT P devices from being operated with a supply voltage that is too low. A malfunction of the EtherCAT P devices due to undervoltage is thus impossible.

Threshold values

The undervoltage protection has two threshold values, see chapter Technical data [▶ 11]:

- U_{warn}: If a supply voltage U_S or U_P falls below the upper threshold value U_{warn}, the bit "Warning Us" or "Warning Up" in the process data object "DPO Inputs Device" is set.
- U_{err}: If a supply voltage falls below the lower threshold value U_{err}, all outputs are switched off and the bit "Error Us" or "Error Up" in the process data object "DPO Inputs Device" is set.

The threshold values of the undervoltage protection cannot be adjusted.

Disabling for U_p

You can disable the undervoltage protection for the peripheral voltage U_P by setting the CoE parameter F80E:05 "Disable Up Undervoltage Error" to TRUE. That is useful in applications in which U_P is not needed. In such applications U_P would otherwise only have to be connected so as not to trigger the undervoltage protection.

Resetting an error state

If the output voltages have been switched off by the undervoltage protection, they can be re-activated in two ways:

- a positive edge on the output variable „DPO Inputs Device“ > „Global Reset“.
- A voltage reset of U_S

Requirement: Both supply voltages are higher at this point in time than the upper threshold value U_{warn}.

5.2.4 Overtemperature protection

The overtemperature protection monitors the internal temperature.

It has two threshold values, see chapter Technical data [▶ 11]:

- T_{warn}: If the internal temperature exceeds T_{warn}, the bit "Warning Temperature" in the process data object "DPO Inputs Device" is set.
- T_{err}: If the internal temperature exceeds T_{err}, all output voltages are switched off and the bit "Error Temperature" in the process data object "DPO Inputs Device" is set.

Resetting an error state

1. Allow the box to cool down until the internal temperature has fallen below T_{warn}.
2. Apply a positive edge on the output variable “DPO Outputs Device” > “Global Reset”.

⇨ The error message is reset.

⇨ All output voltages are switched on again, provided no other protective function prevents this.

5.2.5 Warning and error messages

Protective functions output warning and error messages.

Warning messages are temporary. They indicate that a measured variable lies outside of the nominal operating range. The warning message is canceled if the measured variable returns to within the nominal operating range.

Error messages are persistent. They persist until they are actively reset: Resetting an error state [▶ 35].
They also persist after a voltage reset (U_S).
A protective function signals through an error message that it has switched off at least one output voltage.

Warning messages and error messages are signaled in two ways:

- Status LEDs [▶ 29]
- Status bits in the process data

Use the Status bits to narrow down the cause of warnings or errors.

Status bits for group errors

- "Global Error Bit"
  (input variable "DPO Inputs Device" > "Device Status").
  This status bit is set with every error message. If it is not set, there is no error message from any protective function.
- "Channel Error"
  (input variables "DPO Inputs Channel n" > "Status").
  These status bits are set with every error message that concerns the respective EtherCAT P port.

Global Status bits

Input variable: "DPO Inputs Device" > "Device Status":

Status bit	Responsible protective function
Warning Temperature	Overtemperature protection [▶ 40]
Error Temperature	
Warning Us	Undervoltage protection [▶ 40]
Error Us	
Warning Up	
Error Up	
Warning Sum Current	Overcurrent protection for sum currents [▶ 39]
Error Sum Current	

Status bits per output

Input variable: "DPO Inputs Channel n" > "Status"
(n = 0 for X52, n = 1 for X53, n = 2 for X54, n = 3 for X55)

Status bit	Responsible protective function
Error Us	Overcurrent protection
Error Up	
Warning Us	
Warning Up	
Error Sum Current	Overcurrent protection for sum currents [▶ 39]
Warning Sum Current	

5.3 Diagnostic functions

5.3.1 Data logger

The data logger enables the recording of measured values. The recording can be used for the analysis of errors. See also Chapter Troubleshooting with the data logger [▶ 44].

Once the recording has been started, it saves all measured values continuously in a ring buffer. The recording stops automatically if a protective function signals an error. With the recorded measured values you can trace the events that led to the error.

Activate control

You have to activate additional process data objects in the process image in order to be able to use the data logger:

- PDO 0x1610 (Sync Manager SM2 "Outputs")
- PDO 0x1A10 (Sync Manager SM3 "Inputs")

Proceed as follows:

✓ Requirement: an EP9224-0037 is appended in the I/O tree in TwinCAT.

1. Double-click on the EP9224-0037 I/O module in the I/O tree.
2. Click the **Process Data** tab.
3. Click "Outputs" in the "**Sync Manager**" box.
4. Activate the **PDO Assignment (0x1C12)** checkbox next to the entry "0x1610".
   ⇨ The process data object "LOG Control" appears in the I/O tree.
5. Click "Inputs" in the **Sync Manager** box.
6. Activate the **PDO Assignment (0x1C13)** checkbox next to the entry "0x1A10".
   ⇨ The process data object "LOG Status" appears in the I/O tree.

⇨ Result: The process data objects for controlling the data logger are activated.

Parameterization

The sampling rate for the recording can be selected in the index 8040:11 "Sampling Rate".

Start recording

The output variable "Start Logger" is located in the process data object "LOG Control". The recording is started by a positive edge on this output variable.

If the recording is running, the Status bit
"LOG Status" > "Status" > "Logger Running"
is set.

Stop recording

The recording stops in two cases:

- if a protective function signals an error.
- upon a positive edge on the output variable
  "LOG Control" > "Control" > "Stop Logger".

If the recording has stopped, the input variable
"LOG Status" > "Status" > "Logger Running"
has the value "0".

Evaluate recorded measured values

The recorded measured values are available as a .csv file. The file must be uploaded from the box to the control computer in order to be able to evaluate it.

Proceed as follows to upload the recorded measured values to the control computer:

1. Double-click on the EP9224-0037 I/O module in the I/O tree.
2. Click the "**Online**" tab.
3. Click the **Upload** button.
   ⇨ A dialog box with the title "Save As" appears.
4. Select a directory and write in the field **File Name**:
   "logdata.csv"
5. Click the **Save** button.
   ⇨ A dialog box appears with the title "Edit FoE Name".
6. Click the **OK** button.

⇨ The file with the measured values was uploaded to the control computer.

File format

The file with the measured values begins with a header „`**** Logfile from Ethercat Slave ****`".

Below this follows:

- a file header
- a measured value table

Format of the file header:

Field	Description
Device Name	Name of the module
File Version	Version number (Note: when importing from EXCEL the version, e.g. 1.5, is interpreted/displayed as a date (1st May))
Reason for which the snapshot was taken	Reason for stopping the data logger
Age of snapshot	time elapsed from stopping the data logger until the upload
System timestamp (0 if DC not supported)	current timestamp when uploading

Format of the measured value table:

Type	Description
Time offset additional to snapshot age	The age of the measured values in the row in relation to the stopping of the data logger (0 = stop, > 0 older values) in ms
I(U...)	present current values of the channels Us / Up 1 - 4 in 100 mA
Internal Temperature	internal module temperature in °C
Us / Up	Input voltage Us and Up at the 7/8" input in V
Sum Current Us / Up	Sum current of Us and Up in A
I^2t(U...)	virtual overload, incremented or decremented depending on the nominal current • from 10% warning • at 100% shut-off

5.3.1.1 Troubleshooting with the data logger

You can use the data logger to determine the cause of an error, among other things. The prerequisite for this is that the recording of the measured values is already enabled when the error occurs.

Determine the cause of the error

The data logger stops recording the measured values if an error occurs, among other things. The reason for the last stop of the recording is output in the process data and via a CoE parameter:

- PDO "Log Status" > "Trigger Reason"
- CoE parameter 6040:12 "Trigger Reason"

Possible values:

Value	Enum text	Reason for stopping the recording
0	Undefined	Unknown.
1	Undervoltage Us	Undervoltage of U_S at voltage input X70 "IN".
2	Undervoltage Up	Undervoltage of U_P at voltage input X70 "IN".
3	Overtemperature	Internal temperature too high.
4	Overcurrent	The overload switch-off of an EtherCAT P port has switched off an output voltage.
5	FoE Transfer	The data upload was started before the recording was stopped.
6	Hardware Protection	The starting current limitation of an EtherCAT P port has switched off an output voltage.
7	User Stop Bit	Set the bit "Stop Logger" in the process data.
255	Logger still running	N/A. The recording has not yet been stopped.

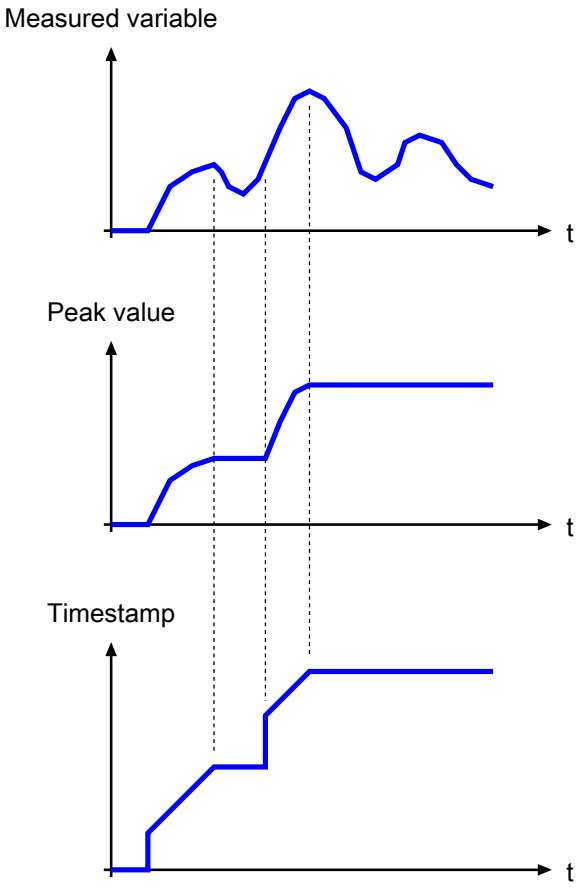
5.3.2 Peak value detector

The peak value detector detects two types of event:

- Occurrence of an extreme value of a measured variable (output current, supply voltage, temperature).
- Output of a warning message or error message.

The value of the maximum extreme value and the time of occurrence in input variables are available at all times.

The following diagrams illustrate the mode of operation of the peak value detector taking the example of the maximum of a measured variable:



Activate peak value detector

You have to activate additional process data objects in the process image in order to be able to use the peak value detector:

Scope	Process data objects for control		Process data objects for evaluation	
	Index (Sync Manager SM2)	Name	Index (Sync Manager SM3)	Name
EtherCAT P port X52	0x1601	DPO Extended Diag Outputs Channel 1	0x1A01	DPO Extended Diag Inputs Channel 1
EtherCAT P port X53	0x1603	DPO Extended Diag Outputs Channel 2	0x1A03	DPO Extended Diag Inputs Channel 2
EtherCAT P port X54	0x1605	DPO Extended Diag Outputs Channel 3	0x1A05	DPO Extended Diag Inputs Channel 3
EtherCAT P port X55	0x1607	DPO Extended Diag Outputs Channel 4	0x1A07	DPO Extended Diag Inputs Channel 4
Global	0x1609	DPO Extended Diag Outputs Device	0x1A09	DPO Extended Diag Inputs Device

Proceed as follows:

1. Double-click on the EP9224-0037 I/O module in the I/O tree.
2. Click the **Process Data** tab.
3. Click "Outputs" in the "**Sync Manager**" box.
4. Activate the **PDO Assignment (0x1C12)** checkbox next to the desired PDOs.
   ⇨ The corresponding process data object "DPO Extended Diag Outputs […]" appears in the I/O tree.
5. Click "Inputs" in the **Sync Manager** box.
6. Activate the **PDO Assignment (0x1C13)** checkbox next to the desired PDOs.
   ⇨ The corresponding process data object "DPO Extended Diag Inputs […]" appears in the I/O tree.

⇨ Result: The process data objects for controlling and evaluating the peak value detector are activated.

Select measured variables/messages

You can select ten measured variables or messages for which events are to be detected:

- Two measured variables or messages per EtherCAT P port.
- Two global measured variables or messages that concern the complete box (temperatures, supply voltages, sum currents).

The following table shows the CoE indices in which the measured variables or messages can be selected:

Scope	Input variables	CoE Index
EtherCAT P port X52	"DPO Extended Diag Inputs Channel 1" > "Peak Value 1" > "Timestamp 1"	8000:15
	"DPO Extended Diag Inputs Channel 1" > "Peak Value 2" > "Timestamp 2"	8000:16
EtherCAT P port X53	"DPO Extended Diag Inputs Channel 2" > "Peak Value 1" > "Timestamp 1"	8010:15
	"DPO Extended Diag Inputs Channel 2" > "Peak Value 2" > "Timestamp 2"	8010:16
EtherCAT P port X54	"DPO Extended Diag Inputs Channel 3" > "Peak Value 1" > "Timestamp 1"	8020:15
	"DPO Extended Diag Inputs Channel 3" > "Peak Value 2" > "Timestamp 2"	8020:16
EtherCAT P port X55	"DPO Extended Diag Inputs Channel 4" > "Peak Value 1" > "Timestamp 1"	8030:15
	"DPO Extended Diag Inputs Channel 4" > "Peak Value 2" > "Timestamp 2"	8030:16
Global	"DPO Extended Diag Inputs Device" > "Peak Value 1" > "Timestamp 1"	F80E:15
	"DPO Extended Diag Inputs Device" > "Peak Value 2" > "Timestamp 2"	F80E:16

Reset

Resetting the peak value detector leads to the current measured value and the current timestamp being adopted as the new peak value and new timestamp.

You can reset the peak value detector for each port and for the global peak values individually.

To do this, apply a positive edge to the respective output variable "Reset Extended Diag Data".

Evaluation

The peak values and timestamp can be found in the process data objects "DPO Extended Diag Inputs" as input variables:

- "Peak Value 1" and the associate "Timestamp 1"
- "Peak Value 2" and the associate "Timestamp 2"

5.4 Switch output voltages

You can switch the output voltages U_S and U_P of each EtherCAT P port individually.

Protective functions [▶ 35] can prevent an output voltage from being switched on.

A switched-on output voltage is signaled in two ways:

- Status LEDs [▶ 29].
- Status bits in the process data:
  "DPO Inputs Channel n" > "Status" > "Status Us"
  "DPO Inputs Channel n" > "Status" > "Status Up"
  (where: n = 0 for X52, n = 1 for X53, n = 2 for X54, n = 3 for X55)

The output variable "DPO Outputs Device" > "Enable Control Via Fieldbus" defines whether the output voltages are switched manually or automatically:

- "0": automatic (factory setting)
- "1": manual

Inadvertent switching of output voltages.

If you change the value of "Enable Control Via Fieldbus", it is possible that the output voltages may be switched on or off.
To prevent that, match the values of the CoE indices (automatic switching) and output variables (manual switching) mentioned below to each other before changing the value of "Enable Control Via Fieldbus".

Automatic switching

In the factory setting, all output voltages are switched on automatically when the supply voltage U_S is applied. You can activate or deactivate automatic switch-on for each output voltage individually.

The following table shows the correlation of the output voltages and the CoE indices that control the automatic switch-on.

EtherCAT P port	Output voltage	Parameter	
X52	U_S	8000:02	"DPO Settings Ch. 1" > "Default State Us"
	U_P	8000:03	"DPO Settings Ch. 1" > "Default State Up"
X53	U_S	8010:02	"DPO Settings Ch. 2" > "Default State Us"
	U_P	8010:03	"DPO Settings Ch. 2" > "Default State Up"
X54	U_S	8020:02	"DPO Settings Ch. 3" > "Default State Us"
	U_P	8020:03	"DPO Settings Ch. 3" > "Default State Up"
X55	U_S	8030:02	"DPO Settings Ch. 4" > "Default State Us"
	U_P	8030:03	"DPO Settings Ch. 4" > "Default State Up"

Value range:

- "1": U_S/U_P is switched on automatically when U_S is applied (factory setting).
- "0": U_S/U_P remains switched off when U_S is applied.

The output voltages are switched on with a time offset. The time offset prevents the input inrush currents of the connected EtherCAT P devices from adding up.
You can set the time offset in CoE index F80E:11 "Startup Delay":

- "0": "Fast"
- "1": "Moderate"
- "2": "Slow"

Manual switching

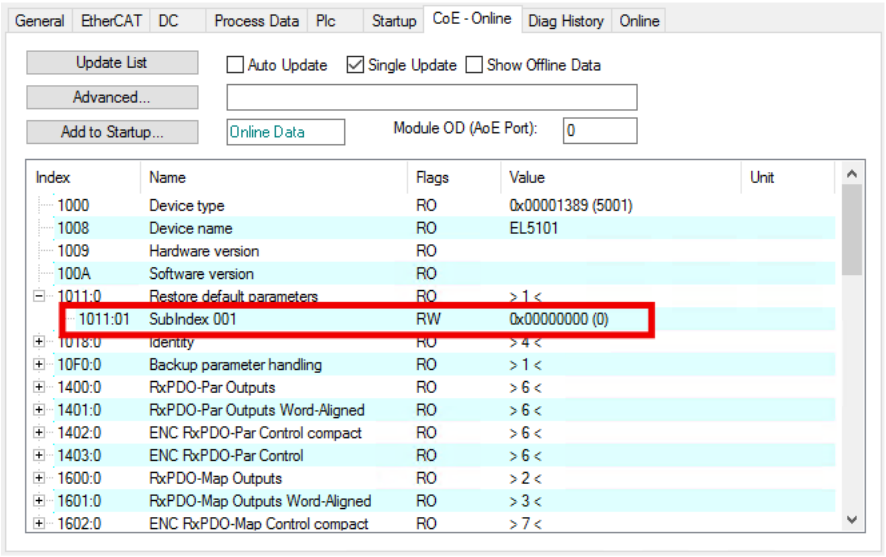
Set the variable "Enable Control Via Fieldbus" to "1" to switch output voltages manually via output variables.

EtherCAT P port	Output voltage	Output variable
X52	U_S	"DPO Outputs Channel 1" > "Output Us"
	U_P	"DPO Outputs Channel 1" > "Output Up"
X53	U_S	"DPO Outputs Channel 2" > "Output Us"
	U_P	"DPO Outputs Channel 2" > "Output Up"
X54	U_S	"DPO Outputs Channel 3" > "Output Us"
	U_P	"DPO Outputs Channel 3" > "Output Up"
X55	U_S	"DPO Outputs Channel 4" > "Output Us"
	U_P	"DPO Outputs Channel 4" > "Output Up"

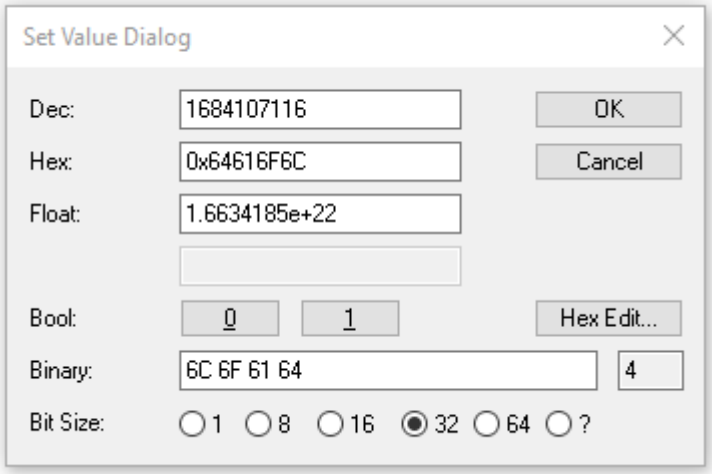
5.5 Restore the delivery state

You can restore the delivery state of the backup objects as follows:

1. Ensure that TwinCAT is running in Config mode.
2. In CoE object 1011:0 "Restore default parameters" select parameter 1011:01 "Subindex 001".



3. Double-click on "Subindex 001".
   ⇨ The "Set Value Dialog" dialog box opens.
4. Enter the value 1684107116 in the "Dec" field.
   Alternatively: enter the value 0x64616F6C in the "Hex" field.



5. Confirm with "OK".

⇨ All backup objects are reset to the delivery state.

Alternative restore value

With some older modules the backup objects can be changed with an alternative restore value:
Decimal value: 1819238756
Hexadecimal value: 0x6C6F6164

An incorrect entry for the restore value has no effect.

6 CoE parameters

Parameterization

You can parameterize the box via the "CoE - Online" tab in TwinCAT.

EtherCAT XML Device Description

The presentation matches that of the EtherCAT XML Device Description.
Recommendation: download the latest XML file from https://www.beckhoff.com and install it according to the installation instructions.

Index (hex)	Name
1000	Device type [▶ 59]
1008	Device name [▶ 59]
1009	Hardware version [▶ 59]
100A	Software version [▶ 59]
100B	Bootloader version [▶ 59]
1011	Restore default parameters [▶ 52]
1018	Identity [▶ 59]
10F0	Backup parameter handling [▶ 59]
1600	DPO RxPDO-Map Outputs Ch.1 [▶ 60]
1601	DPO RxPDO-Map Extended Diag Outputs Ch.1 [▶ 60]
1602	DPO RxPDO-Map Outputs Ch.2 [▶ 60]
1603	DPO RxPDO-Map Extended Diag Outputs Ch.2 [▶ 60]
1604	DPO RxPDO-Map Outputs Ch.3 [▶ 60]
1605	DPO RxPDO-Map Extended Diag Outputs Ch.3 [▶ 60]
1606	DPO RxPDO-Map Outputs Ch.4 [▶ 61]
1607	DPO RxPDO-Map Extended Diag Outputs Ch.4 [▶ 61]
1608	DPO RxPDO-Map Outputs Device [▶ 61]
1609	DPO RxPDO-Map Extended Diag Outputs Device [▶ 61]
1610	LOG RxPDO-Map Control [▶ 61]
1A00	DPO TxPDO-Map Inputs Ch.1 [▶ 62]
1A01	DPO TxPDO-Map Extended Diag Inputs Ch.1 [▶ 62]
1A02	DPO TxPDO-Map Inputs Ch.2 [▶ 62]
1A03	DPO TxPDO-Map Extended Diag Inputs Ch.2 [▶ 62]
1A04	DPO TxPDO-Map Inputs Ch.3 [▶ 63]
1A05	DPO TxPDO-Map Extended Diag Inputs Ch.3 [▶ 63]
1A06	DPO TxPDO-Map Inputs Ch.4 [▶ 63]
1A07	DPO TxPDO-Map Extended Diag Inputs Ch.4 [▶ 63]
1A08	DPO TxPDO-Map Inputs Device [▶ 64]
1A09	DPO TxPDO-Map Extended Diag Inputs Device [▶ 64]
1A10	LOG TxPDO-Map Status [▶ 64]
1C00	Sync manager type [▶ 64]
1C12	RxPDO assign [▶ 65]
1C13	TxPDO assign [▶ 65]
1C32	SM output parameter [▶ 66]
1C33	SM input parameter [▶ 67]
6000	DPO Inputs Ch.1 [▶ 69]
6010	DPO Inputs Ch.2 [▶ 69]
6020	DPO Inputs Ch.3 [▶ 70]
6030	DPO Inputs Ch.4 [▶ 70]
6040	LOG Status [▶ 70]

Index (hex)	Name
7000	DPO Outputs Ch.1 [▶ 71]
7010	DPO Outputs Ch.2 [▶ 71]
7020	DPO Outputs Ch.3 [▶ 71]
7030	DPO Outputs Ch.4 [▶ 71]
7040	LOG Control [▶ 71]
8000	DPO Settings Ch.1 [▶ 53]
800F	DPO Vendor Data Ch.1 [▶ 53]
8010	DPO Settings Ch.2 [▶ 55]
801F	DPO Vendor Data Ch.2 [▶ 54]
8020	DPO Settings Ch.3 [▶ 55]
802F	DPO Vendor Data Ch.3 [▶ 55]
8030	DPO Settings Ch.4 [▶ 56]
803F	DPO Vendor Data Ch.4 [▶ 56]
8040	LOG Settings [▶ 57]
F000	Modular Device Profile [▶ 67]
F008	Code word [▶ 67]
F010	Module Profile List [▶ 68]
F607	DPO Inputs Device [▶ 72]
F707	DPO Outputs Device [▶ 72]
F80E	DPO Settings Device [▶ 57]
F81F	DPO Vendor Data Device [▶ 58]

6.1 Objects for parameterization

Index 1011 Restore default parameters

Index (hex)	Name	Meaning	Data type	Flags	Default
1011:0	Restore default parameters	Restore default parameters	UINT8	RO	0x01 (1_{dec})
1011:01	SubIndex 001	If this object is set to "0x64616F6C" in the set value dialog, all backup objects are reset to their delivery state.	UINT32	RW	0x00000000 (0_{dec})

Index 8000 DPO Settings Ch.1

Index (hex)	Name	Meaning	Data type	Flags	Default
8000:0	DPO Settings Ch.1		UINT8	RO	0x16 (22_{dec})
8000:02	Default State Us	The output assumes this value if F707:01 "Enable Control Via Fieldbus" is not set. See chapter Switch output voltages [▶ 48].	BOOLEAN	RW	0x01 (1_{dec})
8000:03	Default State Up	The output assumes this value if F707:01 "Enable Control Via Fieldbus" is not set. See chapter Switch output voltages [▶ 48].	BOOLEAN	RW	0x01 (1_{dec})
8000:04	Enable Sum Current Limitation	Activates the overcurrent protection for the sum current Us+Up on this output. See chapter Overcurrent protection for sum currents [▶ 39].	BOOLEAN	RW	0x00 (0_{dec})
8000:11	Characteristic	Tripping characteristics of the overload switch-off: • 0: Very fast acting • 1: Fast acting • 2: Slow acting • 3: Time delay See chapter Overload protection [▶ 36].	UINT16	RW	0x0001 (1_{dec})
8000:12	Nominal Current Us	Nominal current for U_S. Unit: mA Value range: 1000 ... 3000_{dec} See chapter Overload protection [▶ 36].	UINT16	RW	0x0BB8 (3000_{dec})
8000:13	Nominal Current Up	Nominal current for U_P. Unit: mA Value range: 1000 ... 3000_{dec} See chapter Overload protection [▶ 36].	UINT16	RW	0x0BB8 (3000_{dec})
8000:14	Nominal Sum Current	Nominal maximum sum current (Us+Up) at the output. See chapter Overcurrent protection for sum currents [▶ 39].	UINT16	RW	0x1770 (6000_{dec})
8000:15	Timestamp 1 Trigger	Defines which events are detected by the peak value detector at this port. Possible values: • 0: Error Us • 1: Error Up • 2: Warning Us • 3: Warning Up • 7: Error Sum Current • 8: Warning Sum Current • 16: Minimum Current Us • 17: Maximum Current Us • 18: Minimum Current Up • 19: Maximum Current Up See chapter Peak value detector [▶ 45].	UINT16	RW	0x0000 (0_{dec})
8000:16	Timestamp 2 Trigger	See 8000:15.	UINT16	RW	0x0000 (0_{dec})

800F DPO Vendor Data Ch.1

Index (hex)	Name	Meaning	Data type	Flags	Default
800F:0	DPO Vendor Data Ch.1		USINT	RO	0x14 (20_{dec})
800F:11	GainS		UINT	RW	0x4000 (16384_{dec})
800F:12	OffsetS		INT	RW	0x0 (0_{dec})
800F:13	GainP		UINT	RW	0x4000 (16384_{dec})
800F:14	OffsetP		INT	RW	0x0 (0_{dec})

Index 8010 DPO Settings Ch.2

Index (hex)	Name	Meaning	Data type	Flags	Default
8010:0	DPO Settings Ch.2		UINT8	RO	0x16 (22_{dec})
8010:02	Default State Us	The output assumes this value if F707:01 "Enable Control Via Fieldbus" is not set. See chapter Switch output voltages [▶ 48].	BOOLEAN	RW	0x01 (1_{dec})
8010:03	Default State Up	The output assumes this value if F707:01 "Enable Control Via Fieldbus" is not set. See chapter Switch output voltages [▶ 48].	BOOLEAN	RW	0x01 (1_{dec})
8010:04	Enable Sum Current Limitation	Activates the overcurrent protection for the sum current Us+Up on this output. See chapter Overcurrent protection for sum currents [▶ 39].	BOOLEAN	RW	0x00 (0_{dec})
8010:11	Characteristic	Tripping characteristics of the overload switch-off: • 0: Very fast acting • 1: Fast acting • 2: Slow acting • 3: Time delay See chapter Overload protection [▶ 36].	UINT16	RW	0x0001 (1_{dec})
8010:12	Nominal Current Us	Nominal current for U_S. Unit: mA Value range: 1000 ... 3000_{dec} See chapter Overload protection [▶ 36].	UINT16	RW	0x0BB8 (3000_{dec})
8010:13	Nominal Current Up	Nominal current for U_P. Unit: mA Value range: 1000 ... 3000_{dec} See chapter Overload protection [▶ 36].	UINT16	RW	0x0BB8 (3000_{dec})
8010:14	Nominal Sum Current	Nominal maximum sum current (Us+Up) at the output. See chapter Overcurrent protection for sum currents [▶ 39].	UINT16	RW	0x1770 (6000_{dec})
8010:15	Timestamp 1 Trigger	Defines which events are detected by the peak value detector at this port. Possible values: • 0: Error Us • 1: Error Up • 2: Warning Us • 3: Warning Up • 7: Error Sum Current • 8: Warning Sum Current • 16: Minimum Current Us • 17: Maximum Current Us • 18: Minimum Current Up • 19: Maximum Current Up See chapter Peak value detector [▶ 45].	UINT16	RW	0x0000 (0_{dec})
8010:16	Timestamp 2 Trigger	See 8010:15.	UINT16	RW	0x0000 (0_{dec})

801F DPO Vendor Data Ch.2

Index (hex)	Name	Meaning	Data type	Flags	Default
801F:0	DPO Vendor Data Ch.2		USINT	RO	0x14 (20_{dec})
801F:11	GainS		UINT	RW	0x4000 (16384_{dec})
801F:12	OffsetS		INT	RW	0x0 (0_{dec})
801F:13	GainP		UINT	RW	0x4000 (16384_{dec})
801F:14	OffsetP		INT	RW	0x0 (0_{dec})

Index 8020 DPO Settings Ch.3

Index (hex)	Name	Meaning	Data type	Flags	Default
8020:0	DPO Settings Ch.3		UINT8	RO	0x16 (22_{dec})
8020:02	Default State Us	The output assumes this value if F707:01 "Enable Control Via Fieldbus" is not set. See chapter Switch output voltages [▶ 48].	BOOLEAN	RW	0x01 (1_{dec})
8020:03	Default State Up	The output assumes this value if F707:01 "Enable Control Via Fieldbus" is not set. See chapter Switch output voltages [▶ 48].	BOOLEAN	RW	0x01 (1_{dec})
8020:04	Enable Sum Current Limitation	Activates the overcurrent protection for the sum current Us+Up on this output. See chapter Overcurrent protection for sum currents [▶ 39].	BOOLEAN	RW	0x00 (0_{dec})
8020:11	Characteristic	Tripping characteristics of the overload switch-off: • 0: Very fast acting • 1: Fast acting • 2: Slow acting • 3: Time delay See chapter Overload protection [▶ 36].	UINT16	RW	0x0001 (1_{dec})
8020:12	Nominal Current Us	Nominal current for U_S. Unit: mA Value range: 1000 ... 3000_{dec} See chapter Overload protection [▶ 36].	UINT16	RW	0x0BB8 (3000_{dec})
8020:13	Nominal Current Up	Nominal current for U_P. Unit: mA Value range: 1000 ... 3000_{dec} See chapter Overload protection [▶ 36].	UINT16	RW	0x0BB8 (3000_{dec})
8020:14	Nominal Sum Current	Nominal maximum sum current (Us+Up) at the output. See chapter Overcurrent protection for sum currents [▶ 39].	UINT16	RW	0x1770 (6000_{dec})
8020:15	Timestamp 1 Trigger	Defines which events are detected by the peak value detector at this port. Possible values: • 0: Error Us • 1: Error Up • 2: Warning Us • 3: Warning Up • 7: Error Sum Current • 8: Warning Sum Current • 16: Minimum Current Us • 17: Maximum Current Us • 18: Minimum Current Up • 19: Maximum Current Up See chapter Peak value detector [▶ 45].	UINT16	RW	0x0000 (0_{dec})
8020:16	Timestamp 2 Trigger	See 8020:15	UINT16	RW	0x0000 (0_{dec})

802F DPO Vendor Data Ch.3

Index (hex)	Name	Meaning	Data type	Flags	Default
802F:0	DPO Vendor Data Ch.3		USINT	RO	0x14 (20_{dec})
802F:11	GainS		UINT	RW	0x4000 (16384_{dec})
802F:12	OffsetS		INT	RW	0x0 (0_{dec})
802F:13	GainP		UINT	RW	0x4000 (16384_{dec})
802F:14	OffsetP		INT	RW	0x0 (0_{dec})

Index 8030 DPO Settings Ch.4

Index (hex)	Name	Meaning	Data type	Flags	Default
8030:0	DPO Settings Ch.4		UINT8	RO	0x16 (22_{dec})
8030:02	Default State Us	The output assumes this value if F707:01 "Enable Control Via Fieldbus" is not set. See chapter Switch output voltages [▶ 48].	BOOLEAN	RW	0x01 (1_{dec})
8030:03	Default State Up	The output assumes this value if F707:01 "Enable Control Via Fieldbus" is not set. See chapter Switch output voltages [▶ 48].	BOOLEAN	RW	0x01 (1_{dec})
8030:04	Enable Sum Current Limitation	Activates the overcurrent protection for the sum current Us+Up on this output. See chapter Overcurrent protection for sum currents [▶ 39].	BOOLEAN	RW	0x00 (0_{dec})
8030:11	Characteristic	Tripping characteristics of the overload switch-off: • 0: Very fast acting • 1: Fast acting • 2: Slow acting • 3: Time delay See chapter Overload protection [▶ 36].	UINT16	RW	0x0001 (1_{dec})
8030:12	Nominal Current Us	Nominal current for U_S. Unit: mA Value range: 1000 ... 3000_{dec} See chapter Overload protection [▶ 36].	UINT16	RW	0x0BB8 (3000_{dec})
8030:13	Nominal Current Up	Nominal current for U_P. Unit: mA Value range: 1000 ... 3000_{dec} See chapter Overload protection [▶ 36].	UINT16	RW	0x0BB8 (3000_{dec})
8030:14	Nominal Sum Current	Nominal maximum sum current (Us+Up) at the output. See chapter Overcurrent protection for sum currents [▶ 39].	UINT16	RW	0x1770 (6000_{dec})
8030:15	Timestamp 1 Trigger	Defines which events are detected by the peak value detector at this port. Possible values: • 0: Error Us • 1: Error Up • 2: Warning Us • 3: Warning Up • 7: Error Sum Current • 8: Warning Sum Current • 16: Minimum Current Us • 17: Maximum Current Us • 18: Minimum Current Up • 19: Maximum Current Up See chapter Peak value detector [▶ 45].	UINT16	RW	0x0000 (0_{dec})
8030:16	Timestamp 2 Trigger	See 8030:15	UINT16	RW	0x0000 (0_{dec})

803F DPO Vendor Data Ch.4

Index (hex)	Name	Meaning	Data type	Flags	Default
803F:0	DPO Vendor Data Ch.4		USINT	RO	0x14 (20_{dec})
803F:11	GainS		UINT	RW	0x4000 (16384_{dec})
803F:12	OffsetS		INT	RW	0x0 (0_{dec})
803F:13	GainP		UINT	RW	0x4000 (16384_{dec})
803F:14	OffsetP		INT	RW	0x0 (0_{dec})

Index 8040 LOG Settings

Index (hex)	Name	Meaning	Data type	Flags	Default
8040:0	LOG Settings		UINT8	RO	0x11 (17_{dec})
8040:11	Sampling Rate	Sampling rate of the data logger • 1: 1 ms • 10: 10 ms • 25: 25 ms • 100: 100 ms • 1000: 1000 ms See chapter Data logger [▶ 42].	UINT16	RW	0x000A (10_{dec})

Index F80E DPO Settings Device

Index (hex)	Name	Meaning	Data type	Flags	Default
F80E:0	DPO Settings Device		UINT8	RO	0x16 (22_{dec})
F80E:02	Enable Sum Current Limitation	Enables the overcurrent protection for the sum current $\sum U_S + \sum U_P$.	BOOLEAN	RW	0x00 (0_{dec})
F80E:05	Disable Up Undervoltage Error	Disables the undervoltage protection for the peripheral voltage U_P.	BOOLEAN	RW	0x00 (0_{dec})
F80E:11	Startup Delay	Sets the time that is kept between two switch-on procedures: • 0: Fast (10 ms) • 1: Moderate (100 ms) • 2: Slow (200 ms)	UINT16	RW	0x0001 (1_{dec})
F80E:12	Nominal Sum Current	Nominal maximum current for the sum current.	INT16	RW	0x5DC0 (24000_{dec})
F80E:13	Sum Current Characteristic	Specifies the characteristic with which the current monitoring reacts: • 0: Very fast acting • 1: Fast acting • 2: Slow acting • 3: Time delay	UINT16	RW	0x0001 (1_{dec})
F80E:15	Timestamp 1 Trigger	Defines which events are detected by the peak value detector. Possible values: • 0: Temperature Warning • 1: Temperature Error • 2: Us Warning • 3: Us Error • 4: Up Warning • 5: Up Error • 7: Sum Current Warning • 8: Sum Current Error • 16: Minimum Current Us • 17: Maximum Current Us • 18: Minimum Current Up • 19: Maximum Current Up • 20: Minimum Voltage Us • 21: Maximum Voltage Us • 22: Minimum Voltage Up • 23: Maximum Voltage Up • 24: Minimum Temperature • 25: Maximum Temperature See chapter Peak value detector [▶ 45].	UINT16	RW	0x0000 (0_{dec})
F80E:16	Timestamp 2 Trigger	See F80E:15.	UINT16	RW	0x0000 (0_{dec})

F81F DPO Vendor Data Device

Index (hex)	Name	Meaning	Data type	Flags	Default
F81F:0	DPO Vendor Data Device		USINT	RO	0x1a (26_{dec})
F81F:10	Enable Calibration Mode		BOOL	RW	00
F81F:11	GainS		UINT	RW	0x4000 (16384_{dec})
F81F:12	OffsetS		INT	RW	0x0 (0_{dec})
F81F:13	GainP		UINT	RW	0x4000 (16384_{dec})
F81F:14	OffsetP		INT	RW	0x0 (0_{dec})
F81F:15	Gain US		UINT	RW	0x4000 (16384_{dec})
F81F:16	Offset US		INT	RW	0x0 (0_{dec})
F81F:17	Gain UP		UINT	RW	0x4000 (16384_{dec})
F81F:18	Offset UP		INT	RW	0x0 (0_{dec})
F81F:19	Gain Temperature		UINT	RW	0x4000 (16384_{dec})
F81F:1A	Offset Temperature		INT	RW	0x0 (0_{dec})

6.2 Standard objects

1000 Device type

Index (hex)	Name	Meaning	Data type	Flags	Default
1000:0	Device type	Device type of the EtherCAT slave: the Lo-Word contains the used CoE profile (5001). The Hi-Word contains the module profile according to the modular device profile.	UDINT	RO	0x1389 (5001_{dec})

1008 Device name

Index (hex)	Name	Meaning	Data type	Flags	Default
1008:0	Device name	Device name of the EtherCAT slave	STRING(11)	RO	EP9224-0037

1009 Hardware version

Index (hex)	Name	Meaning	Data type	Flags	Default
1009:0	Hardware version	Hardware version of the EtherCAT slave	STRING(2)	RO	-

100A Software version

Index (hex)	Name	Meaning	Data type	Flags	Default
100A:0	Software version	Firmware version of the EtherCAT slave	STRING(2)	RO	-

100B Bootloader version

Index (hex)	Name	Meaning	Data type	Flags	Default
100B:0	Bootloader version	-	STRING(32)	RO	-

1018 Identity

Index (hex)	Name	Meaning	Data type	Flags	Default
1018:0	Identity	Information for identifying the slave	USINT	RO	0x4 (4_{dec})
1018:01	Vendor ID	Vendor ID of the EtherCAT slave	UDINT	RO	0x2 (2_{dec})
1018:02	Product code	Product code of the EtherCAT slave	UDINT	RO	0x24084052 (604520530_{dec})
1018:03	Revision	Revision number of the EtherCAT slave; the Low Word (bit 0-15) indicates the special terminal number, the High Word (bit 16-31) refers to the device description	UDINT	RO	-
1018:04	Serial number	Serial number of the EtherCAT slave; the Low Byte (bit 0-7) of the Low Word contains the year of production, the High Byte (bit 8-15) of the Low Word contains the week of production, the High Word (bit 16-31) is 0	UDINT	RO	-

10F0 Backup parameter handling

Index (hex)	Name	Meaning	Data type	Flags	Default
10F0:0	Backup parameter handling		USINT	RO	0x1 (1_{dec})
10F0:01	Checksum	Checksum across all backup entries of the EtherCAT slave	UDINT	RO	-

1600 DPO RxPDO-Map Outputs Ch.1

Index (hex)	Name	Meaning	Data type	Flags	Default
1600:0	DPO RxPDO-Map Outputs Ch.1		USINT	RO	0x6 (6_{dec})
1600:01	SubIndex 001	PDO Mapping Entry for "Output Us".	UDINT	RO	0x7000:01, 1
1600:02	SubIndex 002	PDO Mapping Entry for "Output Up".	UDINT	RO	0x7000:02, 1
1600:03	SubIndex 003		UDINT	RO	0x0000:00, 2
1600:04	SubIndex 004	PDO Mapping Entry for "Reset Us".	UDINT	RO	0x7000:05, 1
1600:05	SubIndex 005	PDO Mapping Entry for "Reset Up".	UDINT	RO	0x7000:06, 1
1600:06	SubIndex 006		UDINT	RO	0x0000:00, 10

1601 DPO RxPDO-Map Extended Diag Outputs Ch.1

Index (hex)	Name	Meaning	Data type	Flags	Default
1601:0	DPO RxPDO-Map Extended Diag Outputs Ch.1		USINT	RO	0x2 (2_{dec})
1601:01	SubIndex 001	PDO Mapping Entry for "Reset Extended Diag Data".	UDINT	RO	0x7000:11, 1
1601:02	SubIndex 002		UDINT	RO	0x0000:00, 15

1602 DPO RxPDO-Map Outputs Ch.2

Index (hex)	Name	Meaning	Data type	Flags	Default
1602:0	DPO RxPDO-Map Outputs Ch.2		USINT	RO	0x6 (6_{dec})
1602:01	SubIndex 001	PDO Mapping Entry for "Output Us".	UDINT	RO	0x7010:01, 1
1602:02	SubIndex 002	PDO Mapping Entry for "Output Up".	UDINT	RO	0x7010:02, 1
1602:03	SubIndex 003		UDINT	RO	0x0000:00, 2
1602:04	SubIndex 004	PDO Mapping Entry for "Reset Us".	UDINT	RO	0x7010:05, 1
1602:05	SubIndex 005	PDO Mapping Entry for "Reset Up".	UDINT	RO	0x7010:06, 1
1602:06	SubIndex 006		UDINT	RO	0x0000:00, 10

1603 DPO RxPDO-Map Extended Diag Outputs Ch.2

Index (hex)	Name	Meaning	Data type	Flags	Default
1603:0	DPO RxPDO-Map Extended Diag Outputs Ch.2		USINT	RO	0x2 (2_{dec})
1603:01	SubIndex 001	PDO Mapping Entry for "Reset Extended Diag Data".	UDINT	RO	0x7010:11, 1
1603:02	SubIndex 002		UDINT	RO	0x0000:00, 15

1604 DPO RxPDO-Map Outputs Ch.3

Index (hex)	Name	Meaning	Data type	Flags	Default
1604:0	DPO RxPDO-Map Outputs Ch.3		USINT	RO	0x6 (6_{dec})
1604:01	SubIndex 001	PDO Mapping Entry for "Output Us".	UDINT	RO	0x7020:01, 1
1604:02	SubIndex 002	PDO Mapping Entry for "Output Up".	UDINT	RO	0x7020:02, 1
1604:03	SubIndex 003		UDINT	RO	0x0000:00, 2
1604:04	SubIndex 004	PDO Mapping Entry for "Reset Us".	UDINT	RO	0x7020:05, 1
1604:05	SubIndex 005	PDO Mapping Entry for "Reset Up".	UDINT	RO	0x7020:06, 1
1604:06	SubIndex 006		UDINT	RO	0x0000:00, 10

1605 DPO RxPDO-Map Extended Diag Outputs Ch.3

Index (hex)	Name	Meaning	Data type	Flags	Default
1605:0	DPO RxPDO-Map Extended Diag Outputs Ch.3		USINT	RO	0x2 (2_{dec})
1605:01	SubIndex 001	PDO Mapping Entry for "Reset Extended Diag Data".	UDINT	RO	0x7020:11, 1
1605:02	SubIndex 002		UDINT	RO	0x0000:00, 15

1606 DPO RxPDO-Map Outputs Ch.4

Index (hex)	Name	Meaning	Data type	Flags	Default
1606:0	DPO RxPDO-Map Outputs Ch.4		USINT	RO	0x6 (6_{dec})
1606:01	SubIndex 001	PDO Mapping Entry for "Output Us".	UDINT	RO	0x7030:01, 1
1606:02	SubIndex 002	PDO Mapping Entry for "Output Up".	UDINT	RO	0x7030:02, 1
1606:03	SubIndex 003		UDINT	RO	0x0000:00, 2
1606:04	SubIndex 004	PDO Mapping Entry for "Reset Us".	UDINT	RO	0x7030:05, 1
1606:05	SubIndex 005	PDO Mapping Entry for "Reset Up".	UDINT	RO	0x7030:06, 1
1606:06	SubIndex 006		UDINT	RO	0x0000:00, 10

1607 DPO RxPDO-Map Extended Diag Outputs Ch.4

Index (hex)	Name	Meaning	Data type	Flags	Default
1607:0	DPO RxPDO-Map Extended Diag Outputs Ch.4		USINT	RO	0x2 (2_{dec})
1607:01	SubIndex 001	PDO Mapping Entry for "Reset Extended Diag Data".	UDINT	RO	0x7030:11, 1
1607:02	SubIndex 002		UDINT	RO	0x0000:00, 15

1608 DPO RxPDO-Map Outputs Device

Index (hex)	Name	Meaning	Data type	Flags	Default
1608:0	DPO RxPDO-Map Outputs Device		USINT	RO	0x4 (4_{dec})
1608:01	SubIndex 001	PDO Mapping Entry for "Enable Control Via Fieldbus".	UDINT	RO	0xf707:01, 1
1608:02	SubIndex 002		UDINT	RO	0x0000:00, 2
1608:03	SubIndex 003	PDO Mapping Entry for "Global Reset".	UDINT	RO	0xf707:04, 1
1608:04	SubIndex 004		UDINT	RO	0x0000:00, 12

1609 DPO RxPDO-Map Extended Diag Outputs Device

Index (hex)	Name	Meaning	Data type	Flags	Default
1609:0	DPO RxPDO-Map Extended Diag Outputs Device		USINT	RO	0x2 (2_{dec})
1609:01	SubIndex 001	PDO Mapping Entry for "Reset Extended Diag Data".	UDINT	RO	0xf707:11, 1
1609:02	SubIndex 002		UDINT	RO	0x0000:00, 15

1610 LOG RxPDO-Map Control

Index (hex)	Name	Meaning	Data type	Flags	Default
1610:0	LOG RxPDO-Map Control		USINT	RO	0x3 (3_{dec})
1610:01	SubIndex 001	PDO Mapping Entry for "Start Logger".	UDINT	RO	0x7040:01, 1
1610:02	SubIndex 002	PDO Mapping Entry for "Stop Logger".	UDINT	RO	0x7040:02, 1
1610:03	SubIndex 003		UDINT	RO	0x0000:00, 14

1A00 DPO TxPDO-Map Inputs Ch.1

Index (hex)	Name	Meaning	Data type	Flags	Default
1A00:0	DPO TxPDO-Map Inputs Ch.1		USINT	RO	0xe (14_{dec})
1A00:01	SubIndex 001	PDO Mapping Entry for "Error Us".	UDINT	RO	0x6000:01, 1
1A00:02	SubIndex 002	PDO Mapping Entry for "Error Up".	UDINT	RO	0x6000:02, 1
1A00:03	SubIndex 003	PDO Mapping Entry for "Warning Us".	UDINT	RO	0x6000:03, 1
1A00:04	SubIndex 004	PDO Mapping Entry for "Warning Up".	UDINT	RO	0x6000:04, 1
1A00:05	SubIndex 005	PDO Mapping Entry for "Status Us".	UDINT	RO	0x6000:05, 1
1A00:06	SubIndex 006	PDO Mapping Entry for "Status Up".	UDINT	RO	0x6000:06, 1
1A00:07	SubIndex 007	PDO Mapping Entry for "Channel Error".	UDINT	RO	0x6000:07, 1
1A00:08	SubIndex 008	PDO Mapping Entry for "Error Sum Current".	UDINT	RO	0x6000:08, 1
1A00:09	SubIndex 009	PDO Mapping Entry for "Warning Sum Current".	UDINT	RO	0x6000:09, 1
1A00:0A	SubIndex 010		UDINT	RO	0x0000:00, 5
1A00:0B	SubIndex 011	PDO Mapping Entry for "TxPDO State".	UDINT	RO	0x6000:0f, 1
1A00:0C	SubIndex 012	PDO Mapping Entry for "TxPDO Toggle".	UDINT	RO	0x6000:10, 1
1A00:0D	SubIndex 013	PDO Mapping Entry for "Current Us".	UDINT	RO	0x6000:11, 16
1A00:0E	SubIndex 014	PDO Mapping Entry for "Current Up".	UDINT	RO	0x6000:12, 16

1A01 DPO TxPDO-Map Extended Diag Inputs Ch.1

Index (hex)	Name	Meaning	Data type	Flags	Default
1A01:0	DPO TxPDO-Map Extended Diag Inputs Ch.1		USINT	RO	0x4 (4_{dec})
1A01:01	SubIndex 001	PDO Mapping Entry for "Peak Value 1".	UDINT	RO	0x6000:13, 16
1A01:02	SubIndex 002	PDO Mapping Entry for "Peak Value 2".	UDINT	RO	0x6000:14, 16
1A01:03	SubIndex 003	PDO Mapping Entry for "Timestamp 1".	UDINT	RO	0x6000:17, 64
1A01:04	SubIndex 004	PDO Mapping Entry for "Timestamp 2".	UDINT	RO	0x6000:18, 64

1A02 DPO TxPDO-Map Inputs Ch.2

Index (hex)	Name	Meaning	Data type	Flags	Default
1A02:0	DPO TxPDO-Map Inputs Ch.2		USINT	RO	0xe (14_{dec})
1A02:01	SubIndex 001	PDO Mapping Entry for "Error Us".	UDINT	RO	0x6010:01, 1
1A02:02	SubIndex 002	PDO Mapping Entry for "Error Up".	UDINT	RO	0x6010:02, 1
1A02:03	SubIndex 003	PDO Mapping Entry for "Warning Us".	UDINT	RO	0x6010:03, 1
1A02:04	SubIndex 004	PDO Mapping Entry for "Warning Up".	UDINT	RO	0x6010:04, 1
1A02:05	SubIndex 005	PDO Mapping Entry for "Status Us".	UDINT	RO	0x6010:05, 1
1A02:06	SubIndex 006	PDO Mapping Entry for "Status Up".	UDINT	RO	0x6010:06, 1
1A02:07	SubIndex 007	PDO Mapping Entry for "Channel Error".	UDINT	RO	0x6010:07, 1
1A02:08	SubIndex 008	PDO Mapping Entry for "Error Sum Current".	UDINT	RO	0x6010:08, 1
1A02:09	SubIndex 009	PDO Mapping Entry for "Warning Sum Current".	UDINT	RO	0x6010:09, 1
1A02:0A	SubIndex 010		UDINT	RO	0x0000:00, 5
1A02:0B	SubIndex 011	PDO Mapping Entry for "TxPDO State".	UDINT	RO	0x6010:0f, 1
1A02:0C	SubIndex 012	PDO Mapping Entry for "TxPDO Toggle".	UDINT	RO	0x6010:10, 1
1A02:0D	SubIndex 013	PDO Mapping Entry for "Current Us".	UDINT	RO	0x6010:11, 16
1A02:0E	SubIndex 014	PDO Mapping Entry for "Current Up".	UDINT	RO	0x6010:12, 16

1A03 DPO TxPDO-Map Extended Diag Inputs Ch.2

Index (hex)	Name	Meaning	Data type	Flags	Default
1A03:0	DPO TxPDO-Map Extended Diag Inputs Ch.2		USINT	RO	0x4 (4_{dec})
1A03:01	SubIndex 001	PDO Mapping Entry for "Peak Value 1".	UDINT	RO	0x6010:13, 16
1A03:02	SubIndex 002	PDO Mapping Entry for "Peak Value 2".	UDINT	RO	0x6010:14, 16
1A03:03	SubIndex 003	PDO Mapping Entry for "Timestamp 1".	UDINT	RO	0x6010:17, 64
1A03:04	SubIndex 004	PDO Mapping Entry for "Timestamp 2".	UDINT	RO	0x6010:18, 64

1A04 DPO TxPDO-Map Inputs Ch.3

Index (hex)	Name	Meaning	Data type	Flags	Default
1A04:0	DPO TxPDO-Map Inputs Ch.3		USINT	RO	0xe (14_{dec})
1A04:01	SubIndex 001	PDO Mapping Entry for "Error Us".	UDINT	RO	0x6020:01, 1
1A04:02	SubIndex 002	PDO Mapping Entry for "Error Up".	UDINT	RO	0x6020:02, 1
1A04:03	SubIndex 003	PDO Mapping Entry for "Warning Us".	UDINT	RO	0x6020:03, 1
1A04:04	SubIndex 004	PDO Mapping Entry for "Warning Up".	UDINT	RO	0x6020:04, 1
1A04:05	SubIndex 005	PDO Mapping Entry for "Status Us".	UDINT	RO	0x6020:05, 1
1A04:06	SubIndex 006	PDO Mapping Entry for "Status Up".	UDINT	RO	0x6020:06, 1
1A04:07	SubIndex 007	PDO Mapping Entry for "Channel Error".	UDINT	RO	0x6020:07, 1
1A04:08	SubIndex 008	PDO Mapping Entry for "Error Sum Current".	UDINT	RO	0x6020:08, 1
1A04:09	SubIndex 009	PDO Mapping Entry for "Warning Sum Current".	UDINT	RO	0x6020:09, 1
1A04:0A	SubIndex 010		UDINT	RO	0x0000:00, 5
1A04:0B	SubIndex 011	PDO Mapping Entry for "TxPDO State".	UDINT	RO	0x6020:0f, 1
1A04:0C	SubIndex 012	PDO Mapping Entry for "TxPDO Toggle".	UDINT	RO	0x6020:10, 1
1A04:0D	SubIndex 013	PDO Mapping Entry for "Current Us".	UDINT	RO	0x6020:11, 16
1A04:0E	SubIndex 014	PDO Mapping Entry for "Current Up".	UDINT	RO	0x6020:12, 16

1A05 DPO TxPDO-Map Extended Diag Inputs Ch.3

Index (hex)	Name	Meaning	Data type	Flags	Default
1A05:0	DPO TxPDO-Map Extended Diag Inputs Ch.3		USINT	RO	0x4 (4_{dec})
1A05:01	SubIndex 001	PDO Mapping Entry for "Peak Value 1".	UDINT	RO	0x6020:13, 16
1A05:02	SubIndex 002	PDO Mapping Entry for "Peak Value 2".	UDINT	RO	0x6020:14, 16
1A05:03	SubIndex 003	PDO Mapping Entry for "Timestamp 1".	UDINT	RO	0x6020:17, 64
1A05:04	SubIndex 004	PDO Mapping Entry for "Timestamp 2".	UDINT	RO	0x6020:18, 64

1A06 DPO TxPDO-Map Inputs Ch.4

Index (hex)	Name	Meaning	Data type	Flags	Default
1A06:0	DPO TxPDO-Map Inputs Ch.4		USINT	RO	0xe (14_{dec})
1A06:01	SubIndex 001	PDO Mapping Entry for "Error Us".	UDINT	RO	0x6030:01, 1
1A06:02	SubIndex 002	PDO Mapping Entry for "Error Up".	UDINT	RO	0x6030:02, 1
1A06:03	SubIndex 003	PDO Mapping Entry for "Warning Us".	UDINT	RO	0x6030:03, 1
1A06:04	SubIndex 004	PDO Mapping Entry for "Warning Up".	UDINT	RO	0x6030:04, 1
1A06:05	SubIndex 005	PDO Mapping Entry for "Status Us".	UDINT	RO	0x6030:05, 1
1A06:06	SubIndex 006	PDO Mapping Entry for "Status Up".	UDINT	RO	0x6030:06, 1
1A06:07	SubIndex 007	PDO Mapping Entry for "Channel Error".	UDINT	RO	0x6030:07, 1
1A06:08	SubIndex 008	PDO Mapping Entry for "Error Sum Current".	UDINT	RO	0x6030:08, 1
1A06:09	SubIndex 009	PDO Mapping Entry for "Warning Sum Current".	UDINT	RO	0x6030:09, 1
1A06:0A	SubIndex 010		UDINT	RO	0x0000:00, 5
1A06:0B	SubIndex 011	PDO Mapping Entry for "TxPDO State".	UDINT	RO	0x6030:0f, 1
1A06:0C	SubIndex 012	PDO Mapping Entry for "TxPDO Toggle".	UDINT	RO	0x6030:10, 1
1A06:0D	SubIndex 013	PDO Mapping Entry for "Current Us".	UDINT	RO	0x6030:11, 16
1A06:0E	SubIndex 014	PDO Mapping Entry for "Current Up".	UDINT	RO	0x6030:12, 16

1A07 DPO TxPDO-Map Extended Diag Inputs Ch.4

Index (hex)	Name	Meaning	Data type	Flags	Default
1A07:0	DPO TxPDO-Map Extended Diag Inputs Ch.4		USINT	RO	0x4 (4_{dec})
1A07:01	SubIndex 001	PDO Mapping Entry for "Peak Value 1".	UDINT	RO	0x6030:13, 16
1A07:02	SubIndex 002	PDO Mapping Entry for "Peak Value 2"".	UDINT	RO	0x6030:14, 16
1A07:03	SubIndex 003	PDO Mapping Entry for "Timestamp 1".	UDINT	RO	0x6030:17, 64
1A07:04	SubIndex 004	PDO Mapping Entry for "Timestamp 2".	UDINT	RO	0x6030:18, 64

1A08 DPO TxPDO-Map Inputs Device

Index (hex)	Name	Meaning	Data type	Flags	Default
1A08:0	DPO TxPDO-Map Inputs Device		USINT	RO	0x11 (17_{dec})
1A08:01	SubIndex 001	PDO Mapping Entry for "Warning Temperature".	UDINT	RO	0xf607:01, 1
1A08:02	SubIndex 002	PDO Mapping Entry for "Error Temperature".	UDINT	RO	0xf607:02, 1
1A08:03	SubIndex 003	PDO Mapping Entry for "Warning Us".	UDINT	RO	0xf607:03, 1
1A08:04	SubIndex 004	PDO Mapping Entry for "Error Us".	UDINT	RO	0xf607:04, 1
1A08:05	SubIndex 005	PDO Mapping Entry for "Warning Up".	UDINT	RO	0xf607:05, 1
1A08:06	SubIndex 006	PDO Mapping Entry for "Error Up".	UDINT	RO	0xf607:06, 1
1A08:07	SubIndex 007	PDO Mapping Entry for "Global Error Bit".	UDINT	RO	0xf607:07, 1
1A08:08	SubIndex 008	PDO Mapping Entry for "Warning Sum Current".	UDINT	RO	0xf607:08, 1
1A08:09	SubIndex 009	PDO Mapping Entry for "Error Sum Current".	UDINT	RO	0xf607:09, 1
1A08:0A	SubIndex 010		UDINT	RO	0x0000:00, 5
1A08:0B	SubIndex 011	PDO Mapping Entry for "TxPDO State".	UDINT	RO	0xf607:0f, 1
1A08:0C	SubIndex 012	PDO Mapping Entry for "TxPDO Toggle".	UDINT	RO	0xf607:10, 1
1A08:0D	SubIndex 013	PDO Mapping Entry for "Current Us".	UDINT	RO	0xf607:11, 16
1A08:0E	SubIndex 014	PDO Mapping Entry for "Current Up".	UDINT	RO	0xf607:12, 16
1A08:0F	SubIndex 015	PDO Mapping Entry for "Voltage Us".	UDINT	RO	0xf607:13, 16
1A08:10	SubIndex 016	PDO Mapping Entry for "Voltage Up".	UDINT	RO	0xf607:14, 16
1A08:11	SubIndex 017	PDO Mapping Entry for "Temperature".	UDINT	RO	0xf607:15, 16

1A09 DPO TxPDO-Map Extended Diag Inputs Device

Index (hex)	Name	Meaning	Data type	Flags	Default
1A09:0	DPO TxPDO-Map Extended Diag Inputs Device		USINT	RO	0x4 (4_{dec})
1A09:01	SubIndex 001	PDO Mapping Entry for "Peak Value 1".	UDINT	RO	0xf607:16, 16
1A09:02	SubIndex 002	PDO Mapping Entry for "Peak Value 2".	UDINT	RO	0xf607:17, 16
1A09:03	SubIndex 003	PDO Mapping Entry for "Timestamp 1".	UDINT	RO	0xf607:18, 64
1A09:04	SubIndex 004	PDO Mapping Entry for "Timestamp 2".	UDINT	RO	0xf607:19, 64

1A10 LOG TxPDO-Map Status

Index (hex)	Name	Meaning	Data type	Flags	Default
1A10:0	LOG TxPDO-Map Status		USINT	RO	0x4 (4_{dec})
1A10:01	SubIndex 001	PDO Mapping Entry for "Logger Running".	UDINT	RO	0x6040:01, 1
1A10:02	SubIndex 002		UDINT	RO	0x0000:00, 15
1A10:03	SubIndex 003	PDO Mapping Entry for "Elapsed Time".	UDINT	RO	0x6040:11, 32
1A10:04	SubIndex 004	PDO Mapping Entry for "Trigger Reason".	UDINT	RO	0x6040:12, 16

1C00 Sync manager type

Index (hex)	Name	Meaning	Data type	Flags	Default
1C00:0	Sync manager type		USINT	RO	0x4 (4_{dec})
1C00:01	SubIndex 001	Sync-Manager Type Channel 1: Mailbox Write	USINT	RO	0x1 (1_{dec})
1C00:02	SubIndex 002	Sync-Manager Type Channel 2: Mailbox Read	USINT	RO	0x2 (2_{dec})
1C00:03	SubIndex 003	Sync-Manager Type Channel 3: Process Data Write (Outputs)	USINT	RO	0x3 (3_{dec})
1C00:04	SubIndex 004	Sync-Manager Type Channel 4: Process Data Read (Inputs)	USINT	RO	0x4 (4_{dec})

1C12 RxPDO assign

Index (hex)	Name	Meaning	Data type	Flags	Default
1C12:0	RxPDO assign		USINT	RO	0x5 (5_{dec})
1C12:01	SubIndex 001		UINT	RW	0x1600 (5632_{dec})
1C12:02	SubIndex 002		UINT	RW	0x1602 (5634_{dec})
1C12:03	SubIndex 003		UINT	RW	0x1604 (5636_{dec})
1C12:04	SubIndex 004		UINT	RW	0x1606 (5638_{dec})
1C12:05	SubIndex 005		UINT	RW	0x1608 (5640_{dec})
1C12:06	SubIndex 006		UINT	RW	0x0 (0_{dec})
1C12:07	SubIndex 007		UINT	RW	0x0 (0_{dec})
1C12:08	SubIndex 008		UINT	RW	0x0 (0_{dec})
1C12:09	SubIndex 009		UINT	RW	0x0 (0_{dec})
1C12:0A	SubIndex 010		UINT	RW	0x0 (0_{dec})
1C12:0B	SubIndex 011		UINT	RW	0x0 (0_{dec})

1C13 TxPDO assign

Index (hex)	Name	Meaning	Data type	Flags	Default
1C13:0	TxPDO assign		USINT	RO	0x5 (5_{dec})
1C13:01	SubIndex 001		UINT	RW	0x1a00 (6656_{dec})
1C13:02	SubIndex 002		UINT	RW	0x1a02 (6658_{dec})
1C13:03	SubIndex 003		UINT	RW	0x1a04 (6660_{dec})
1C13:04	SubIndex 004		UINT	RW	0x1a06 (6662_{dec})
1C13:05	SubIndex 005		UINT	RW	0x1a08 (6664_{dec})
1C13:06	SubIndex 006		UINT	RW	0x0 (0_{dec})
1C13:07	SubIndex 007		UINT	RW	0x0 (0_{dec})
1C13:08	SubIndex 008		UINT	RW	0x0 (0_{dec})
1C13:09	SubIndex 009		UINT	RW	0x0 (0_{dec})
1C13:0A	SubIndex 010		UINT	RW	0x0 (0_{dec})
1C13:0B	SubIndex 011		UINT	RW	0x0 (0_{dec})

1C32 SM output parameter

Index (hex)	Name	Meaning	Data type	Flags	Default
1C32:0	SM output parameter	Synchronization parameters for the outputs	USINT	RO	0x20 (32_{dec})
1C32:01	Sync mode	Current synchronization mode: • 0: Free Run • 1: Synchron with SM 2 Event • 2: DC-Mode - Synchron with SYNC0 Event 3: DC-Mode - Synchron with SYNC1 Event	UINT	RW	0x0 (0_{dec})
1C32:02	Cycle time	Cycle time (in ns): • Free Run: cycle time of the local timer • Synchron with SM 2 Event: cycle time of the master DC-Mode: SYNC0/SYNC1 Cycle Time	UDINT	RW	0xf4240 (1000000_{dec})
1C32:03	Shift time	Time between SYNC0 event and output of the outputs (in ns, DC mode only)	UDINT	RO	0x0 (0_{dec})
1C32:04	Sync modes supported	Sync modes supported: • Bit 0 = 1: Free Run is supported • Bit 1 = 1: Synchron with SM 2 Event is supported • Bit 2-3 = 01: DC-Mode is supported • Bit 4-5 = 10: Output Shift with SYNC1 Event (only DC mode) Bit 14 = 1: dynamic times (measurement through writing of 1C32:08)	UINT	RO	0x1 (1_{dec})
1C32:05	Minimum cycle time	Minimum cycle time (in ns)	UDINT	RO	0xf4240 (1000000_{dec})
1C32:06	Calc and copy time	Minimum time between SYNC0 and SYNC1 event (in ns, DC Mode only)	UDINT	RO	0x0 (0_{dec})
1C32:07	Minimum delay time		UDINT	RO	0x0 (0_{dec})
1C32:08	Get Cycle Time	Possible values: • 0: Stop measurement of the local cycle time • 1: Start measurement of the local cycle time The parameters 1C32:03, 1C32:05, 1C32:06, 1C32:09, 1C33:03, 1C33:06, 1C33:09 are updated with the maximum measured values. For a subsequent measurement the measured values are reset	UINT	RW	0x0 (0_{dec})
1C32:09	Maximum delay time	Time between SYNC1 event and output of the outputs (in ns, DC mode only)	UDINT	RO	0x0 (0_{dec})
1C32:0B	SM event missed counter	Number of missed SM events in OPERATIONAL (DC Mode only)	UINT	RO	-
1C32:0C	Cycle exceeded counter	Number of occasions the cycle time was exceeded in OPERATIONAL (cycle was not completed in time or the next cycle began too early)	UINT	RO	-
1C32:0D	Shift too short counter	Number of intervals between SYNC0 and SYNC1 events that are too short (DC Mode only)	UINT	RO	-
1C32:20	Sync error	The synchronization was not correct in the last cycle (outputs were output too late; DC Mode only)	BOOL	RO	-

1C33 SM input parameter

Index (hex)	Name	Meaning	Data type	Flags	Default
1C33:0	SM input parameter	Synchronization parameters for the inputs	USINT	RO	0x20 (32_{dec})
1C33:01	Sync mode	Current synchronization mode: • 0: Free Run • 1: Synchron with SM 3 Event (no outputs available) • 2: DC - Synchron with SYNC0 Event • 3: DC - Synchron with SYNC1 Event 34: Synchron with SM 2 Event (outputs available)	UINT	RW	0x0 (0_{dec})
1C33:02	Cycle time	as 1C32:02	UDINT	RW	0xf4240 (1000000_{dec})
1C33:03	Shift time	Time between SYNC0 event and reading of the inputs (in ns, DC Mode only)	UDINT	RO	0x0 (0_{dec})
1C33:04	Sync modes supported	Sync modes supported: • Bit 0: Free Run is supported • Bit 1: Synchron with SM 2 Event is supported (outputs available) • Bit 1: Synchron with SM 3 Event is supported (no outputs available) • Bit 2-3 = 01: DC-Mode is supported • Bit 4-5 = 01: Input shift through local event (outputs available) • Bit 4-5 = 10: Input shift with SYNC1 event (no outputs available) Bit 14 = 1: dynamic times (measurement through writing of 1C32:08 or 1C33:08)	UINT	RO	0x1 (1_{dec})
1C33:05	Minimum cycle time	as 1C32:05	UDINT	RO	0xf4240 (1000000_{dec})
1C33:06	Calc and copy time	Time between reading of the inputs and the inputs being available for the master (in ns, DC Mode only)	UDINT	RO	0x0 (0_{dec})
1C33:07	Minimum delay time		UDINT	RO	0x0 (0_{dec})
1C33:08	Get Cycle Time	as 1C32:08	UINT	RW	0x0 (0_{dec})
1C33:09	Maximum delay time	Time between SYNC1 event and reading of the inputs (in ns, DC Mode only)	UDINT	RO	0x0 (0_{dec})
1C33:0B	SM event missed counter	as 1C32:11	UINT	RO	-
1C33:0C	Cycle exceeded counter	as 1C32:12	UINT	RO	-
1C33:0D	Shift too short counter	as 1C32:13	UINT	RO	-
1C33:20	Sync error	as 1C32:32	BOOL	RO	-

F000 Modular Device Profile

Index (hex)	Name	Meaning	Data type	Flags	Default
F000:0	Modular Device Profile		USINT	RO	0x2 (2_{dec})
F000:01	Index distance		UINT	RO	0x10 (16_{dec})
F000:02	Maximum number of modules		UINT	RO	0x5 (5_{dec})

F008 Code word

Index (hex)	Name	Meaning	Data type	Flags	Default
F008:0	Code word	-	UDINT	RO	-

F010 Module Profile List

Index (hex)	Name	Meaning	Data type	Flags	Default
F010:0	Module Profile List		USINT	RO	0x5 (5_{dec})
F010:01	SubIndex 001		UDINT	RO	0x10e (270_{dec})
F010:02	SubIndex 002		UDINT	RO	0x10e (270_{dec})
F010:03	SubIndex 003		UDINT	RO	0x10e (270_{dec})
F010:04	SubIndex 004		UDINT	RO	0x10e (270_{dec})
F010:05	SubIndex 005		UDINT	RO	0x384 (900_{dec})

6.3 Profile-specific objects

6000 DPO Inputs Ch.1

Index (hex)	Name	Meaning	Data type	Flags	Default
6000:0	DPO Inputs Ch.1		USINT	RO	0x18 (24_{dec})
6000:01	Error Us	-	BOOL	RO	-
6000:02	Error Up	-	BOOL	RO	-
6000:03	Warning Us	-	BOOL	RO	-
6000:04	Warning Up	-	BOOL	RO	-
6000:05	Status Us	-	BOOL	RO	-
6000:06	Status Up	-	BOOL	RO	-
6000:07	Channel Error	-	BOOL	RO	-
6000:08	Error Sum Current	-	BOOL	RO	-
6000:09	Warning Sum Current	-	BOOL	RO	-
6000:0F	TxPDO State	-	BOOL	RO	-
6000:10	TxPDO Toggle	-	BOOL	RO	-
6000:11	Current Us	-	INT	RO	-
6000:12	Current Up	-	INT	RO	-
6000:13	Peak Value 1	-	INT	RO	-
6000:14	Peak Value 2	-	INT	RO	-
6000:17	Timestamp 1	-	ULINT	RO	-
6000:18	Timestamp 2	-	ULINT	RO	-

6010 DPO Inputs Ch.2

Index (hex)	Name	Meaning	Data type	Flags	Default
6010:0	DPO Inputs Ch.2		USINT	RO	0x18 (24_{dec})
6010:01	Error Us	-	BOOL	RO	-
6010:02	Error Up	-	BOOL	RO	-
6010:03	Warning Us	-	BOOL	RO	-
6010:04	Warning Up	-	BOOL	RO	-
6010:05	Status Us	-	BOOL	RO	-
6010:06	Status Up	-	BOOL	RO	-
6010:07	Channel Error	-	BOOL	RO	-
6010:08	Error Sum Current	-	BOOL	RO	-
6010:09	Warning Sum Current	-	BOOL	RO	-
6010:0F	TxPDO State	-	BOOL	RO	-
6010:10	TxPDO Toggle	-	BOOL	RO	-
6010:11	Current Us	-	INT	RO	-
6010:12	Current Up	-	INT	RO	-
6010:13	Peak Value 1	-	INT	RO	-
6010:14	Peak Value 2	-	INT	RO	-
6010:17	Timestamp 1	-	ULINT	RO	-
6010:18	Timestamp 2	-	ULINT	RO	-

6020 DPO Inputs Ch.3

Index (hex)	Name	Meaning	Data type	Flags	Default
6020:0	DPO Inputs Ch.3		USINT	RO	0x18 (24_{dec})
6020:01	Error Us	-	BOOL	RO	-
6020:02	Error Up	-	BOOL	RO	-
6020:03	Warning Us	-	BOOL	RO	-
6020:04	Warning Up	-	BOOL	RO	-
6020:05	Status Us	-	BOOL	RO	-
6020:06	Status Up	-	BOOL	RO	-
6020:07	Channel Error	-	BOOL	RO	-
6020:08	Error Sum Current	-	BOOL	RO	-
6020:09	Warning Sum Current	-	BOOL	RO	-
6020:0F	TxPDO State	-	BOOL	RO	-
6020:10	TxPDO Toggle	-	BOOL	RO	-
6020:11	Current Us	-	INT	RO	-
6020:12	Current Up	-	INT	RO	-
6020:13	Peak Value 1	-	INT	RO	-
6020:14	Peak Value 2	-	INT	RO	-
6020:17	Timestamp 1	-	ULINT	RO	-
6020:18	Timestamp 2	-	ULINT	RO	-

6030 DPO Inputs Ch.4

Index (hex)	Name	Meaning	Data type	Flags	Default
6030:0	DPO Inputs Ch.4		USINT	RO	0x18 (24_{dec})
6030:01	Error Us	-	BOOL	RO	-
6030:02	Error Up	-	BOOL	RO	-
6030:03	Warning Us	-	BOOL	RO	-
6030:04	Warning Up	-	BOOL	RO	-
6030:05	Status Us	-	BOOL	RO	-
6030:06	Status Up	-	BOOL	RO	-
6030:07	Channel Error	-	BOOL	RO	-
6030:08	Error Sum Current	-	BOOL	RO	-
6030:09	Warning Sum Current	-	BOOL	RO	-
6030:0F	TxPDO State	-	BOOL	RO	-
6030:10	TxPDO Toggle	-	BOOL	RO	-
6030:11	Current Us	-	INT	RO	-
6030:12	Current Up	-	INT	RO	-
6030:13	Peak Value 1	-	INT	RO	-
6030:14	Peak Value 2	-	INT	RO	-
6030:17	Timestamp 1	-	ULINT	RO	-
6030:18	Timestamp 2	-	ULINT	RO	-

6040 LOG Status

Index (hex)	Name	Meaning	Data type	Flags	Default
6040:0	LOG Status		USINT	RO	0x12 (18_{dec})
6040:01	Logger Running	-	BOOL	RO	-
6040:11	Elapsed Time	-	UDINT	RO	-
6040:12	Trigger Reason	-	UINT	RO	-

7000 DPO Outputs Ch.1

Index (hex)	Name	Meaning	Data type	Flags	Default
7000:0	DPO Outputs Ch.1		USINT	RO	0x11 (17_{dec})
7000:01	Output Us	-	BOOL	RO	-
7000:02	Output Up	-	BOOL	RO	-
7000:05	Reset Us	-	BOOL	RO	-
7000:06	Reset Up	-	BOOL	RO	-
7000:11	Reset Extended Diag Data	-	BOOL	RO	-

7010 DPO Outputs Ch.2

Index (hex)	Name	Meaning	Data type	Flags	Default
7010:0	DPO Outputs Ch.2		USINT	RO	0x11 (17_{dec})
7010:01	Output Us	-	BOOL	RO	-
7010:02	Output Up	-	BOOL	RO	-
7010:05	Reset Us	-	BOOL	RO	-
7010:06	Reset Up	-	BOOL	RO	-
7010:11	Reset Extended Diag Data	-	BOOL	RO	-

7020 DPO Outputs Ch.3

Index (hex)	Name	Meaning	Data type	Flags	Default
7020:0	DPO Outputs Ch.3		USINT	RO	0x11 (17_{dec})
7020:01	Output Us	-	BOOL	RO	-
7020:02	Output Up	-	BOOL	RO	-
7020:05	Reset Us	-	BOOL	RO	-
7020:06	Reset Up	-	BOOL	RO	-
7020:11	Reset Extended Diag Data	-	BOOL	RO	-

7030 DPO Outputs Ch.4

Index (hex)	Name	Meaning	Data type	Flags	Default
7030:0	DPO Outputs Ch.4		USINT	RO	0x11 (17_{dec})
7030:01	Output Us	-	BOOL	RO	-
7030:02	Output Up	-	BOOL	RO	-
7030:05	Reset Us	-	BOOL	RO	-
7030:06	Reset Up	-	BOOL	RO	-
7030:11	Reset Extended Diag Data	-	BOOL	RO	-

7040 LOG Control

Index (hex)	Name	Meaning	Data type	Flags	Default
7040:0	LOG Control		USINT	RO	0x2 (2_{dec})
7040:01	Start Logger	-	BOOL	RO	-
7040:02	Stop Logger	-	BOOL	RO	-

F607 DPO Inputs Device

Index (hex)	Name	Meaning	Data type	Flags	Default
F607:0	DPO Inputs Device		USINT	RO	0x19 (25_{dec})
F607:01	Warning Temperature	-	BOOL	RO	-
F607:02	Error Temperature	-	BOOL	RO	-
F607:03	Warning Us	-	BOOL	RO	-
F607:04	Error Us	-	BOOL	RO	-
F607:05	Warning Up	-	BOOL	RO	-
F607:06	Error Up	-	BOOL	RO	-
F607:07	Global Error Bit	-	BOOL	RO	-
F607:08	Warning Sum Current	-	BOOL	RO	-
F607:09	Error Sum Current	-	BOOL	RO	-
F607:0F	TxPDO State	-	BOOL	RO	-
F607:10	TxPDO Toggle	-	BOOL	RO	-
F607:11	Current Us	-	INT	RO	-
F607:12	Current Up	-	INT	RO	-
F607:13	Voltage Us	-	INT	RO	-
F607:14	Voltage Up	-	INT	RO	-
F607:15	Temperature	-	INT	RO	-
F607:16	Peak Value 1	-	INT	RO	-
F607:17	Peak Value 2	-	INT	RO	-
F607:18	Timestamp 1	-	ULINT	RO	-
F607:19	Timestamp 2	-	ULINT	RO	-

F707 DPO Outputs Device

Index (hex)	Name	Meaning	Data type	Flags	Default
F707:0	DPO Outputs Device		USINT	RO	0x11 (17_{dec})
F707:01	Enable Control Via Fieldbus	-	BOOL	RO	-
F707:04	Global Reset	-	BOOL	RO	-
F707:11	Reset Extended Diag Data	-	BOOL	RO	-

7 Appendix

7.1 General operating conditions

Protection rating according to IP code

The degrees of protection are defined and divided into different classes in the IEC 60529 standard (EN 60529). Degrees of protection are designated by the letters "IP" and two numerals: **IPxy**

- Numeral x: Dust protection and contact protection
- Numeral y: Protection against water

x	Meaning
0	Not protected
1	Protected against access to dangerous parts with the back of the hand. Protected against solid foreign objects of 50 mm Ø
2	Protected against access to dangerous parts with a finger. Protected against solid foreign objects of 12.5 mm Ø
3	Protected against access to dangerous parts with a tool. Protected against solid foreign objects of 2.5 mm Ø
4	Protected against access to dangerous parts with a wire. Protected against solid foreign objects of 1 mm Ø
5	Protection against access to dangerous parts with a wire. Dust-protected. Ingress of dust is not prevented completely, although the quantity of dust able to penetrate is limited to such an extent that the proper function of the device and safety are not impaired
6	Protection against access to dangerous parts with a wire. Dust-tight. No ingress of dust

y	Meaning
0	Not protected
1	Protection against vertically falling water drops
2	Protection against vertically falling water drops when enclosure tilted up to 15°
3	Protection against spraying water. Water sprayed at an angle of up to 60° on either side of the vertical shall have no harmful effects
4	Protection against splashing water. Water splashed against the enclosure from any direction shall have no harmful effects
5	Protection against water jets.
6	Protection against powerful water jets.
7	Protected against the effects of temporary immersion in water. Ingress of water in quantities causing harmful effects shall not be possible when the enclosure is immersed in water at a depth of 1 m for 30 minutes

Chemical resistance

The resistance refers to the housing of the IP67 modules and the metal parts used. In the table below you will find some typical resistances.

Type	Resistance
Water vapor	unstable at temperatures > 100 °C
Sodium hydroxide solution (ph value > 12)	stable at room temperature unstable > 40 °C
Acetic acid	unstable
Argon (technically pure)	stable

Key

- resistant: Lifetime several months
- non inherently resistant: Lifetime several weeks
- not resistant: Lifetime several hours resp. early decomposition

7.2 Accessories

Labeling material, protective caps

Ordering information	Description	
ZS5000-0010	Blanking plug for M8 sockets, IP67 (50 pieces)	Website
ZS5100-0000	Inscription labels, unprinted, 4 strips of 10	Data sheet
ZS5000-xxxx	Printed inscription labels on enquiry	n/a

Cables

A complete overview of pre-assembled cables can be found on the Beckhoff website: Link.

Ordering information	Description	Link
ZK700x-xxxx-xxxx	EtherCAT P cable M8	Website
ZK7208-3xxx-Axxx	ENP cable B17 5G 1.5 mm^2	Website

Tools

Ordering information	Description	Link
ZB8801-0000	Torque wrench for plugs, 0.4…1.0 Nm	Website
ZB8801-0001	Torque cable key for M8/wrench size 9 for ZB8801-0000	Website

Further accessories

You can find further accessories at https://www.beckhoff.com/accessories.

7.3 Version identification of EtherCAT devices

7.3.1 General notes on marking

Name

A Beckhoff EtherCAT device has a 14-digit technical designation consisting of

- Family key
- Type
- Version
- Revision

Example	Family	Type	Version	Revision
EL3314-0000-0016	EL Terminal 12 mm, fixed connection level	3314 4-channel thermocouple terminal	0000 basic type	0016
ES3602-0010-0017	ES Terminal 12 mm, pluggable connection level	3602 2-channel voltage measurement	0010 high-precision version	0017
CU2008-0000-0000	CU device	2008 8-port Fast Ethernet switch	0000 basic type	0000

Notes

- The elements stated above result in the **technical designation**. EL3314-0000-0016 is used in the example below.
- EL3314-0000 is the order identifier, for “-0000” usually abbreviated to EL3314. “-0016” is the EtherCAT revision.
- The **order identifier** is composed of
  - family key (EL, EP, CU, ES, KL, CX, etc.)
  - type (3314)
  - version (0000)
- The **revision** -0016 reflects the technical progress such as feature enhancement with regard to EtherCAT communication and is managed by Beckhoff.
  In principle, a device with a higher revision can replace a device with a lower revision, unless otherwise specified, e.g. in the documentation.
  There is usually a description (ESI, EtherCAT Slave Information) in the form of an XML file which is associated and synonymous with each revision, and this is available for download from the Beckhoff website.
  Since January 2014, the revision has been marked on the outside of the IP20 terminals; see Fig. *“EL2872 with revision 0022 and serial number 01200815.”*
- The type, version, and revision are read as decimal numbers, even if they are technically saved in hexadecimal.

7.3.2 Version identification of IP67 modules

The serial number/date code for Beckhoff IO devices is usually the 8-digit number printed on the device or on a sticker. The serial number indicates the configuration in delivery state and therefore refers to a whole production batch, without distinguishing the individual modules within a batch.

Structure of the serial number: **KK YY FF HH**

KK – week of production (calendar week)
YY – year of production
FF – firmware version
HH – hardware version

Example with serial number 12 06 3A 02:

12 – week of production 12
06 – year of production 2006
3A – firmware version 3A
02 – hardware version 02

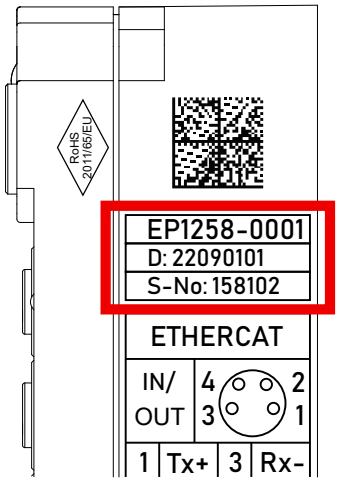


Fig. 8: EP1258-00001 IP67 EtherCAT Box with batch number/DateCode 22090101 and unique serial number 158102

7.3.3 Beckhoff Identification Code (BIC)

The Beckhoff Identification Code (BIC) is increasingly being applied to Beckhoff products to uniquely identify them. The BIC is represented as a Data Matrix code (DMC, code schema ECC200); its content is based on ANSI standard MH10.8.2-2016.

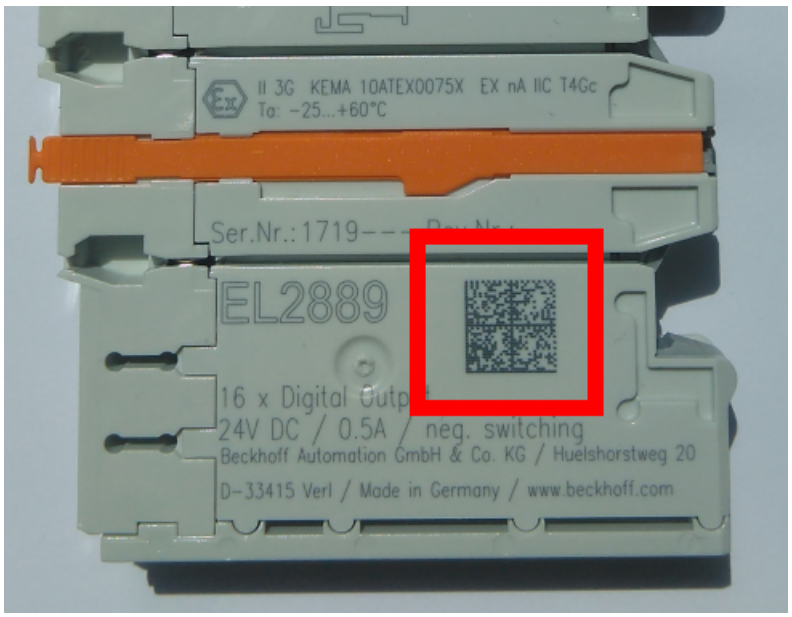


Fig. 9: BIC as a Data Matrix code (DMC, ECC200 code scheme)

The BIC is being introduced gradually across all product groups.
Depending on the product, it can be found in the following locations:

- on the packaging unit
- directly on the product (if space suffices)
- on the packaging unit and the product

The BIC is machine-readable and contains information that can be used for handling and product management by the customer.

Each item of information is clearly identifiable with the data identifier (ANSI MH10.8.2-2016). The data identifier is followed by a character string. Both together have a maximum length stated by the following table. If the items of information are shorter, spaces are added.

The following information may be present; items 1 through 4 are always included, while the others depend on the product family's requirements:

Item no.	Type of information	Explanation	Data identifier	Number of characters including the data identifier	Example
1	Beckhoff order number	**Beckhoff order number**	1P	8	**1P**072222
2	Beckhoff Traceability Number (BTN)	**Unique serial number, see note below**	SBTN	12	**SBTN**k4p562d7
3	Article description	**Beckhoff article description, e.g. EL1008**	1K	32	**1K**EL1809
4	Quantity	**Quantity in packaging unit, e.g. 1, 10, etc.**	Q	6	**Q**1
5	Batch number	Optional: Year and week of production	2P	14	**2P**401503180016
6	ID/serial number	Optional: Previous serial number system, e.g., for safety products or calibrated terminals	51S	12	**51S**678294
7	Variant	Optional: Product variant number on the basis of standard products	30P	12	**30P**F971, 2*K183
...					

Beckhoff uses additional types of information and data identifiers for internal processes.

Structure of the BIC

Example of composite information consisting of items 1 through 4 and the example value mentioned above in item 6. The data identifiers are highlighted in bold:

1P072222**SBTN**k4p562d7**1K**EL1809 **Q**1 **51S**678294

The same number as a DMC:



Fig. 10: Example DMC **1P**072222**SBTN**k4p562d7**1K**EL1809 **Q**1 **51S**678294

BTN

An important component of the BIC is the Beckhoff Traceability Number (BTN, item no. 2). The BTN is a unique 8-character serial number that will replace all other serial number systems at Beckhoff in the future (e.g. batch designations on IO components, previous serial number circle for safety products, etc.). The BTN is also being introduced gradually, so it may not yet be coded in the BIC.

NOTICE

This information has been carefully prepared. However, the method described is constantly being refined. We reserve the right to revise and change procedures and documentation at any time and without notice. No claims for modification may be made on the basis of the data, diagrams, and descriptions in this documentation.

7.3.4 Electronic access to the BIC (eBIC)

Electronic BIC (eBIC)

The Beckhoff Identification Code (BIC) is applied to the outside of Beckhoff products in a visible place. If possible, it should also be electronically readable.

The interface that the product can be electronically addressed by is crucial for the electronic readout.

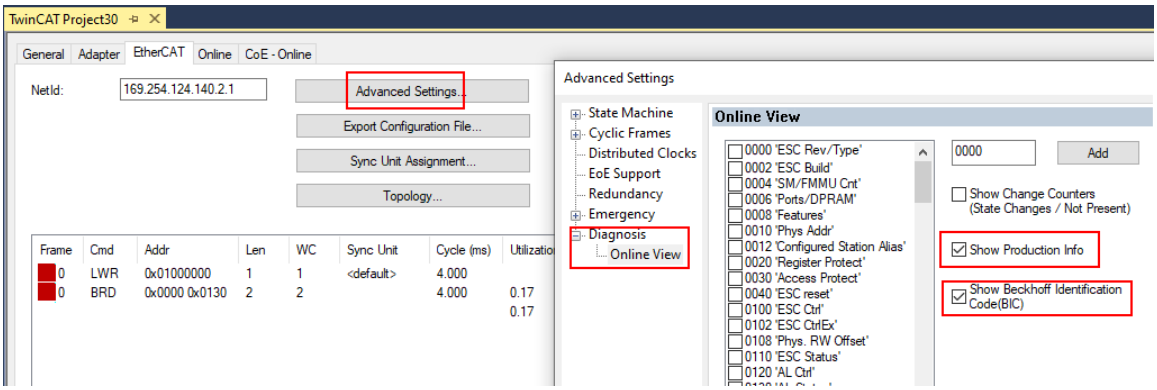
EtherCAT devices (IP20, IP67)

All Beckhoff EtherCAT devices have an ESI-EEPROM which contains the EtherCAT identity with the revision number. The EtherCAT slave information, also colloquially known as the ESI/XML configuration file for the EtherCAT master, is stored in it. See the corresponding chapter in the EtherCAT system manual (Link) for the relationships.

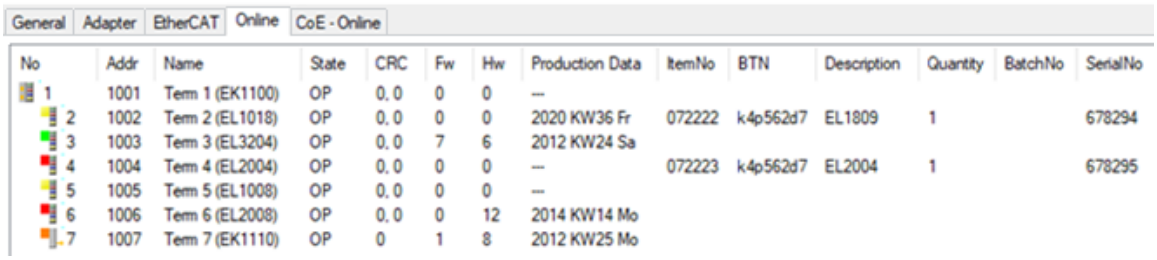
Beckhoff also writes the eBIC in the ESI-EEPROM. The eBIC was introduced into Beckhoff IO production (terminals, box modules) in 2020; as of 2023, implementation is largely complete.

The user can electronically access the eBIC (if present) as follows:

- With all EtherCAT devices, the EtherCAT master (TwinCAT) can read the eBIC from the ESI-EEPROM:
  - From TwinCAT 3.1 build 4024.11, the eBIC can be displayed in the online view.
  - To do this, check the “Show Beckhoff Identification Code (BIC)” checkbox under EtherCAT → Advanced Settings → Diagnostics:

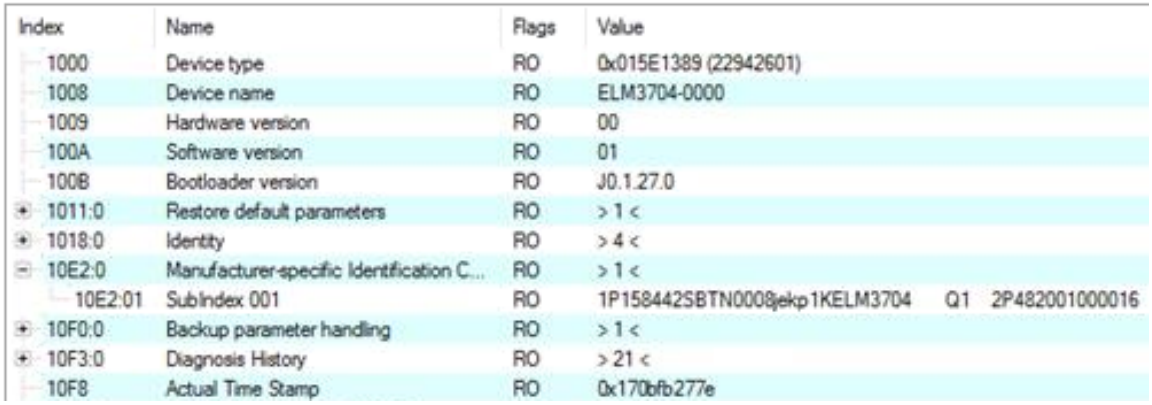


  - The BTN and its contents are then displayed:



  - Note: As shown in the figure, the production data HW version, FW version, and production date, which have been programmed since 2012, can also be displayed with “Show production info”.
  - Access from the PLC: From TwinCAT 3.1. build 4024.24, the functions *FB_EcReadBIC* and *FB_EcReadBTN* for reading into the PLC are available in the Tc2_EtherCAT library from v3.3.19.0.
- EtherCAT devices with a CoE directory may also have the object 0x10E2:01 to display their own eBIC, which can also be easily accessed by the PLC:

- The device must be in PREOP/SAFEOP/OP for access



Index	Name	Flags	Value
1000	Device type	RO	0x015E1389 (22942601)
1008	Device name	RO	ELM3704-0000
1009	Hardware version	RO	00
100A	Software version	RO	01
100B	Bootloader version	RO	J0.1.27.0
1011:0	Restore default parameters	RO	> 1 <
1018:0	Identity	RO	> 4 <
10E2:0	Manufacturer-specific Identification C...	RO	> 1 <
10E2:01	SubIndex 001	RO	1P158442SBTN0008jekp1KELM3704 Q1 2P482001000016
10F0:0	Backup parameter handling	RO	> 1 <
10F3:0	Diagnosis History	RO	> 21 <
10F8	Actual Time Stamp	RO	0x170bfb277e

- The object 0x10E2 will be preferentially introduced into stock products in the course of necessary firmware revision.
- From TwinCAT 3.1. build 4024.24, the functions *FB_EcCoEReadBIC* and *FB_EcCoEReadBTN* for reading into the PLC are available in the Tc2_EtherCAT library from v3.3.19.0

- The following auxiliary functions are available for processing the BIC/BTN data in the PLC in *Tc2_Utilities* as of TwinCAT 3.1 build 4024.24
  - F_SplitBIC: The function splits the BIC sBICValue into its components using known identifiers and returns the recognized substrings in the ST_SplittedBIC structure as a return value
  - BIC_TO_BTN: The function extracts the BTN from the BIC and returns it as a return value
- Note: If there is further electronic processing, the BTN is to be handled as a string(8); the identifier “SBTN” is not part of the BTN.
- On the technical background:
  The new BIC information is written as an additional category in the ESI-EEPROM during device production. The structure of the ESI content is largely dictated by the ETG specifications, therefore the additional vendor-specific content is stored using a category in accordance with the ETG.2010. ID 03 tells all EtherCAT masters that they may not overwrite these data in the event of an update or restore the data after an ESI update.
  The structure follows the content of the BIC, see here. The EEPROM therefore requires approx. 50… 200 bytes of memory.
- Special cases
  - In a hierarchical configuration of multiple ESCs (EtherCAT Slave Controllers) within a single device, only the top-level ESC carries the eBIC information.
  - If multiple non-hierarchically arranged ESCs are installed in a device, all ESCs carry the eBIC information.
  - If the device consists of several sub-devices which each have their own identity, but only the top-level device is accessible via EtherCAT, the eBIC of that ESC is located in the CoE object directory 0x10E2:01 and the eBICs of the sub-devices follow in 0x10E2:nn.

7.4 Support and Service

Beckhoff Support and Service provides assistance with questions regarding Beckhoff products and system solutions, as well as with their planning, commissioning, and operation.

Beckhoff subsidiaries and representative offices

Please contact your Beckhoff subsidiary or your representative office for local support and service for Beckhoff products. You can find the addresses of Beckhoff subsidiaries and representative offices at: www.beckhoff.com/worldwide.

For Beckhoff products and technologies, we offer Training programs, tutorials, and webinars.

Beckhoff Support

Beckhoff Support provides assistance with technical questions regarding the use, planning, programming, and commissioning of Beckhoff products.

☎ Hotline:	+49 5246 963-157
✉ Email:	support@beckhoff.com, Support form
Web page:	www.beckhoff.com/support

Beckhoff Service

Our service specialists are here to assist you with any questions you may have regarding after-sales service processes, such as replacement parts, repairs, etc.

☎ Hotline:	+49 5246 963-460
✉ Email:	service@beckhoff.com, Service form
Web page:	www.beckhoff.com/service

Download finder

The Download finder serves as a central source for downloadable documents and files related to Beckhoff products, such as application reports, technical documentation, drawings, and configuration files.

Beckhoff Information System

The Beckhoff Information System is the central online documentation resource for Beckhoff products and contains documentation on products and automation topics, as well as sample code.

Beckhoff Headquarters

Beckhoff Automation GmbH & Co. KG
Hülshorstweg 20
33415 Verl, Germany

☎ Phone:	+49 5246 963-0
✉ Email:	info@beckhoff.com
Web page:	www.beckhoff.com

Trademark statements

Beckhoff®, ATRO®, EtherCAT®, EtherCAT G®, EtherCAT G10®, EtherCAT P®, MX-System®, Safety over EtherCAT®, TC/BSD®, TwinCAT®, TwinCAT/BSD®, TwinSAFE®, XFC®, XPlanar® and XTS® are registered and licensed trademarks of Beckhoff Automation GmbH.

More Information:
www.beckhoff.com/ep9224-0037

Beckhoff Automation GmbH & Co. KG
Hülshorstweg 20
33415 Verl
Germany
Phone: +49 5246 9630
info@beckhoff.com
www.beckhoff.com