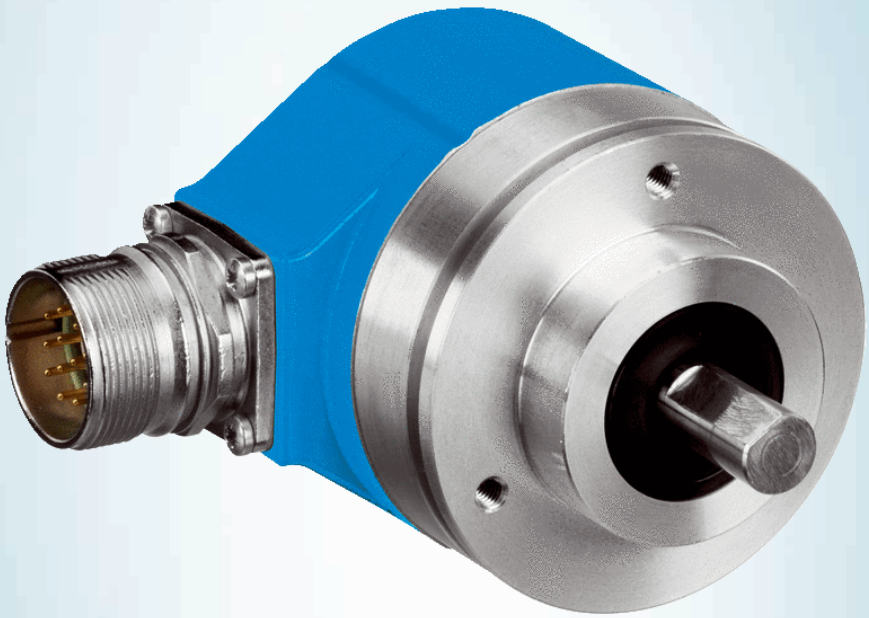
Product data sheet



ARS60-F4A00018

ARS60 SSI/Parallel

ABSOLUTE ENCODERS

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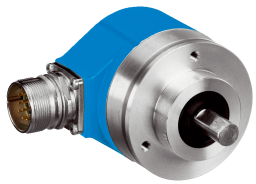


Illustration may differ

Ordering information

Type	Part no.
ARS60-F4A00018	1035186

Other models and accessories ➜ www.sick.com/ARS60_SSI_Parallel

Detailed technical data

Performance

Number of steps per revolution (max. resolution)	18 Any number of steps from 00002 to 32768 possible. Always 5 characters in cleartext.
Error limits G	0.035° (binary number of steps) [1] 0.046° (non-binary number of steps)
Repeatability standard deviation σ_r	0.005° [2]

[1] In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.
[2] In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

Interfaces

Communication interface	Parallel data world
Initialization time	80 ms [1]
SSI	
Code type	Gray
Code sequence parameter adjustable	CW (clockwise) increasing when viewing the clockwise rotating shaft Increasing, when turning the shaft For clockwise rotation, looking in direction “A” (see dimensional drawing)

[1] Valid positional data can be read once this time has elapsed.

Electrical data

Connection type	Male connector, M23, 21-pin, radial
Supply voltage	10 ... 32 V DC
Reverse polarity protection	✓
Short-circuit protection	✓
MTTFd: mean time to dangerous failure	300 years (EN ISO 13849-1) [1]

[1] This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Mechanical data

Mechanical design	Solid shaft, face mount flange
Shaft length	18 mm

Shaft diameter	10 mm
Weight	0.3 kg
Housing material	Aluminum die cast
Start up torque	0.4 Ncm
Operating torque	0.3 Ncm
Permissible Load capacity of shaft	20 N / radial 10 N / axial
Moment of inertia of the rotor	54 gcm²
Bearing lifetime	3.6 x 10^9 revolutions
Angular acceleration	≤ 500,000 rad/s²

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3 [1)]
Enclosure rating	IP65, with mating connector fitted (according to IEC 60529)
Permissible relative humidity	90 % (condensation of the optical scanning not permitted)
Operating temperature range	–20 °C ... +85 °C
Storage temperature range	–40 °C ... +100 °C
Resistance to shocks	50 g, 11 ms (according to EN 60068-2-27)
Resistance to vibration	20 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

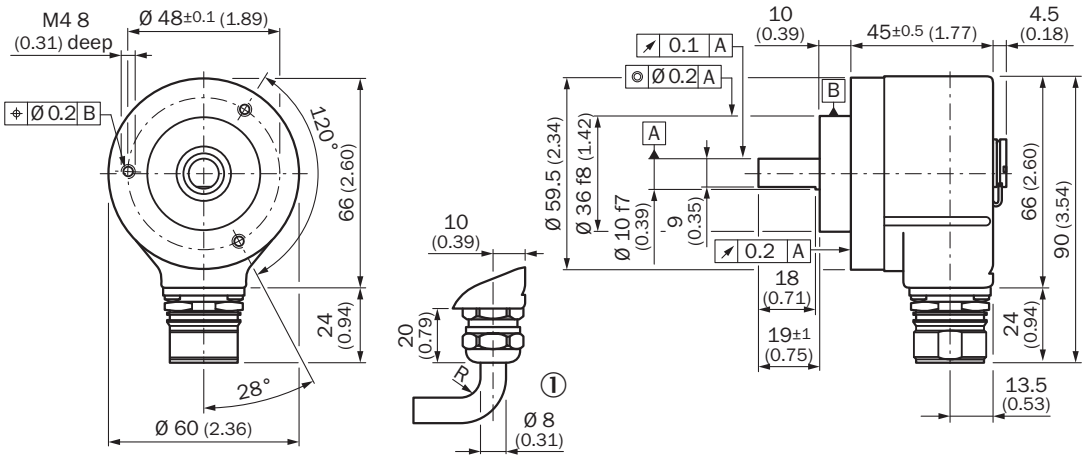
[1)] EMC according to the standards quoted is achieved if shielded cables are used.

Classifications

ECl@ss 5.0	27270502
ECl@ss 5.1.4	27270502
ECl@ss 6.0	27270590
ECl@ss 6.2	27270590
ECl@ss 7.0	27270502
ECl@ss 8.0	27270502
ECl@ss 8.1	27270502
ECl@ss 9.0	27270502
ETIM 5.0	EC001486
ETIM 6.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

Face mount flange, radial plug connection M12 and M23



General tolerances according to DIN ISO 2768-mk

① R = min. bending radius 40 mm

PIN assignment

- Allocation for encoder with 21-pin connector Single; Parallel Interface

PIN	Wire color by cable outlet	Binary	Gray	BCD	Description
1	Lilac	2^0	G_0	2^0 v.10^0	Data lines, outputs
2	White/brown	2^1	G_1	2^1 v.10^0	
3	White/green	2^2	G_2	2^2 v.10^0	
4	White/yellow	2^3	G_3	2^3 v.10^0	
5	White/gray	2^4	G_4	2^0 v.10^1	
6	White/pink	2^5	G_5	2^1 v.10^1	
7	White/blue	2^6	G_6	2^2 v.10^1	
8	White/red	2^7	G_7	2^3 v.10^1	
9	White/black	2^8	G_8	2^0 v.10^2	
10	Brown/green	2^9	G_9	2^1 v.10^2	
11	Brown/yellow	2^{10}	G_{10}	2^2 v.10^2	
12	Brown/gray	2^{11}	G_{11}	2^3 v.10^2	
13	Brown/pink	2^{12}	G_{12}	2^0 v.10^3	
14	Brown/blue	2^{13}	G_{13}	2^1 v.10^3	
15	Brown/red	2^{14}	G_{14}	2^2 v.10^3	
16	Green	Parity	Parity	Parity	
17	Pink	Store_	Store_	Store_	
18	Yellow	Enable_	Enable_	Enable_	
19	Brown	V/R_	V/R_	V/R_	
1)	Gray	SET	SET	SET	
20	Blue	GND	GND	GND	
21	Red	U_s	U_s	U_s	
Housing		Screen	Screen	Screen	

1) Set line only possible with a cable outlet.

U_s Supply voltage to the encoder (before commissioning, note must be taken of the type label of the encoder).

GND Zero volt connection to the encoder; electrically isolated from the housing. The voltage referred to GND is U_s.

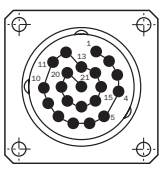
V/R_ Forward/reverse: this input programs the counting direction of the encoder. If not connected, this input is «high». If the encoder shaft, as viewed on the drive shaft, rotates in the clockwise direction, it counts in an increasing sequence. If it should count upwards when the shaft rotates in the anti-clockwise direction, this connection must be connected permanently to «low» level (zero volts).

Enable_ This input activates the data output driver when a «low» level is applied. If not connected, this input is «low». In the case of a «high» level, the outputs are in the tristate mode.

Store_ This input stores the encoder data in Gray code when a «low» level is applied. This avoids a read error if the output data is requested in binary code. If this input is «low», the data at the encoder output is stable, irrespective of whether the input shaft rotates. If not switched, this input is «high».

Parity This output supplies a «high» level when the binary checksum of the data bits is even.

SET This input serves to set the zero electronically. If the SET line is connected to Us for more than 100 ms, the mechanical position corresponds to the value 0.



View of the connector M23 fitted to the encoder body Single, Parallel

Recommended accessories

Other models and accessories ➜ www.sick.com/ARS60_SSI_Parallel

	Brief description	Type	Part no.
Flanges			
	Flange adapter, adaptation of face mount flange with 36 mm centering hub to 50 mm servo flange, aluminum, including 3 flat head screws M4 x 10, Aluminum, including 3 countersunk screws M4 x 10	BEF-FA-036-050	2029160
	Flange adapter, adaptation of face mount flange with 36 mm centering hub to 60 mm square mounting plate, aluminum, including 3 flat head screws M4 x 8, Aluminum, including 3 countersunk screws M4 x 8	BEF-FA-036-060REC	2029162
	Flange adapter, adaptation of face mount flange with 36 mm centering hub to 58 mm square mounting plate with shock absorbers, aluminum, Aluminum	BEF-FA-036-060RSA	2029163
	Flange adapter, adaptation of face mount flange with 36 mm centering hub to 100 mm servo flange with 60 mm centering hub, aluminum, Aluminum	BEF-FA-036-100	2029161
Mounting brackets and plates			
	Mounting bracket for encoder with spigot 36 mm for face mount flange, mounting kit included	BEF-WF-36	2029164
Shaft adaptation			
	Bellows coupling, shaft diameter 6 mm / 10 mm, maximum shaft offset: radial ± 0.25 mm, axial ± 0.4 mm, angular +/- 4°; max. speed 10,000 rpm, –30 °C to +120 °C, max. torque 80 Ncm; material: stainless steel bellows, aluminum hub	KUP-0610-B	5312982
	Spring washer coupling, shaft diameter 6 mm / 10 mm, Maximum shaft offset: radial +/- 0.3 mm, axial +/- 0.4 mm, angular +/- 2.5°; max. speed 12,000 rpm, –10° to +80 °C, max. torque 60 Ncm; material: aluminum flange, glass fiber-reinforced polyamide membrane and hardened steel coupling pin	KUP-0610-F	5312985
	Bellows coupling, shaft diameter 10 mm/10 mm; maximum shaft offset: radial +/- 0.25 mm, axial +/- 0.4 mm, angular +/- 4°; max. revolutions 10,000 rpm, –30° to +120 °C, max. torque 80 Ncm; material: stainless steel bellows, aluminum clamping hubs	KUP-1010-B	5312983
	Spring washer coupling, shaft diameter 10 mm / 10 mm, maximum shaft offset, radial ± 0.3 mm, axial ± 0.4 mm, angle ± 2.5°, torsion spring stiffness 30 Nm/rad; material: aluminum flange, glass-fiber reinforced polyamide membrane and hardened steel coupling pin	KUP-1010-F	5312986
	10 mm / 12 mm; maximum shaft offset: radial +/- 0.25 mm, axial +/- 0.4 mm, angular +/- 4°; max. revolutions 10,000 rpm, –30° to +120 °C, max. torque 80 Ncm; material: stainless steel bellows, aluminum clamping hubs	KUP-1012-B	5312984

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