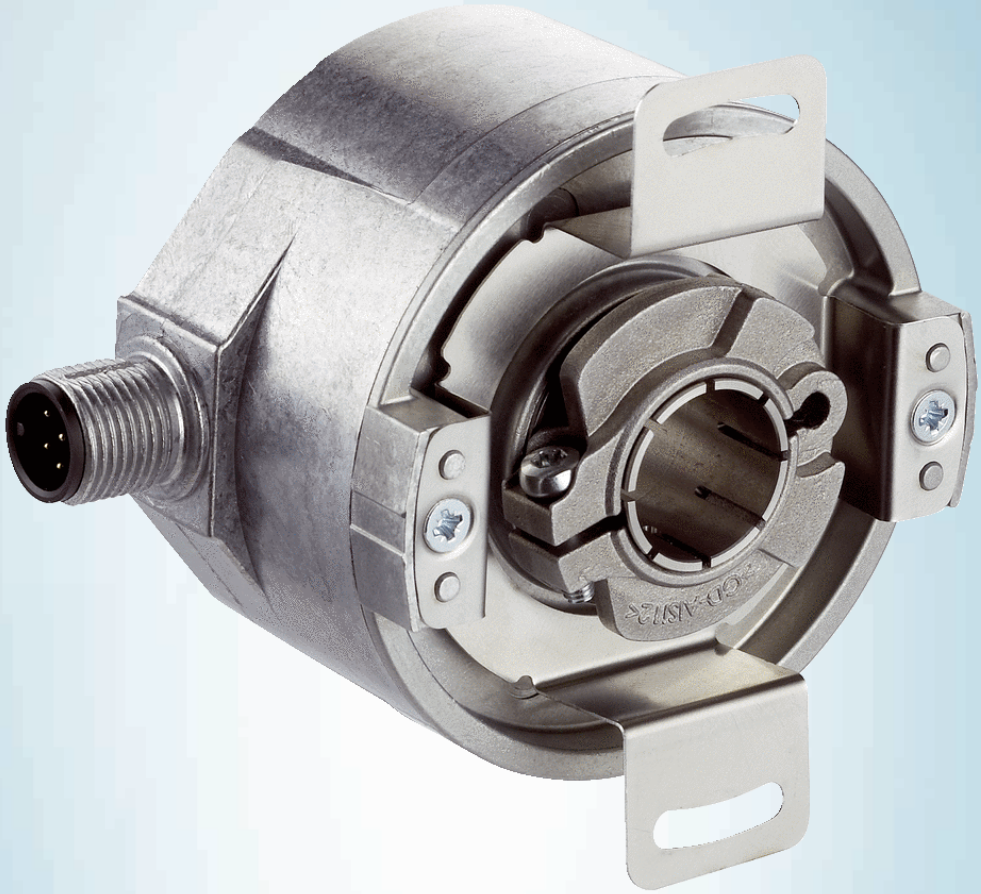
Product data sheet



DFS60B-TGPC10000

DFS60

INCREMENTAL ENCODERS

SICK
Sensor Intelligence.

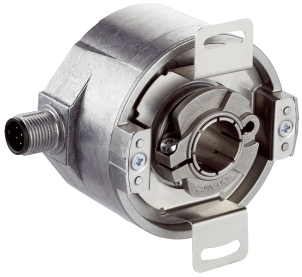


Illustration may differ

Ordering information

Type	Part no.
DFS60B-TGPC10000	1036918

Other models and accessories ➜ www.sick.com/DFS60

Detailed technical data

Performance

Pulses per revolution	10,000 [1]
Measuring step	90° electronically/ppr
Measuring step deviation at non binary number of lines	± 0.01°
Error limits	± 0.05°

[1] See maximum revolution range.

Interfaces

Communication interface	Incremental
Communication Interface detail	TTL / HTL
Factory setting	Factory setting: output level TTL
Number of signal channels	6-channel
Programmable/configurable	✓
Initialization time	32 ms [1] 30 ms
Output frequency	≤ 600 kHz
Load current	≤ 30 mA
Power consumption	≤ 0.7 W (without load)

[1] With mechanical zero pulse width.

Electrical data

Connection type	Male connector, M12, 8-pin, radial
Supply voltage	4.5 ... 32 V
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B
Reverse polarity protection	✓

[1] Programming TTL with ≥ 5.5 V: short-circuit opposite to another channel or GND permissable for maximum 30 s.

[2] This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Short-circuit protection of the outputs	✓ [1]
MTTFd: mean time to dangerous failure	300 years (EN ISO 13849-1) [2]

[1] Programming TTL with ≥ 5.5 V: short-circuit opposite to another channel or GND permissable for maximum 30 s.

[2] This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Mechanical data

Mechanical design	Through hollow shaft
Shaft diameter	14 mm
Weight	+ 0.2 kg
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum die cast
Start up torque	0.8 Ncm (+20 °C)
Operating torque	0.6 Ncm (+20 °C)
Permissible shaft movement, axial static/dynamic	± 0.5 mm / ± 0.2 mm
Permissible shaft movement, radial static/dynamic	± 0.3 mm / ± 0.1 mm
Operating speed	≤ 6,000 min^{-1} [1]
Moment of inertia of the rotor	40 gcm^2
Bearing lifetime	3.6 x 10^10 revolutions
Angular acceleration	≤ 500,000 rad/s^2

[1] Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP65, housing side, male connector connection (according to IEC 60529) [1] IP65, shaft side (according to IEC 60529)
Permissible relative humidity	90 % (condensation of the optical scanning not permitted)
Operating temperature range	–40 °C ... +100 °C [2] –30 °C ... +100 °C [3]
Storage temperature range	–40 °C ... +100 °C, without package
Resistance to shocks	70 g, 6 ms (according to EN 60068-2-27)
Resistance to vibration	30 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

[1] With mating connector fitted.

[2] Stationary position of the cable.

[3] Flexible position of the cable.

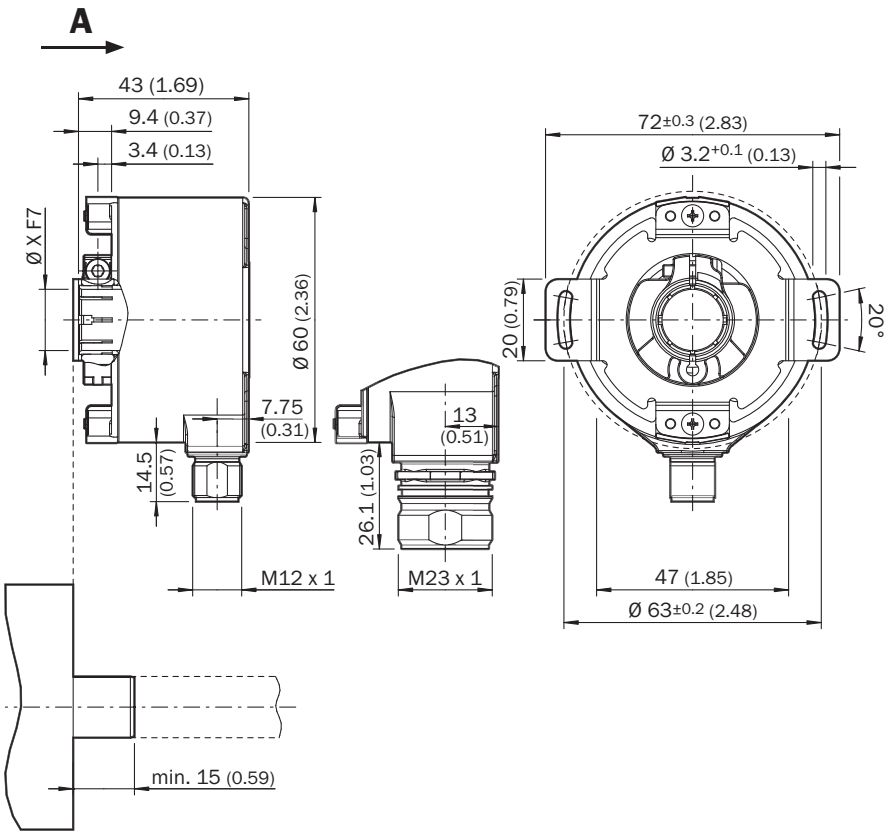
Classifications

ECl@ss 5.0	27270501
ECl@ss 5.1.4	27270501
ECl@ss 6.0	27270590
ECl@ss 6.2	27270590
ECl@ss 7.0	27270501

ECl@ss 8.0	27270501
ECl@ss 8.1	27270501
ECl@ss 9.0	27270501
ECl@ss 10.0	27270501
ECl@ss 11.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

Through hollow shaft, radial plug connection M12 and M23



General tolerances according to DIN ISO 2768-mk

① Cable diameter = 5.6 mm +/- 0.2 mm bend radius = 30 mm

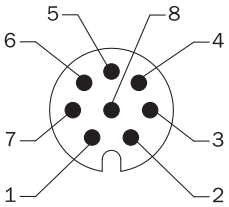
Type Through hollow shaft	Shaft diameter XF7	Shaft diameter xj7
DFS60x-TAxxxxxxxx	6 mm	Provided by customer
DFS60x-TBxxxxxxxx	8 mm	
DFS60x-TCxxxxxxxx	3/8"	
DFS60x-TDxxxxxxxx	10 mm	
DFS60x-TExxxxxxxx	12 mm	

Type Through hollow shaft	Shaft diameter XF7	Shaft diameter xj7
DFS60x-TFxxxxxxxx	1/2″	
DFS60x-TGxxxxxxxx	14 mm	
DFS60x-THxxxxxxxx	15 mm	
DFS60x-TJxxxxxxxx	5/8″	

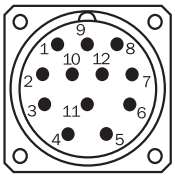
PIN assignment

Cable, 8-wire

View of M12 male device connector on encoder



View of M23 male device connector on encoder

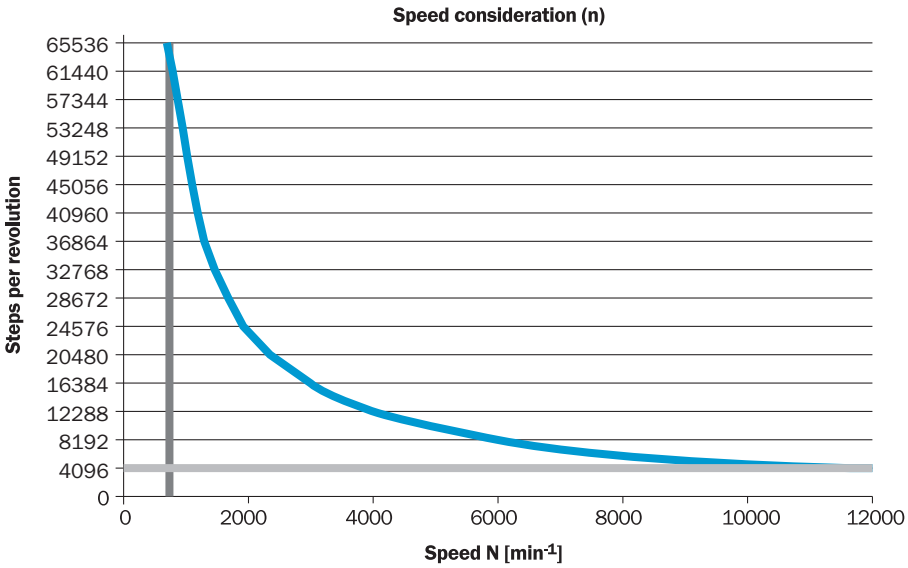


PIN, 8-pin, M12 male connector	PIN, 12-pin, M23 male connector	Color of the wires for encoders with cable outlet	TTL/HTL signal	Sin/cos 1.0 V_{ss}	Explanation
1	6	Brown	$\overline{A}$	COS–	Signal wire
2	5	White	A	COS+	Signal wire
3	1	Black	$\overline{B}$	SIN–	Signal wire
4	8	Pink	B	SIN+	Signal wire
5	4	Yellow	$\overline{Z}$	$\overline{Z}$	Signal wire
6	3	Violet	Z	Z	Signal wire
7	10	Blue	GND	GND	Ground connection of the encoder
8	12	Red	$+U_S$	$+U_S$	Supply voltage (volt-free to housing)
–	9	–	n.c.	n.c.	Not assigned
–	2	–	n.c.	n.c.	Not assigned
–	11	–	n.c.	n.c.	Not assigned
–	7 [1]	–	0-SET [1]	n.c.	Set zero pulse [1]
Screen	Screen	Screen	Screen	Screen	Screen connected to housing on encoder side. Connected to ground on control side.

[1] For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 male connector. The 0-SET input is used to set the zero pulse on the current shaft position. If the 0-SET input is connected to U_S for longer than 250 ms after it had previously been unassigned for at least 1,000 ms or had been connected to the GND, the current position of the shaft is assigned to the zero pulse signal “Z”.

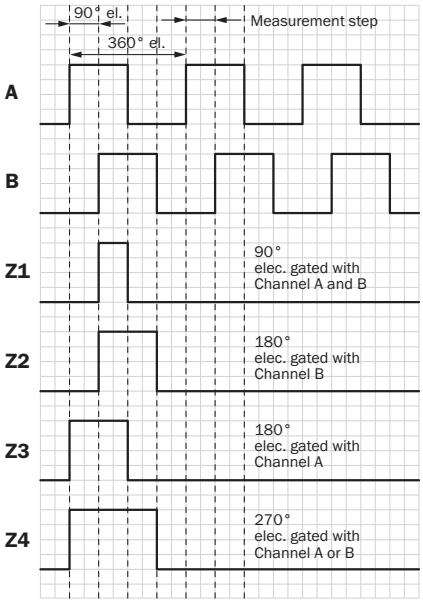
Maximum revolution range

Maximum revolution range



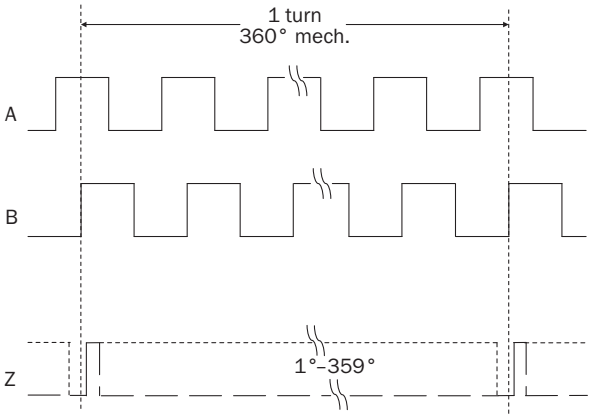
Diagrams

Electrical zero pulse width can be configured to 90°, 180°, or 270°. Width of the zero pulse in relation to a pulse period.



Cw with view on the encoder shaft in direction "A", compare dimensional drawing.

Mechanical zero pulse width 1° to 359° programmable. Width of the zero pulse in relation to a mechanical revolution of the shaft.



Recommended accessories

Other models and accessories ➜ www.sick.com/DFS60

	Brief description	Type	Part no.
Flanges			
	Standard stator coupling	BEF-DS00XFX	2056812
Other mounting accessories			
	Clamping ring for metal hollow shaft, metal	BEF-KR-M	2064709
Plug connectors and cables			
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: PUR, halogen-free, shielded, 2 m	DOL-1208-G02MAC1	6032866
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: PUR, halogen-free, shielded, 5 m	DOL-1208-G05MAC1	6032867
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: PUR, halogen-free, shielded, 10 m	DOL-1208-G10MAC1	6032868
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: PUR, halogen-free, shielded, 20 m	DOL-1208-G20MAC1	6032869
	Head A: female connector, M12, 8-pin, straight Head B: male connector, D-Sub, 9-pin, straight Cable: Incremental, shielded, 0.5 m Programming adapter cable for programming tool PGT-10-Pro and PGT-08-S	DSL-2D08-G0M5AC3	2046579
	Head A: female connector, M12, 8-pin, straight, A-coded Head B: - Cable: Incremental, SSI, shielded	DOS-1208-GA01	6045001

	Brief description	Type	Part no.
Programming and configuration tools			
	USB programming unit, for programmable SICK encoders AFS60, AFM60, DFS60, VFS60, DFV60 and wire draw encoders with programmable encoders	PGT-08-S	1036616
	Programming unit display for programmable SICK DFS60, DFV60, AFS/AFM60, AHS/AHM36 encoders, and wire draw encoder with DFS60, AFS/AFM60 and AHS/AHM36. Compact dimensions, low weight, and intuitive operation.	PGT-10-Pro	1072254

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