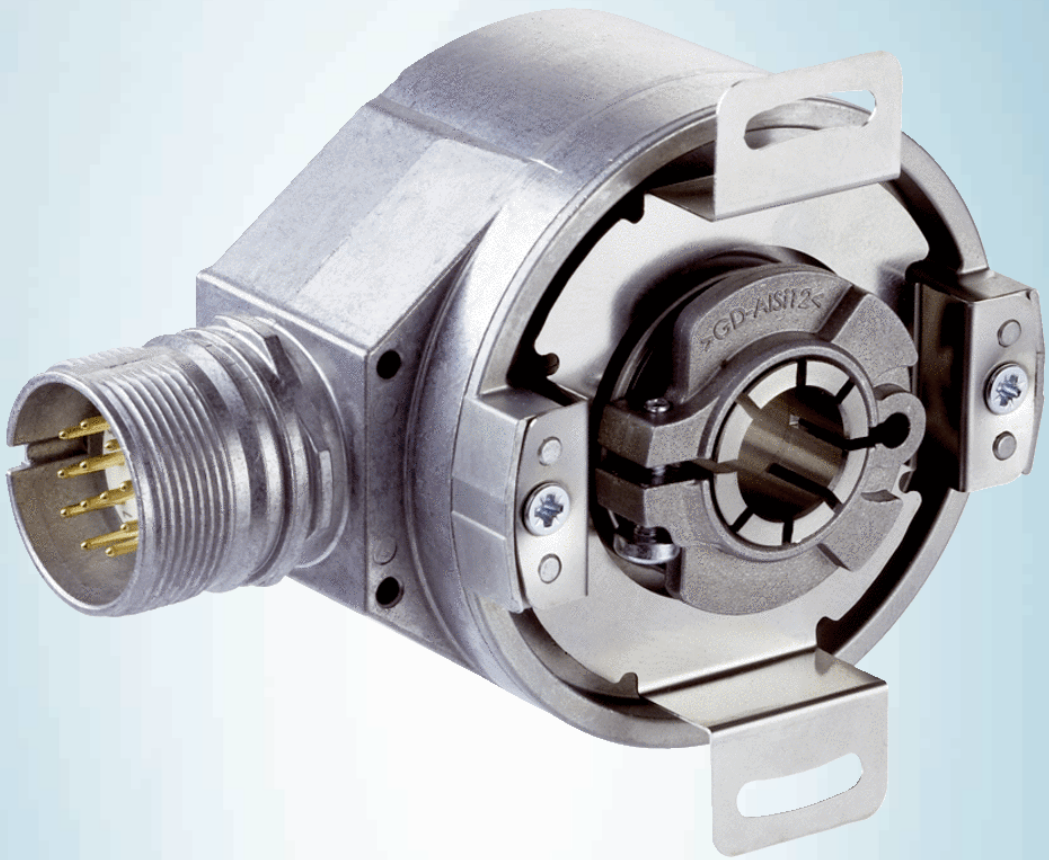
Product data sheet



DFS60E-TEEA00100

DFS60

INCREMENTAL ENCODERS

SICK
Sensor Intelligence.

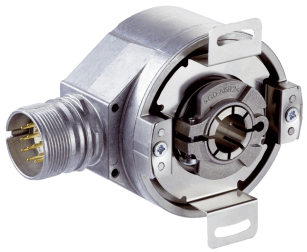


Illustration may differ

Ordering information

Type	Part no.
DFS60E-TEEA00100	1038106

Other models and accessories ➜ www.sick.com/DFS60

Detailed technical data

Performance

Pulses per revolution	100 [1]
Measuring step	90° electronically/ppr
Measuring step deviation at non binary number of lines	± 0.2°
Error limits	± 0.3°

[1] See maximum revolution range.

Interfaces

Communication interface	Incremental
Communication Interface detail	HTL / Push pull
Number of signal channels	6-channel
Initialization time	40 ms
Output frequency	≤ 300 kHz
Load current	≤ 30 mA
Power consumption	≤ 0.5 W (without load)

Electrical data

Connection type	Male connector, M23, 12-pin, radial
Supply voltage	10 ... 32 V
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B
Reverse polarity protection	✓
Short-circuit protection of the outputs	✓ [1]
MTTFd: mean time to dangerous failure	300 years (EN ISO 13849-1) [2]

[1] Short-circuit opposite to another channel, US or GND permissable for maximum 30 s.

[2] This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Mechanical data

Mechanical design	Through hollow shaft
Shaft diameter	12 mm
Weight	+ 0.2 kg
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum die cast
Start up torque	0.8 Ncm (+20 °C)
Operating torque	0.6 Ncm (+20 °C)
Permissible shaft movement, axial static/dynamic	± 0.5 mm / ± 0.2 mm
Permissible shaft movement, radial static/dynamic	± 0.3 mm / ± 0.1 mm
Operating speed	≤ 6,000 min^{-1} [1]
Moment of inertia of the rotor	40 gcm^2
Bearing lifetime	3.6 x 10^10 revolutions
Angular acceleration	≤ 500,000 rad/s^2

[1] Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-4
Enclosure rating	IP65, housing side, male connector connection (according to IEC 60529) [1] IP65, shaft side (according to IEC 60529)
Permissible relative humidity	90 % (condensation of the optical scanning not permitted)
Operating temperature range	0 °C ... +85 °C
Storage temperature range	–40 °C ... +100 °C, without package
Resistance to shocks	50 g, 6 ms (according to EN 60068-2-27)
Resistance to vibration	20 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

[1] With mating connector fitted.

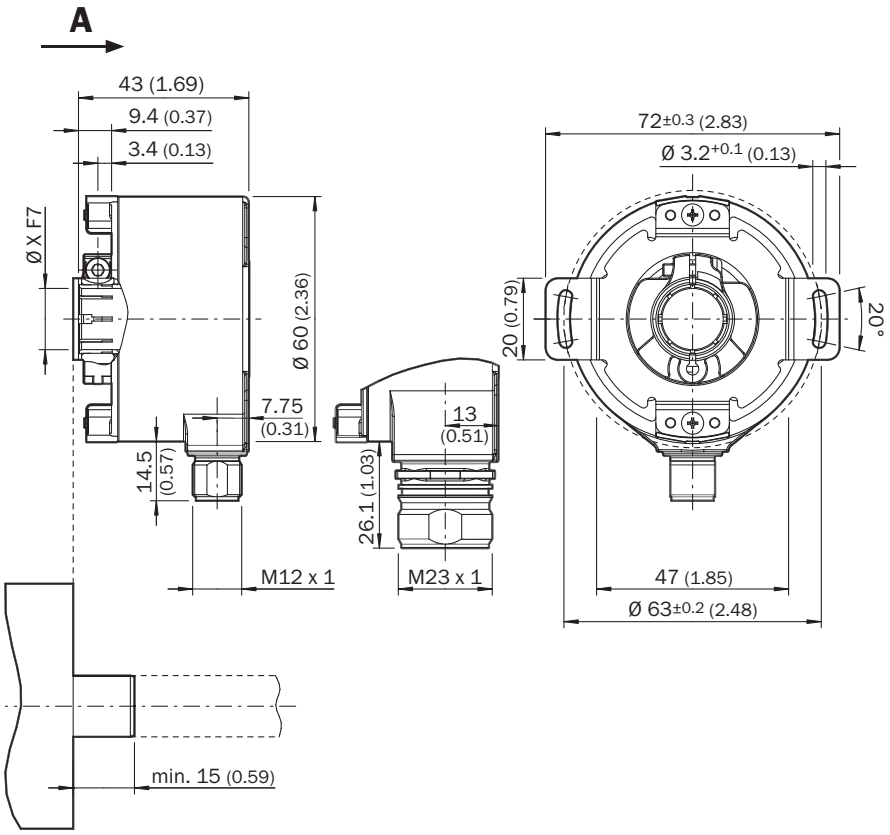
Classifications

ECl@ss 5.0	27270501
ECl@ss 5.1.4	27270501
ECl@ss 6.0	27270590
ECl@ss 6.2	27270590
ECl@ss 7.0	27270501
ECl@ss 8.0	27270501
ECl@ss 8.1	27270501
ECl@ss 9.0	27270501
ECl@ss 10.0	27270501
ECl@ss 11.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486

ETIM 7.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

Through hollow shaft, radial plug connection M12 and M23



General tolerances according to DIN ISO 2768-mk

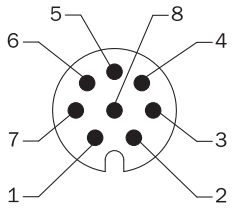
① Cable diameter = 5.6 mm +/- 0.2 mm bend radius = 30 mm

Type Through hollow shaft	Shaft diameter XF7	Shaft diameter xj7
DFS60x-TAxxxxxxxx	6 mm	Provided by customer
DFS60x-TBxxxxxxxx	8 mm	
DFS60x-TCxxxxxxxx	3/8"	
DFS60x-TDxxxxxxxx	10 mm	
DFS60x-TExxxxxxxx	12 mm	
DFS60x-TFxxxxxxxx	1/2″	
DFS60x-TGxxxxxxxx	14 mm	
DFS60x-THxxxxxxxx	15 mm	
DFS60x-TJxxxxxxxx	5/8″	

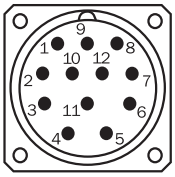
PIN assignment

Cable, 8-wire

View of M12 male device connector on encoder



View of M23 male device connector on encoder

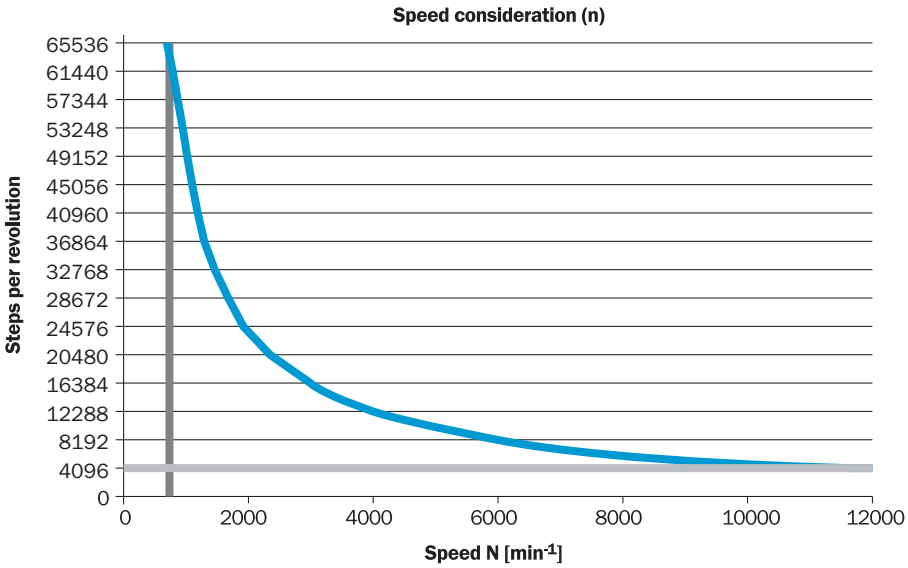


PIN, 8-pin, M12 male connector	PIN, 12-pin, M23 male connector	Color of the wires for encoders with cable outlet	TTL/HTL signal	Sin/cos 1.0 V_{ss}	Explanation
1	6	Brown	$\overline{A}$	COS–	Signal wire
2	5	White	A	COS+	Signal wire
3	1	Black	$\overline{B}$	SIN–	Signal wire
4	8	Pink	B	SIN+	Signal wire
5	4	Yellow	$\overline{Z}$	$\overline{Z}$	Signal wire
6	3	Violet	Z	Z	Signal wire
7	10	Blue	GND	GND	Ground connection of the encoder
8	12	Red	$+U_S$	$+U_S$	Supply voltage (volt-free to housing)
–	9	–	n.c.	n.c.	Not assigned
–	2	–	n.c.	n.c.	Not assigned
–	11	–	n.c.	n.c.	Not assigned
–	7 [1]	–	0-SET [1]	n.c.	Set zero pulse [1]
Screen	Screen	Screen	Screen	Screen	Screen connected to housing on encoder side. Connected to ground on control side.

[1] For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 male connector. The 0-SET input is used to set the zero pulse on the current shaft position. If the 0-SET input is connected to U_S for longer than 250 ms after it had previously been unassigned for at least 1,000 ms or had been connected to the GND, the current position of the shaft is assigned to the zero pulse signal “Z”.

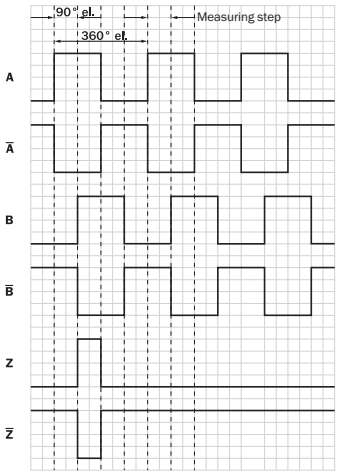
Maximum revolution range

Maximum revolution range



Signal outputs

Signal outputs



CW with view on the encoder shaft in direction “A”, compare dimensional drawing.

Supply voltage	Output
4,5 V ... 5,5 V	TTL
10 V ... 32 V	TTL
10 V ... 32 V	HTL

Recommended accessories

Other models and accessories ➜ www.sick.com/DFS60

	Brief description	Type	Part no.
Flanges			
	Standard stator coupling	BEF-DS00XFX	2056812
Other mounting accessories			
	Bearing bracket for hollow shaft encoders, fastening screws included the Bearing Block is intended for very large radial and axial shaft loads. Particularly for application on: Belt pulleys, Chain pinions, Friction wheels. It is designed this way to enable fitting of encoder with blind hollow shaft with ø 12 mm., fastening screws included	BEF-FA-B12-010	2042728
	Clamping ring for metal hollow shaft, metal	BEF-KR-M	2064709
Plug connectors and cables			
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: Incremental, PUR, shielded, 2 m	DOL-2312-G02MLA3	2030682
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: Incremental, PUR, halogen-free, shielded, 3 m	DOL-2312-G03MMA3	2029213
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: Incremental, PUR, halogen-free, shielded, 5 m	DOL-2312-G05MMA3	2029214
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: Incremental, PUR, shielded, 7 m	DOL-2312-G07MLA3	2030685
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: Incremental, PUR, shielded, 10 m	DOL-2312-G10MLA3	2030688
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: Incremental, PUR, halogen-free, shielded, 10 m	DOL-2312-G10MMA3	2029215
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: Incremental, PUR, shielded, 15 m	DOL-2312-G15MLA3	2030692
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: Incremental, PUR, halogen-free, shielded, 1.5 m	DOL-2312-G1M5MA3	2029212
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: Incremental, PUR, shielded, 20 m	DOL-2312-G20MLA3	2030695
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: Incremental, PUR, halogen-free, shielded, 20 m	DOL-2312-G20MMA3	2029216
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: Incremental, PUR, shielded, 25 m	DOL-2312-G25MLA3	2030699
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: Incremental, PUR, shielded, 30 m	DOL-2312-G30MLA3	2030702
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: Incremental, PUR, halogen-free, shielded, 30 m	DOL-2312-G30MMA3	2029217

	Brief description	Type	Part no.
	Head A: female connector, M23, 12-pin, straight Head B: - Cable: HIPERFACE®, SSI, Incremental, shielded	DOS-2312-G02	2077057
	Head A: female connector, M23, 12-pin, angled Head B: - Cable: HIPERFACE®, SSI, Incremental, shielded	DOS-2312-W01	2072580

SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

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