

ONLINE DATA SHEET
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Absolute encoders
AFS/AFM60 SSI

AFS60E-THAA004096

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Absolute encoders
AFS/AFM60 SSI

Model Name	**> AFS60E-THAA004096**
Part No.	**> 1038210**



At a glance

- High-resolution absolute encoders with up to 30 bits (AFM60) or up to 18 bits (AFS60)
- Face mount flange, servo flange, blind or through hollow shaft
- SSI, SSI + Incremental or SSI + Sin/Cos interface
- Programmable resolution and offset (dependent on type)
- Connection system: M12, M23 connector or cable outlet
- Enclosure rating: IP 67 (housing), IP 65 (shaft)
- Operating temperature: -30 °C to +100 °C (depends on type)

Your benefits

- Programmability of the encoders means less storage, greater machine availability and easy installation
- Precise positioning due to high resolutions
- Large selection of mechanical interfaces and electrical contacting possibilities: Suitable for all applications
- Suitable for applications with limited space requirements (extremely short installation depth of 30 mm)
- Very good rotation accuracy due to increased bearing distance
- One programming tool and software with automatic encoder detection for AFS60/AFM60/DFS60

Performance

Max. number of steps per revolution:	4,096
Max. number of revolutions:	1
Resolution power:	4,096 x 1
Error limits:	± 0.3 °
Repeatability (Ta not constant):	0.002 °
Measuring step deviation:	± 0.2 °
Measuring step:	0.09 ° 360 °/number of steps
Initialization time:	50 ms [1)]

[1)] Valid positional data can be read once this time has elapsed

Mechanical data

Mechanical interface:	Through hollow shaft
Shaft diameter:	15 mm
Mass:	0.2 kg

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Start up torque:	0.8 Ncm (20 °C)
Operating torque:	0.6 Ncm (20 °C)
Maximum operating speed:	9,000 /min [1]
Moment of inertia of the rotor:	40 gcm²
Bearing lifetime:	3.0 x 10^9 revolutions
Max. angular acceleration:	500,000 rad/s²
Permissible movement axial static/dynamic:	± 0.5 mm, ± 0.2 mm
Permissible movement radial static/dynamic:	± 0.3 mm, ± 0.1 mm
Type of mounting shaft:	Through hollow shaft

[1] Self warming of 3.3 K per 1000 revolutions/min when applying note working temperature range

Electrical data

Power consumption:	0.5 W (without load)
Operating voltage range:	4.5 V DC ... 32 V DC
MTTFd: mean time to dangerous failure:	250 a (EN ISO 13849-1) [1]
Connection type:	Connector M23, 12-pin, radial
Code type:	Gray
Code sequence:	CW/CCW, parameter adjustable
Reverse polarity protection:	1

[1] This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Interfaces

Electrical interface:	SSI/Gray
Interface signals:	Clock +, Clock -, Data +, Data-
Clock frequency:	1 MHz [1]
SET (electronic adjustment):	H-active (L ≡ 0 - 1,5 V, H ≡ 2,0 - Us V)
CW/CCW (counting sequence when turning):	L-active (L ≡ 0 - 1,5 V, H ≡ 2,0 - Us V)

[1]

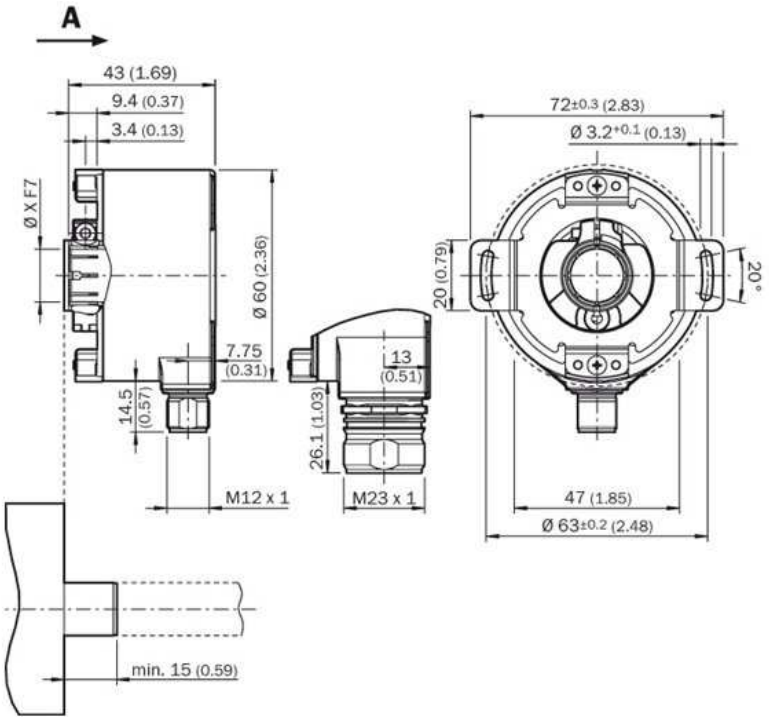
Ambient data

EMC:	(according to EN 61000-6-2 and EN 61000-6-3) [1]
Enclosure rating:	IP 65 (according to IEC 60529), housing side, IP 65 (according to IEC 60529), shaft side [2]
Permissible relative humidity:	90 % (condensation of the optical scanning not permitted)
Working temperature range:	0 °C ... 85 °C
Storage temperature range:	-40 °C ... 100 °C, without package
Resistance to shocks:	50 g, 6 ms (according to EN 60068-2-27)
Resistance to vibration:	20 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

[1] [2] With mating connector fitted

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Dimensional drawing



|1| Cable diameter = 5,6 mm
+/- 2 mmBending radius = 30 mm

PIN assignment

Connector M23, 12-pin
SSI/Gray

Pin	Signal	Explanation
1	GND	Ground connection
2	Data+	Interface signals
3	Clock+	Interface signals
4	N. C.	Not connected
5	N. C.	Not connected
6	N. C.	Not connected
7	N. C.	Not connected
8	$+U_V$	Supply voltage
9	SET	Electronic adjustment
10	Data-	Interface signals
11	Clock-	Interface signals
12	CW/$\overline{\text{CCW}}$	Counting sequence when turning
	Screen	Screen on the encoder side connected to the housing. On the control side connected to earth.

Connector M23, 12-pin and cable outlet, cable 12-core
SSI/Gray + Incremental

Pin	Color wires	Signal	Explanation
1	Red	$+U_V$	Supply voltage
2	Blue	GND	Ground connection
3	Yellow	Clock+	Interface signal
4	White	Data+	Interface signal
5	Orange	SET	Electronic adjustment
6	Brown	Data-	Interface signal
7	Violet	Clock-	Interface signal
8	Black	$\overline{\text{B}}$	Signal line
9	Orange/black	CW/$\overline{\text{CCW}}$	Counting sequence when turning
10	Green	$\overline{\text{A}}$	Signal line
11	Gray	A	Signal line
12	Pink	B	Signal line
	Screen		Screen on the encoder side connected to the housing. On the control side connected to earth.

Connector M23, 12-pin and cable outlet, cable 12-core
SSI/Gray + Sin/Cos

Pin	Color wires	Signal	Explanation
1	Red	$+U_V$	Supply voltage
2	Blue	GND	Ground connection
3	Yellow	Clock+	Interface signal
4	White	Data+	Interface signal
5	Orange	SET	Electronic adjustment
6	Brown	Data-	Interface signal
7	Violet	Clock-	Interface signal
8	Black	Sin-	Signal line
9	Orange/black	CW/$\overline{\text{CCW}}$	Counting sequence when turning
10	Green	Cos-	Signal line
11	Gray	Cos+	Signal line
12	Pink	Sin+	Signal line
		Screen	Screen on the encoder side connected to the housing. On the control side connected to earth.

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Signalausgänge

SSI data format singleturn



Bit 1–18: Position Bits

- LSB: Least significant Bit
- MSB: Most significant Bit

Bit 19–21: Error Bits

- ERRDIG: Failure message about speed. If this failure occurs during the position building procedure it will be indicated by the ERRDIG-Bit.
- ERRSI: Light source monitoring failure.
- ERRSYNC: Contamination of the disc or scanning system. During the determination of the position, an error has occurred since the last SSI transmission. The error bit will be deleted during the next data transmission.

The evaluation of the error bits has to be realized in the PLC.

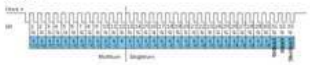
The provided error bits don't have to be used by the PLC compulsorily.

Example

If the resolution of the absolute encoder is set on 13 bits, 16 bits are provided by the encoder: 13 data bits and 3 error bits.
If the PLC is not able to evaluate the error bits, the PLC has to be set on a resolution of 13 bits. Then the error bits have to be masked out by the PLC.

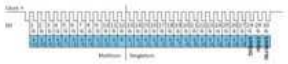
SSI data format multiturn

30 Bits



Bit 1–12: Position Bits multiturn
Bit 13–30: Position Bits singleturn
Bit 31–33: Error Bits

27 Bits



Bit 1–12: Position Bits multiturn
Bit 13–27: Position Bits singleturn
Bit 28–30: Error Bits

Error Bits

- ERRDIG: Failure message about speed. If this failure occurs during the position building procedure it will be indicated by the ERRDIG-Bit.
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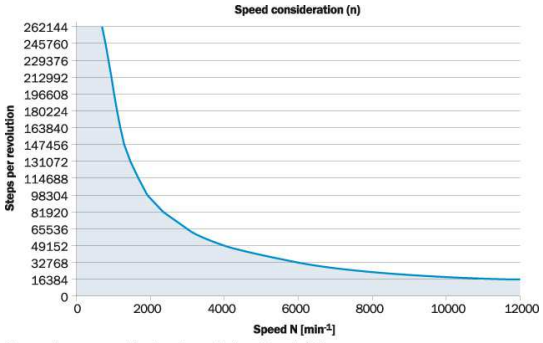
The evaluation of the error bits has to be realized in the PLC.

The provided error bits don't have to be used by the PLC compulsorily. The multiturn resolution is fixed on 12 bits.

Example

If the resolution of the absolute encoder is set on 27 bits, 30 bits are provided by the encoder: 27 data bits and 3 error bits.
If the PLC is not able to evaluate the error bits, the PLC has to be set on a resolution of 27 bits. Then the error bits have to be masked out by the PLC.

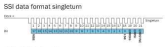
Drehzahlbetrachtung



The maximum speed is also dependent on the shaft type.

Signalausgänge

SSI data format singleturn



Bit 1–18: Position Bits

- LSB: Least significant Bit
- MSB: Most significant Bit

Bit 19–21: Error Bits

- ERRDIG: Failure message about speed. If this failure occurs during the position building procedure it will be indicated by the ERRDIG-Bit.
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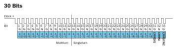
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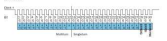
SSI data format multiturn

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27 Bits



Bit 1–12: Position Bits multiturn
Bit 13–27: Position Bits singleturn
Bit 28–30: Error Bits

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The evaluation of the error bits has to be realized in the PLC.

The provided error bits don't have to be used by the PLC compulsorily. The multiturn resolution is fixed on 12 bits.

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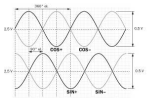
Interfaces

Electrical interfaces sine 0.5 V_{pp}

Power supply	Output
4.5 ... 5.5 V	Sine 0.5 V_{pp}

Signal **before** differential generation at load 120 Ω at U_p = 5 V

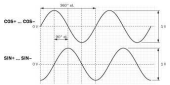
Signal diagram for clockwise rotation of the shaft looking in direction "A" (shaft)



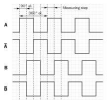
Interface signals Sin, $\overline{Sin}$, Cos, $\overline{Cos}$	Signal before differential generation at load 120 Ω	Signal offset
Analog differential	0.5 V_{pp} ± 20 %	2.5 V ± 10 %

Signal **after** differential generation at load 120 Ω at U_p = 5 V

Signal diagram for clockwise rotation of the shaft looking in direction "A" (shaft)



Incremental pulse diagram for clockwise rotation of the shaft looking in direction "A", see dimensional drawing



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Australia
Phone +61 3 9457 0600
1800 33 48 02 – tollfree
E-Mail sales@sick.com.au

Belgium/Luxembourg
Phone +32 (0)2 466 55 66
E-Mail info@sick.be

Brasil
Phone +55 11 3215-4900
E-Mail marketing@sick.com.br

Canada
Phone +1 905 771 14 44
E-Mail information@sick.com

Česká republika
Phone +420 2 57 91 18 50
E-Mail sick@sick.cz

China
Phone +86 4000 121 000
E-Mail info.china@sick.net.cn
Phone +852-2153 6300
E-Mail ghk@sick.com.hk

Danmark
Phone +45 45 82 64 00
E-Mail sick@sick.dk

Deutschland
Phone +49 211 5301-301
E-Mail info@sick.de

España
Phone +34 93 480 31 00
E-Mail info@sick.es

France
Phone +33 1 64 62 35 00
E-Mail info@sick.fr

Great Britain
Phone +44 (0)1727 831121
E-Mail info@sick.co.uk

India
Phone +91–22–4033 8333
E-Mail info@sick-india.com

Israel
Phone +972-4-6881000
E-Mail info@sick-sensors.com

Italia
Phone +39 02 27 43 41
E-Mail info@sick.it

Japan
Phone +81 (0)3 5309 2112
E-Mail support@sick.jp

Magyarország
Phone +36 1 371 2680
E-Mail office@sick.hu

Nederland
Phone +31 (0)30 229 25 44
E-Mail info@sick.nl

Norge
Phone +47 67 81 50 00
E-Mail sick@sick.no

Österreich
Phone +43 (0)22 36 62 28 8-0
E-Mail office@sick.at

Polska
Phone +48 22 837 40 50
E-Mail info@sick.pl

România
Phone +40 356 171 120
E-Mail office@sick.ro

Russia
Phone +7-495-775-05-30
E-Mail info@sick.ru

Schweiz
Phone +41 41 619 29 39
E-Mail contact@sick.ch

Singapore
Phone +65 6744 3732
E-Mail sales.gsg@sick.com

Slovenija
Phone +386 (0)1-47 69 990
E-Mail office@sick.si

South Africa
Phone +27 11 472 3733
E-Mail info@sickautomation.co.za

South Korea
Phone +82 2 786 6321/4
E-Mail info@sickkorea.net

Suomi
Phone +358-9-25 15 800
E-Mail sick@sick.fi

Sverige
Phone +46 10 110 10 00
E-Mail info@sick.se

Taiwan
Phone +886 2 2375-6288
E-Mail sales@sick.com.tw

Türkiye
Phone +90 (216) 528 50 00
E-Mail info@sick.com.tr

United Arab Emirates
Phone +971 (0) 4 88 65 878
E-Mail info@sick.ae

USA/México
Phone +1(952) 941-6780
1 (800) 325-7425 – tollfree
E-Mail info@sickusa.com

More representatives and agencies
at **www.sick.com**

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