

ONLINE DATA SHEET
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Motor feedback systems rotary HIPERFACE®
SFS/SFM60

SFM60-HMAT0K02



SICK
Sensor Intelligence.

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Model Name	**> SFM60-HMAT0K02**
Part No.	**> 1051086**

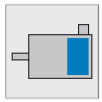




Illustration may differ

At a glance

- HIPERFACE® motor feedback system in singleturn and multiturn design, compatible with the world's leading drive systems
- 1,024 sine/ cosine periods per revolution
- Absolute position with a resolution of 32,768 increments per revolution and 4,096 revolutions with the multiturn system
- HIPERFACE® interface: Programming of the position value and electronic type label
- Mechanical flexibility through different blind hollow shaft and through hollow shaft diameters (8 to 15 mm diameter), available with various torque supports
- Unique ball bearing design, allowing for a ball bearing distance of 30 mm.
- Universal cable outlet and common connector versions
- Protection class IP 65

Your benefits

- Convenient traceability and simple maintenance thanks to storage of motor-specific data in the electronic type label
- Large ball bearing distances reduce uneven wear and minimize vibration on the encoder housing, which increases the encoder's service life
- The nickel code disk offers a high degree of vibration resistance and an extended temperature range
- Shorter development times through standardized mechanical interface
- Platform for the future, since all electrical interfaces (TTL/HTL, 1Vpp, SSI, PROFIBUS, HIPERFACE DSL®) are or will be available in this mechanical component.

Performance

Number of sine/cosine periods per revolution:	1,024
Number of the absolute ascertainable revolutions:	4,096 (Multiturn)
Total number of steps:	134,217,728
Measuring step:	0.3 angular seconds at interpolation of the sine/cosine signals with e.g. 12 Bit
Error limits for the digital absolute value:	± 90 angular seconds (via RS485)
Integral non-linearity typ.:	± 45 angular seconds (Error limits for evaluating sine/cosine period) without mechanical tension of the stator coupling
Differential non-linearity:	± 7 angular seconds (Non-linearity within a sine/cosine period)
Operating speed:	6,000 /min, up to which the absolute position can be reliably produced
Available memory area:	1,792 Byte (EEPROM 2048)

Mechanical data

Shaft diameter:	12 mm
Shaft plug-in length:	15 mm
Flange type/stator coupling:	Standard version
Dimensions:	See dimensional drawing
Mass:	0.2 kg
Moment of inertia of the rotor:	40 gcm²
Maximum operating speed:	9,000 /min [1)]
Maximum angular acceleration:	50,000 rad/s²
Operating torque:	0.6 Ncm (20 °C)
Start up torque:	0.8 Ncm (20 °C)
Permissible shaft movement, radial, static:	± 0.3 mm
Permissible shaft movement, radial, dynamic:	± 0.1 mm
Permissible shaft movement, axial, static:	± 0.5 mm
Permissible shaft movement, axial, dynamic:	± 0.2 mm
Life of ball bearings:	3.6 x 10^9 revolutions
Connection type:	Connector M23, 12-pin, radial
Shaft version:	Through hollow shaft

1) Self-warming 3.3 K/1,000 1/min, when applying note working temperature range

Electrical data

Electrical interface:	HIPERFACE
Operating voltage range/supply Voltage:	7 V DC ... 12 V DC
Recommended supply voltage:	8 V DC
Output frequency for sine/cosine signals:	0 kHz ... 200 kHz
Operating power consumption (no load):	< 80 mA [1)]

1) Without load

Interfaces

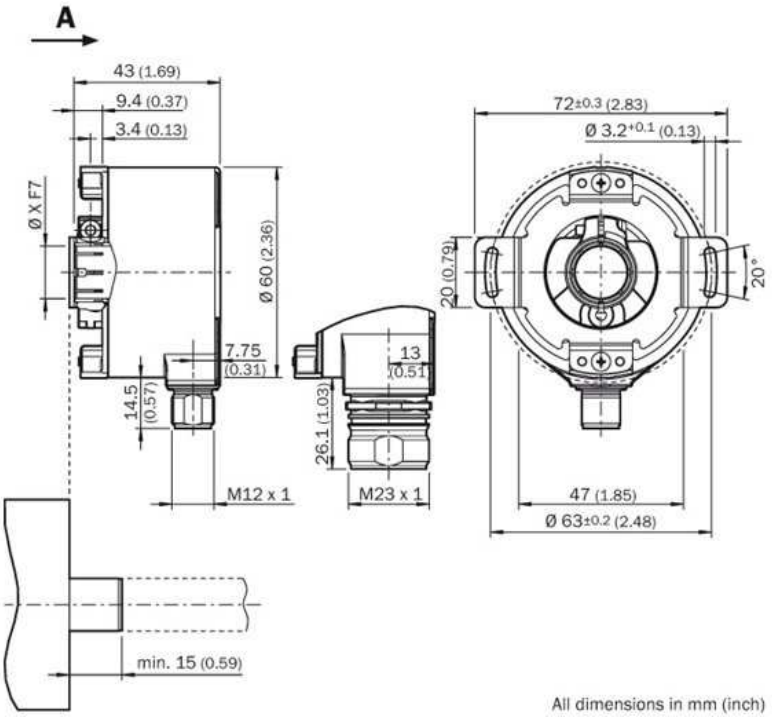
Type of code for the absolute value:	Binary
Code sequence:	Increasing, for clockwise shaft rotation, looking in direction "A" (see dimensional drawing)
Interface signals:	Parameter channel RS 485: digital, Process data channel SIN, REFSIN, COS, REFCOS: analog, differential

Ambient data

Working temperature range:	-30 °C ... 115 °C
Storage temperature range:	-40 °C ... 115 °C, without package
Relative humidity／Condensation:	90 %, Condensation not permitted
Resistance to shocks:	100 g, 6 ms (according to EN 60068-2-27)
Resistance to vibration:	20 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)
EMC:	According to EN 61000-6-2 and EN 61000-6-3 [1)]
Enclosure rating:	IP 65, according to IEC 60529, with mating connector inserted

1) The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. This is also where the GND (0 V) connection of the power supply voltage is linked to earth. Users must perform their own tests when other screen designs are used.

Dimensional drawing



All dimensions in mm (inch)

A4 4c int43

Australia
Phone +61 3 9457 0600
1800 33 48 02 – tollfree
E-Mail sales@sick.com.au

Belgium/Luxembourg
Phone +32 (0)2 466 55 66
E-Mail info@sick.be

Brasil
Phone +55 11 3215-4900
E-Mail marketing@sick.com.br

Canada
Phone +1 905 771 14 44
E-Mail information@sick.com

Česká republika
Phone +420 2 57 91 18 50
E-Mail sick@sick.cz

China
Phone +86 4000 121 000
E-Mail info.china@sick.net.cn
Phone +852-2153 6300
E-Mail ghk@sick.com.hk

Danmark
Phone +45 45 82 64 00
E-Mail sick@sick.dk

Deutschland
Phone +49 211 5301-301
E-Mail info@sick.de

España
Phone +34 93 480 31 00
E-Mail info@sick.es

France
Phone +33 1 64 62 35 00
E-Mail info@sick.fr

Great Britain
Phone +44 (0)1727 831121
E-Mail info@sick.co.uk

India
Phone +91–22–4033 8333
E-Mail info@sick-india.com

Israel
Phone +972-4-6881000
E-Mail info@sick-sensors.com

Italia
Phone +39 02 27 43 41
E-Mail info@sick.it

Japan
Phone +81 (0)3 5309 2112
E-Mail support@sick.jp

Magyarország
Phone +36 1 371 2680
E-Mail office@sick.hu

Nederland
Phone +31 (0)30 229 25 44
E-Mail info@sick.nl

Norge
Phone +47 67 81 50 00
E-Mail sick@sick.no

Österreich
Phone +43 (0)22 36 62 28 8-0
E-Mail office@sick.at

Polska
Phone +48 22 837 40 50
E-Mail info@sick.pl

România
Phone +40 356 171 120
E-Mail office@sick.ro

Russia
Phone +7-495-775-05-30
E-Mail info@sick.ru

Schweiz
Phone +41 41 619 29 39
E-Mail contact@sick.ch

Singapore
Phone +65 6744 3732
E-Mail sales.gsg@sick.com

Slovenija
Phone +386 (0)1-47 69 990
E-Mail office@sick.si

South Africa
Phone +27 11 472 3733
E-Mail info@sickautomation.co.za

South Korea
Phone +82 2 786 6321/4
E-Mail info@sickkorea.net

Suomi
Phone +358-9-25 15 800
E-Mail sick@sick.fi

Sverige
Phone +46 10 110 10 00
E-Mail info@sick.se

Taiwan
Phone +886 2 2375-6288
E-Mail sales@sick.com.tw

Türkiye
Phone +90 (216) 528 50 00
E-Mail info@sick.com.tr

United Arab Emirates
Phone +971 (0) 4 88 65 878
E-Mail info@sick.ae

USA/México
Phone +1(952) 941-6780
1 (800) 325-7425 – tollfree
E-Mail info@sickusa.com

More representatives and agencies
at **www.sick.com**

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