Product data sheet



AFM60B-S1SA032768

AFS/AFM60 SSI

ABSOLUTE ENCODERS

SICK
Sensor Intelligence.



Illustration may differ

Ordering information

Type	Part no.
AFM60B-S1SA032768	1054220

Other models and accessories ➜ www.sick.com/AFS_AFM60_SSI

Detailed technical data

Performance

Max. resolution (number of steps per revolution x number of revolutions)	15 bit x 12 bit (32,768 x 4,096)
Error limits G	0.05° [1]
Repeatability standard deviation σ_r	0.002° [2]

[1] In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.
[2] In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

Interfaces

Communication interface	SSI
Communication Interface detail	SSI + Sin/Cos
Initialization time	50 ms [1]
Position forming time	< 1 µs
SSI	
Code type	Gray
Code sequence parameter adjustable	CW/CCW (V/R) parameter adjustable
Clock frequency	≤ 2 MHz [2]
Set (electronic adjustment)	H-active (L = 0 - 3 V, H = 4,0 - U_s V)
CW/CCW (counting sequence when turning)	L-active (L = 0 - 1,5 V, H = 2,0 - Us V)
Sin/Cos	
Sine/cosine periods per revolution	1,024
Output frequency	≤ 200 kHz
Load resistance	≥ 120 Ω
Signal before differential generation	0.5 V_{pp}, ± 20 %, 120 Ω
Signal offset before differential generation	2.5 V ± 10 %

[1] Valid positional data can be read once this time has elapsed.
[2] Minimum, LOW level (Clock +): 250 ns.

Signal after differential generation	1 V_{pp}, ± 20 %

[1] Valid positional data can be read once this time has elapsed.
[2] Minimum, LOW level (Clock +): 250 ns.

Electrical data

Connection type	Male connector, M23, 12-pin, radial
Supply voltage	4.5 ... 32 V DC
Power consumption	≤ 0.7 W (without load)
Reverse polarity protection	✓
MTTFd: mean time to dangerous failure	250 years (EN ISO 13849-1) [1]

[1] This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Mechanical data

Mechanical design	Solid shaft, Servo flange
Shaft diameter	6 mm
Shaft length	10 mm
Weight	0.3 kg [1]
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum die cast
Start up torque	< 0.5 Ncm [2]
Operating torque	< 0.3 Ncm [2]
Permissible Load capacity of shaft	80 N / radial 40 N / axial
Moment of inertia of the rotor	6.2 gcm²
Bearing lifetime	3.0 x 10^9 revolutions
Angular acceleration	+ 500,000 rad/s²
Operating speed	≤ 9,000 min^{-1} [3]

[1] Relates to devices with male connector connection.
[2] At 20 °C.
[3] Allow for self-heating of approx. 3.3 K / 1,000 rpm when designing the operating temperature range.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3 [1]
Enclosure rating	IP65, shaft side (according to IEC 60529) IP67, housing side (according to IEC 60529) [2]
Permissible relative humidity	90 % (condensation of the optical scanning not permitted)
Operating temperature range	–40 °C ... +100 °C [3]
Storage temperature range	–40 °C ... +100 °C, without package
Resistance to shocks	70 g, 6 ms (according to EN 60068-2-27)

[1] EMC according to the standards quoted is achieved if shielded cables are used.
[2] For devices with connector connection: With mating connector mounted.
[3] Stationary position of the cable.

Resistance to vibration	30 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

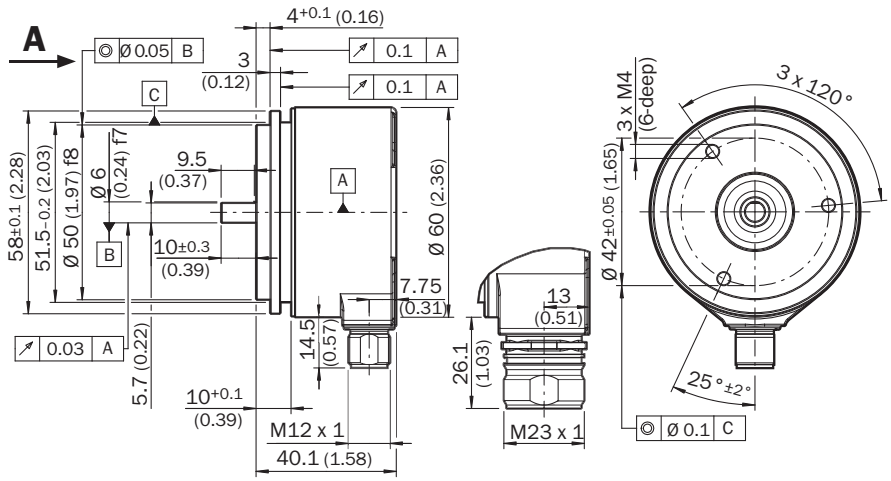
[1] EMC according to the standards quoted is achieved if shielded cables are used.
[2] For devices with connector connection: With mating connector mounted.
[3] Stationary position of the cable.

Classifications

ECl@ss 5.0	27270502
ECl@ss 5.1.4	27270502
ECl@ss 6.0	27270590
ECl@ss 6.2	27270590
ECl@ss 7.0	27270502
ECl@ss 8.0	27270502
ECl@ss 8.1	27270502
ECl@ss 9.0	27270502
ECl@ss 10.0	27270502
ECl@ss 11.0	27270502
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
UNSPSC 16.0901	41112113

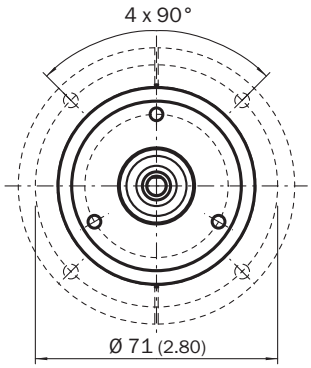
Dimensional drawing (Dimensions in mm (inch))

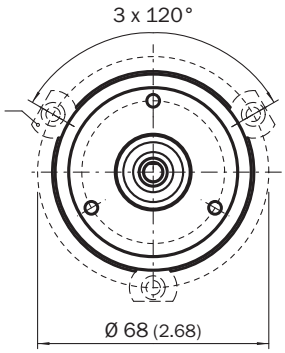
Servo flange, radial plug connection M12 and M23



General tolerances according to DIN ISO 2768-mk

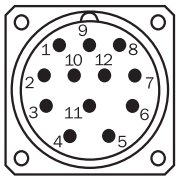
Attachment specifications





PIN assignment

M23 male connector, 12-pin and cable, 12-wire, SSI/Gray, incremental

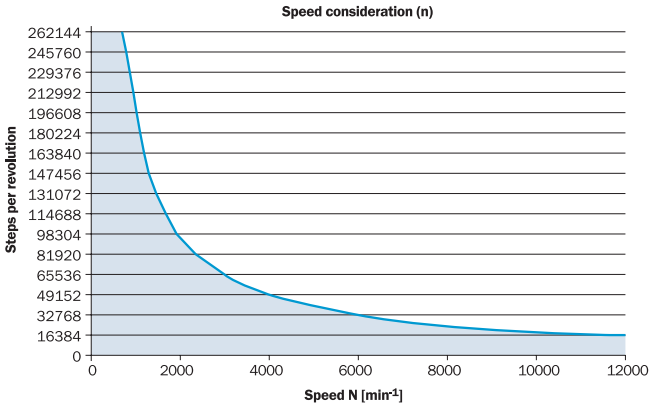


View of M23 male device connector on encoder

PIN	Wire colors (cable connection)	Signal	Explanation
1	Red	U_S	Operating voltage
2	Blue	GND	Ground connection
3	Yellow	Clock +	Interface signals
4	White	Data +	Interface signals
5	Orange	SET	Electronic adjustment
6	Brown	Data -	Interface signals
7	Violet	Clock -	Interface signals
8	Black	- SIN	Signal wire
9	Orange-black	CW/CCW (V/R)	Sequence in direction of rotation
10	Green	- COS	Signal wire
11	Gray	+ COS	Signal wire
12	Pink	+ SIN	Signal wire

PIN	Wire colors (cable connection)	Signal	Explanation
		Screen	Screen connected to housing on encoder side. Connected to ground on control side.

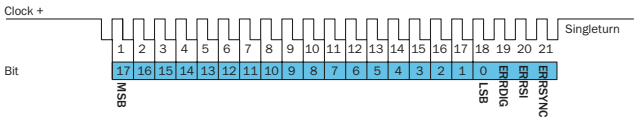
Maximum revolution range



The maximum speed is also dependent on the shaft type.

Diagrams

SSI data format singleturn



Bit 1–18: Position Bits

- LSB: Least significant Bit
- MSB: Most significant Bit

Bit 19–21: Error Bits

- ERRDIG: Failure message about speed. If this failure occurs during the position building procedure it will be indicated by the ERRDIG-Bit.
- ERRSI: Light source monitoring failure.
- ERRSYNC: Contamination of the disc or scanning system. During the determination of the position, an error has occurred since the last SSI transmission. The error bit will be deleted during the next data transmission.

The evaluation of the error bits has to be realized in the PLC.

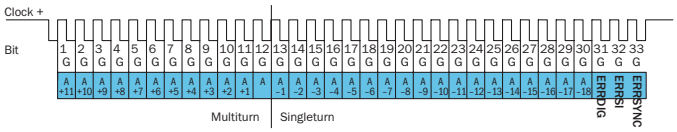
The provided error bits don't have to be used by the PLC compulsorily.

Example

If the resolution of the absolute encoder is set on 13 bits, 16 bits are provided by the encoder: 13 data bits and 3 error bits.
If the PLC is not able to evaluate the error bits, the PLC has to be set on a resolution of 13 bits. Then the error bits have to be masked out by the PLC.

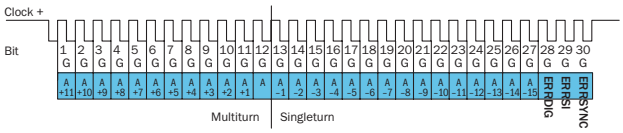
SSI data format multiturn

30 Bits



Bit 1–12: Position Bits multiturn
Bit 13–30: Position Bits singleturn
Bit 31–33: Error Bits

27 Bits



Bit 1–12: Position Bits multiturn
Bit 13–27: Position Bits singleturn
Bit 28–30: Error Bits

Error Bits

- ERRDIG: Failure message about speed. If this failure occurs during the position building procedure it will be indicated by the ERRDIG-Bit.
- ERRSI: Light source monitoring failure.
- ERRSYNC: Contamination of the disc or scanning system. During the determination of the position, an error has occurred since the last SSI transmission. The error bit will be deleted during the next data transmission.

The evaluation of the error bits has to be realized in the PLC.

The provided error bits don't have to be used by the PLC compulsorily. The multiturn resolution is fixed on 12 bits.

Example

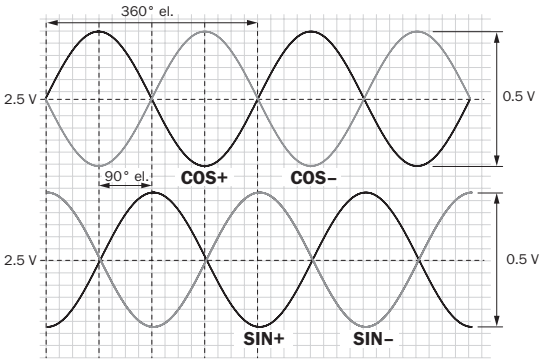
If the resolution of the absolute encoder is set on 27 bits, 30 bits are provided by the encoder: 27 data bits and 3 error bits.
If the PLC is not able to evaluate the error bits, the PLC has to be set on a resolution of 27 bits. Then the error bits have to be masked out by the PLC.

Electrical interfaces sine 0.5 V_{pp}

Power supply	Output
4.5 ... 5.5 V	Sine 0.5 V_{pp}

Signal **before** differential generation at load 120 Ω at U_S = 5 V

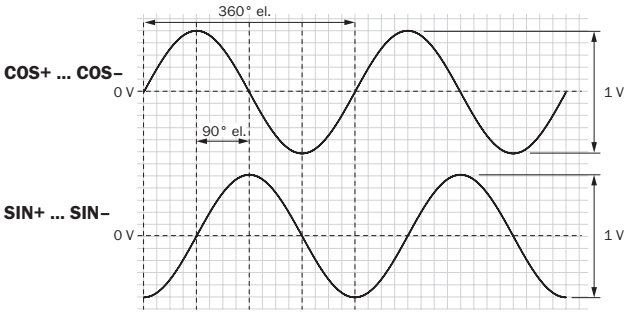
Signal diagram for clockwise rotation of the shaft looking in direction "A" (shaft)



Interface signals Sin, $\overline{\text{Sin}}$, Cos, $\overline{\text{Cos}}$	Signal before differential generation at load 120 Ω	Signal offset
Analog differential	0.5 V_{pp} ± 20 %	2.5 V ± 10 %

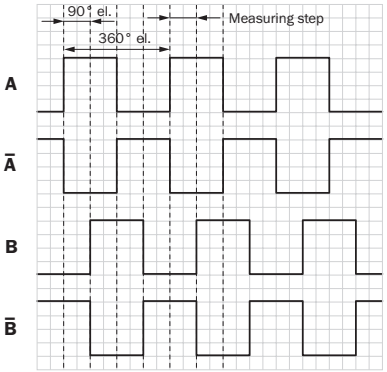
Signal **after** differential generation at load 120 Ω at U_S = 5 V

Signal diagram for clockwise rotation of the shaft looking in direction "A" (shaft)



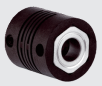
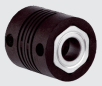
Electrical interfaces HTL/TTL

Incremental pulse diagram for clockwise rotation of the shaft looking in direction "A", see dimensional drawing



Recommended accessories

Other models and accessories ➜ www.sick.com/AFS_AFM60_SSI

	Brief description	Type	Part no.
Other mounting accessories			
	Servo clamps, large, for servo flanges (clamps, eccentric fastener), 3 pcs., without mounting material, without mounting hardware	BEF-WK-SF	2029166
Shaft adaptation			
	Bellows coupling, shaft diameter 6 mm / 6 mm, maximum shaft offset: radial ± 0.25 mm, axial ± 0.4 mm, angular +/- 4°; max. speed 10,000 rpm, –30 °C to +120 °C, max. torque 80 Ncm; material: stainless steel bellows, aluminum hub	KUP-0606-B	5312981
	Bar coupling, shaft diameter 6 mm / 6 mm, maximum shaft offset: radial ± 0.3 mm, axial ± 0.2 mm, angle ± 3°; max. speed 10,000 rpm, –10° to +80 °C, max. torque 80 Ncm; material: fiber-glass reinforced polyamide, aluminum hub	KUP-0606-S	2056406
	Bar coupling, shaft diameter 6 mm /8 mm, maximum shaft offset radial ± 0.3 mm, axial ± 0.2 mm, angle ± 3°, max. speed 10,000 rpm, torsion spring rigidity 38 Nm/wheel; material: fiber-glass reinforced polyamide, aluminum hub	KUP-0608-S	5314179
	Bellows coupling, shaft diameter 6 mm / 10 mm, maximum shaft offset: radial ± 0.25 mm, axial ± 0.4 mm, angular +/- 4°; max. speed 10,000 rpm, –30 °C to +120 °C, max. torque 80 Ncm; material: stainless steel bellows, aluminum hub	KUP-0610-B	5312982
	Double loop coupling, shaft diameter 6 mm / 10 mm, max. shaft offset: radially +/- 2,5 mm, axially +/-3 mm, angle +/- 10 degrees;max. speed 3.000 rpm, –30 to +80 degrees Celsius, torsional spring stiffness of 25 Nm/rad	KUP-0610-D	5326697
	Spring washer coupling, shaft diameter 6 mm / 10 mm, Maximum shaft offset: radial +/- 0.3 mm, axial +/- 0.4 mm, angular +/- 2.5°; max. speed 12,000 rpm, –10° to +80 °C, max. torque 60 Ncm; material: aluminum flange, glass fiber-reinforced polyamide membrane and hardened steel coupling pin	KUP-0610-F	5312985
	Bar coupling, shaft diameter 6 mm / 10 mm, max. shaft offset: radial ± 0,3 mm, axial ± 0,3 mm, angular ± 3°; max. speed 10.000 rpm, –10° to +80 °C, max. torque: 80 Ncm, material: fiber-glass reinforced polyamide, aluminum hub	KUP-0610-S	2056407
Plug connectors and cables			
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: shielded, 3 m	DOL-2312-G03MMD2	2062300
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: shielded, 5 m	DOL-2312-G05MMD2	2062301
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: shielded, 10 m	DOL-2312-G10MMD2	2062302
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: unshielded, 1.5 m	DOL-2312-G1M5MD2	2062284
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: shielded, 20 m	DOL-2312-G20MMD2	2062303
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: shielded, 30 m	DOL-2312-G30MMD2	2062304
	Head A: female connector, M23, 12-pin, straight Head B: - Cable: HIPERFACE®, SSI, Incremental, shielded	DOS-2312-G DOS-2312-G02	6027538 2077057

	Brief description	Type	Part no.
	Head A: female connector, M23, 12-pin, angled Head B: - Cable: HIPERFACE®, SSI, Incremental, shielded	DOS-2312-W01	2072580
Programming and configuration tools			
	USB programming unit, for programmable SICK encoders AFS60, AFM60, DFS60, VFS60, DFV60 and wire draw encoders with programmable encoders	PGT-08-S	1036616
	Programming unit display for programmable SICK DFS60, DFV60, AFS/AFM60, AHS/AHM36 encoders, and wire draw encoder with DFS60, AFS/AFM60 and AHS/AHM36. Compact dimensions, low weight, and intuitive operation.	PGT-10-Pro	1072254

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