

ONLINE DATA SHEET
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Incremental encoders
DFS60, Rotary

DFS60B-S4AC00500



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DFS60, Rotary

Model Name > DFS60B-S4AC00500
Part No. > 1063692



Illustration may differ

At a glance

- Compact installation depth
- High resolution up to 16 bits
- Optionally programmable: Output voltage, zero pulse position, zero pulse width and number of pulses
- Connection: Radial or axial cable outlet, M23 or M12 connector, axial or radial
- Electrical interfaces: 5V & 24V TTL/RS-422, 24 V HTL/push pull
- Mechanical interfaces: face mount or servo flange, blind or through hollow shaft
- Remote zero set possible

Your benefits

- Reduced storage costs and downtime due to customer-specific programming
- Variety of different mechanical and electrical interfaces enable the encoder to be optimally adjusted to fit the installation situation
- Excellent concentricity even at high speeds
- High resolution of up to 16 bits ensures precise measurements
- Permanent and safe operation due to a high enclosure rating, temperature resistance and a long bearing lifetime
- Programmability via the PGT-08 programming software and the PGT-10-S display programming tool allow the encoder to be adapted flexibly and quickly according to customer needs
- Programmable zero pulse position simplifies installation

Performance

Error limits:	± 0.05 °
Measuring step:	Electronically/number of lines
Initialization time:	40 ms
Pulses per revolution:	500

Mechanical data

Mechanical interface:	Solid shaft, Face mount flange
Shaft diameter:	10 mm x 19 mm
Mass:	0.3 kg
Start up torque:	0.5 Ncm (+20 °C)
Operating torque:	0.3 Ncm (+20 °C)
Maximum operating speed:	10,000 /min
Moment of inertia of the rotor:	6.2 gcm²
Bearing lifetime:	3.6 x 10^10 revolutions

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Max. angular acceleration:	500,000 rad/s²
Permissible shaft loading radial/axial:	40 N (axial), 80 N (radial)

Electrical data

Electrical interface:	4.5 V ... 5.5 V, TTL/RS422, Connector M12, 8-pin, radial
Connection type:	Male connector M12, 8-pin, radial
Maximum output frequency:	600 kHz
Reference signal, number:	1
Reference signal, position:	90 °, electronically, gated with A and B
Operating voltage range:	4.5 V ... 5.5 V
Load current max.:	30 mA
Power consumption:	Without load
MTTFd: mean time to dangerous failure:	300 a (EN ISO 13849-1) [1]

[1] This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

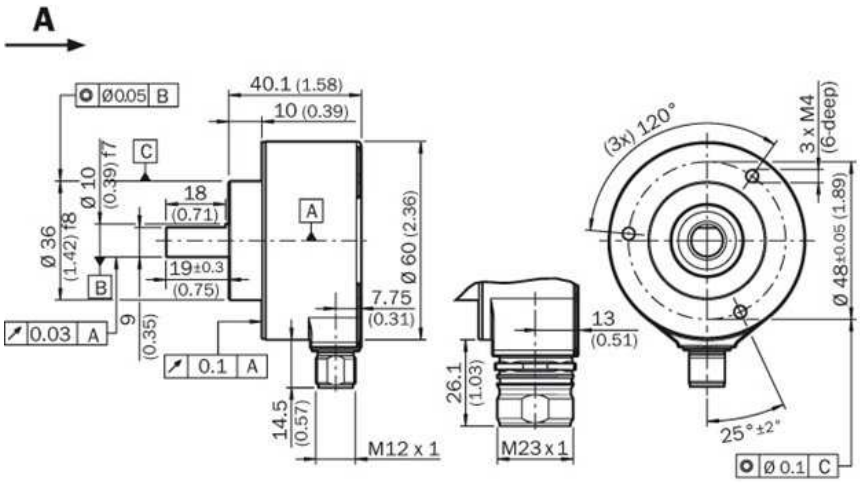
Ambient data

EMC:	(according to EN 61000-6-2 and EN 61000-6-3)
Working temperature range:	-30 °C ... +100 °C
Storage temperature range:	-40 °C ... +100 °C, without package
Resistance to shocks:	70 g (according to EN 60068-2-27)
Resistance to vibration:	30 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)
Enclosure rating:	IP 65 (according to IEC 60529), shaft side, IP 67 (according to IEC 60529), housing side [1]
Permissible relative humidity:	90 % (condensation of the optical scanning not permitted)

[1] With mating connector fitted

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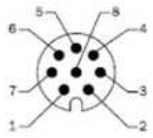
Dimensional drawing



PIN assignment

8-core cable

View of M12 device connector on encoder



View of M23 device connector on encoder



PIN, 8-pin, M12 connector	PIN, 12-pin, M23 connector	Core colors of encoders with cable outlet	TTL/HTL signal	Explanation
1	6	Brown	$\overline{A}$	Signal cable
2	5	White	A	Signal cable
3	1	Black	$\overline{B}$	Signal cable
4	8	Pink	B	Signal cable
5	4	Yellow	$\overline{Z}$	Signal cable
6	3	Lilac	Z	Signal cable
7	10	Blue	GND	Ground connection of the encoder
8	12	Red	$+U_s$	Supply voltage (volt-free to housing)
–	9	–	N.C.	Not assigned
–	2	–	N.C.	Not assigned
–	11	–	N.C.	Not assigned
–	7 [1]	–	SET	Zero pulse teach
Shield	Shield	Shield	Shield	Shield connected to housing on side of encoder. Connected to ground on side of control.

[1] Only at 4.5 ... 32 V, TTL/HTL programmable

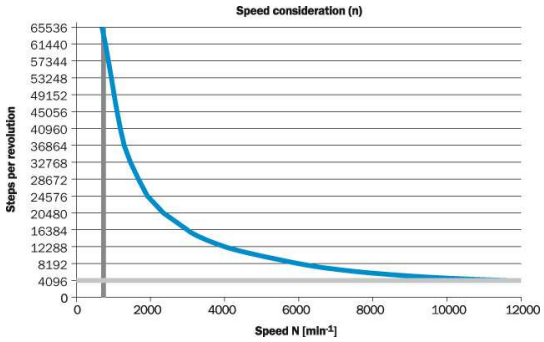
The SET input serves to carry out the zero pulse teach function. If the SET input is applied to U_s for longer than 250 ms, after it has was open for at least 1,000 ms or applied to GND, the current shaft position is assigned the zero pulse signal "Z".

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Signalausgänge

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Drehzahlbetrachtung



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Australia
Phone +61 3 9457 0600
1800 33 48 02 – tollfree
E-Mail sales@sick.com.au

Belgium/Luxembourg
Phone +32 (0)2 466 55 66
E-Mail info@sick.be

Brasil
Phone +55 11 3215-4900
E-Mail marketing@sick.com.br

Canada
Phone +1 905 771 14 44
E-Mail information@sick.com

Česká republika
Phone +420 2 57 91 18 50
E-Mail sick@sick.cz

China
Phone +86 4000 121 000
E-Mail info.china@sick.net.cn
Phone +852-2153 6300
E-Mail ghk@sick.com.hk

Danmark
Phone +45 45 82 64 00
E-Mail sick@sick.dk

Deutschland
Phone +49 211 5301-301
E-Mail info@sick.de

España
Phone +34 93 480 31 00
E-Mail info@sick.es

France
Phone +33 1 64 62 35 00
E-Mail info@sick.fr

Great Britain
Phone +44 (0)1727 831121
E-Mail info@sick.co.uk

India
Phone +91–22–4033 8333
E-Mail info@sick-india.com

Israel
Phone +972-4-6881000
E-Mail info@sick-sensors.com

Italia
Phone +39 02 27 43 41
E-Mail info@sick.it

Japan
Phone +81 (0)3 5309 2112
E-Mail support@sick.jp

Magyarország
Phone +36 1 371 2680
E-Mail office@sick.hu

Nederland
Phone +31 (0)30 229 25 44
E-Mail info@sick.nl

Norge
Phone +47 67 81 50 00
E-Mail sick@sick.no

Österreich
Phone +43 (0)22 36 62 28 8-0
E-Mail office@sick.at

Polska
Phone +48 22 837 40 50
E-Mail info@sick.pl

România
Phone +40 356 171 120
E-Mail office@sick.ro

Russia
Phone +7-495-775-05-30
E-Mail info@sick.ru

Schweiz
Phone +41 41 619 29 39
E-Mail contact@sick.ch

Singapore
Phone +65 6744 3732
E-Mail sales.gsg@sick.com

Slovenija
Phone +386 (0)1-47 69 990
E-Mail office@sick.si

South Africa
Phone +27 11 472 3733
E-Mail info@sickautomation.co.za

South Korea
Phone +82 2 786 6321/4
E-Mail info@sickkorea.net

Suomi
Phone +358-9-25 15 800
E-Mail sick@sick.fi

Sverige
Phone +46 10 110 10 00
E-Mail info@sick.se

Taiwan
Phone +886 2 2375-6288
E-Mail sales@sick.com.tw

Türkiye
Phone +90 (216) 528 50 00
E-Mail info@sick.com.tr

United Arab Emirates
Phone +971 (0) 4 88 65 878
E-Mail info@sick.ae

USA/México
Phone +1(952) 941-6780
1 (800) 325-7425 – tollfree
E-Mail info@sickusa.com

More representatives and agencies
at **www.sick.com**

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